



Mobility

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Reflecting joint work with Luís Caires, Andrew D. Gordon.

Widely Distributed Systems

Concurrent systems that are *spatially* distributed:

- Not in the same box.
- Not on the same LAN.
- Not inside the same firewall.
- Not always in the same place.

They have well-defined subsystems that:

- Fail independently.
- Recover independently.
- Hold secrets, mistrust each other.
- Move around.

Spatial distribution is (in practice) an observable.

- Both in terms of performance and security.

The New Machine

The “machine” we now write programs for, is the whole Internet.

- New instruction sets (programming models):
 - Message-centric, asynchronous, often stateless. Cannot rely on distributed consensus.
 - In striking contrast to shared-memory concurrency, and handshake-based (synchronous) concurrency.
- New type systems:
 - Traditional “strong” type systems have been (finally!) enthusiastically adopted as a foundation for security.
 - But entirely new type systems are needed for regulating communication, and to manage application-level security.
- New program logics:
 - Privacy/security concerns override everything else.
 - Need “location awareness” and “resource awareness”.

What's the Difference?

(1) Global Communication

- Why it is different from, e.g., **send/receive**.
- Why it needs new communication models.

(2) Global Computation

- Why it is different from, e.g., **method invocation**.
- Why it needs new specification logics.

(3) Global Data

- Why it is different from, e.g., **arrays** and **records**.
- Why it needs new type systems.

(4) Spatial Logic

- For Global Computation (as a specification logic)
- For Global Data (as a type system)

Global Communication

Isn't π -calculus good(/bad) enough?

- Most process calculi use a powerful *channel* abstraction.
- This is “too abstract” for global communication: failure modes get increasingly harder to ignore.
- Channels abstract *wires*.

What kind of wires do we actually need to model?

Two “Paradoxes” of global communication:

- Wires are very, very complicated.
Most of Computer Science is about modeling or implementing wires.
- Even when nothing goes wrong, still things don't work.
Global Murphy's Law.

Ditch channels, but keep π -names.

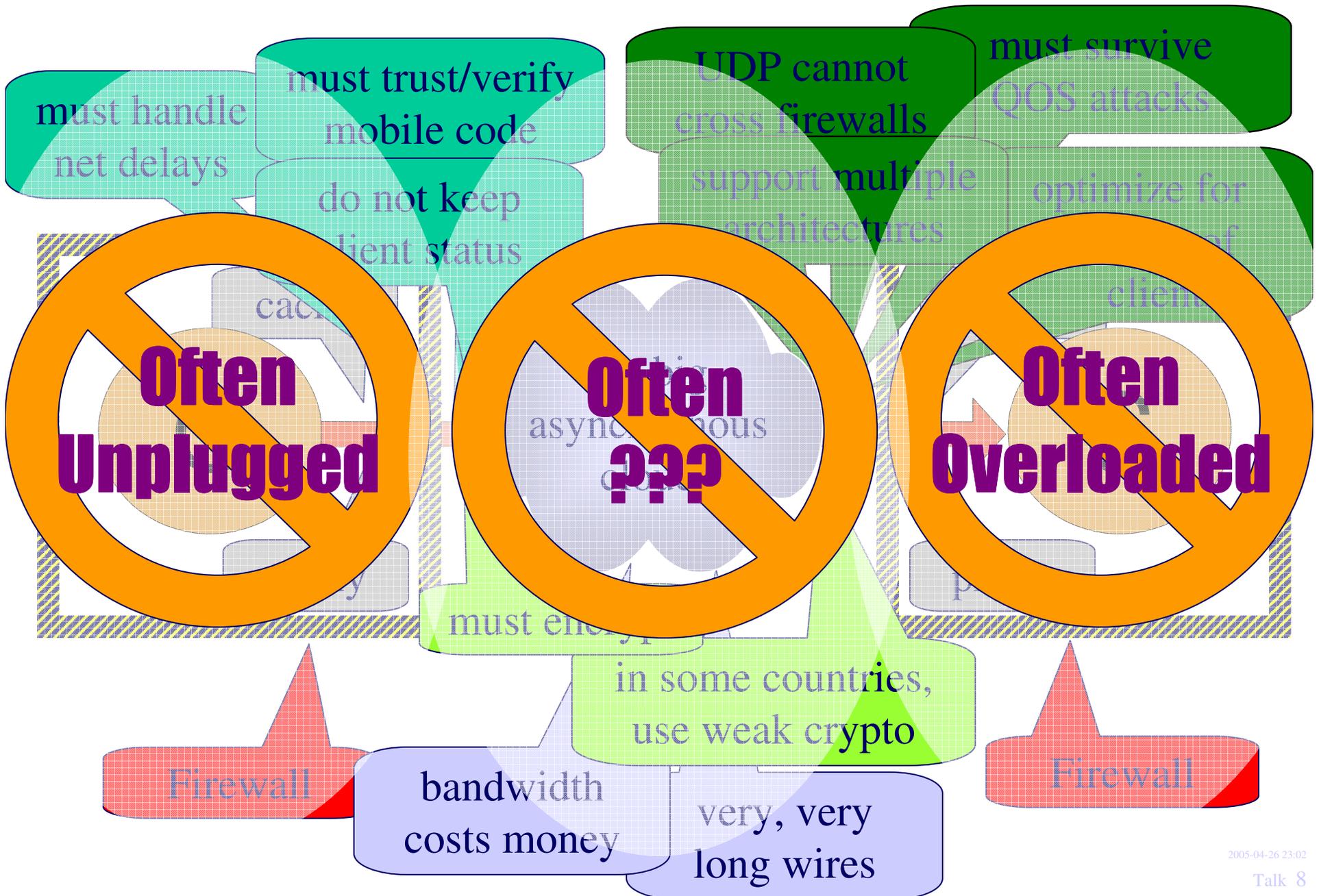
In-Memory Wires



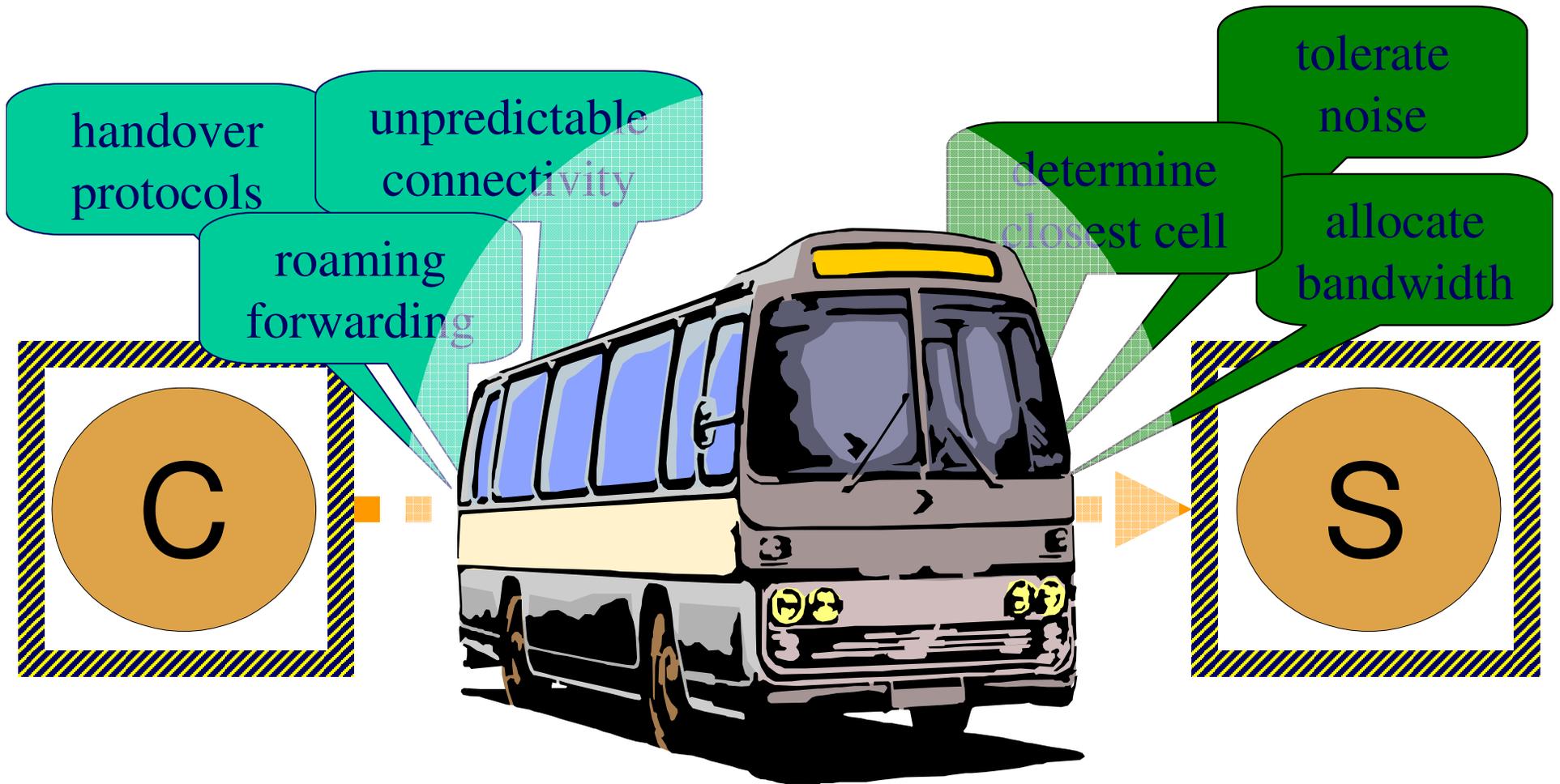
LAN Wires



WAN Wires



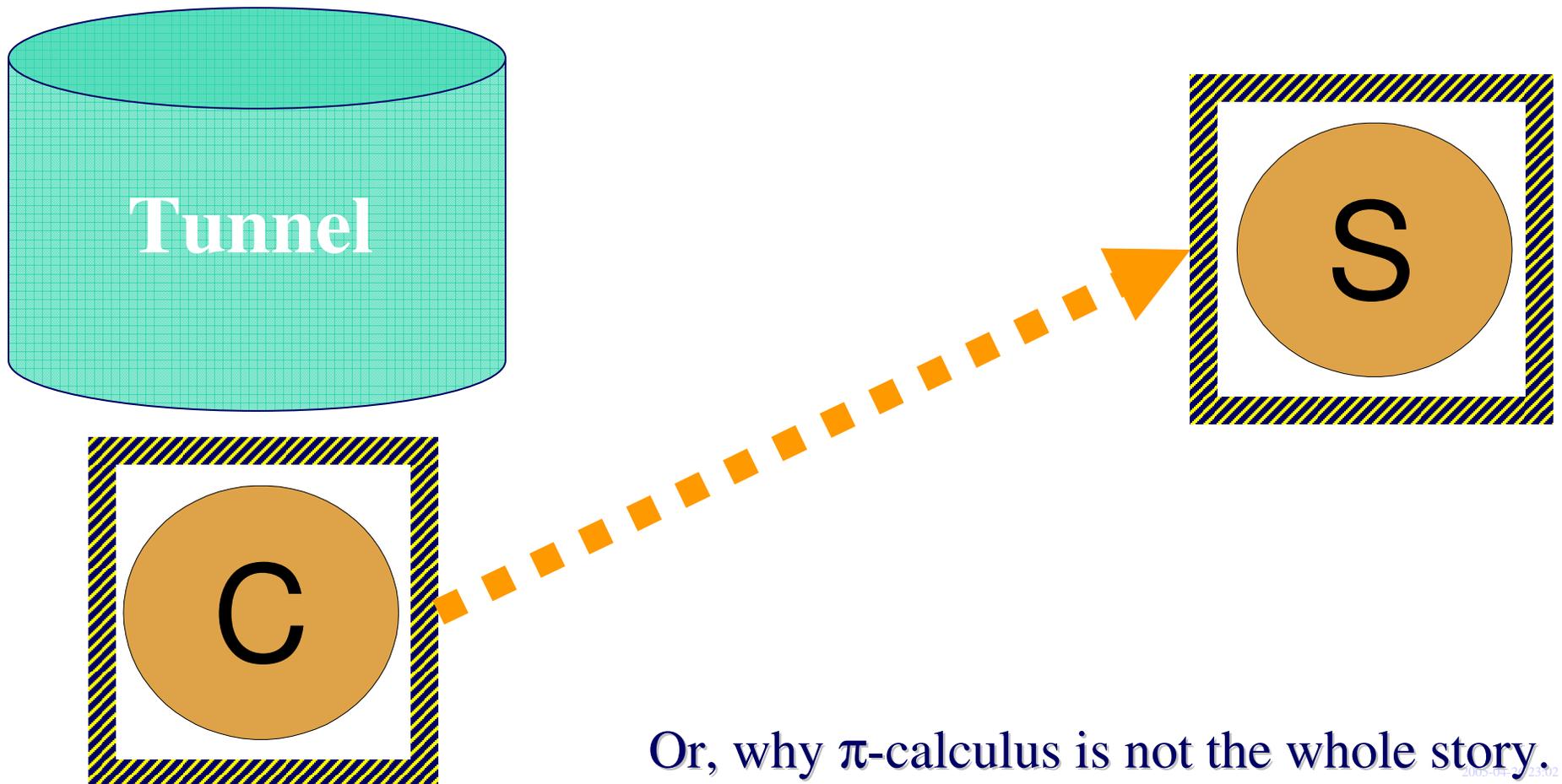
Mobile (“Wireless”) Wires



Mobile obstacles

Tunnel Effect

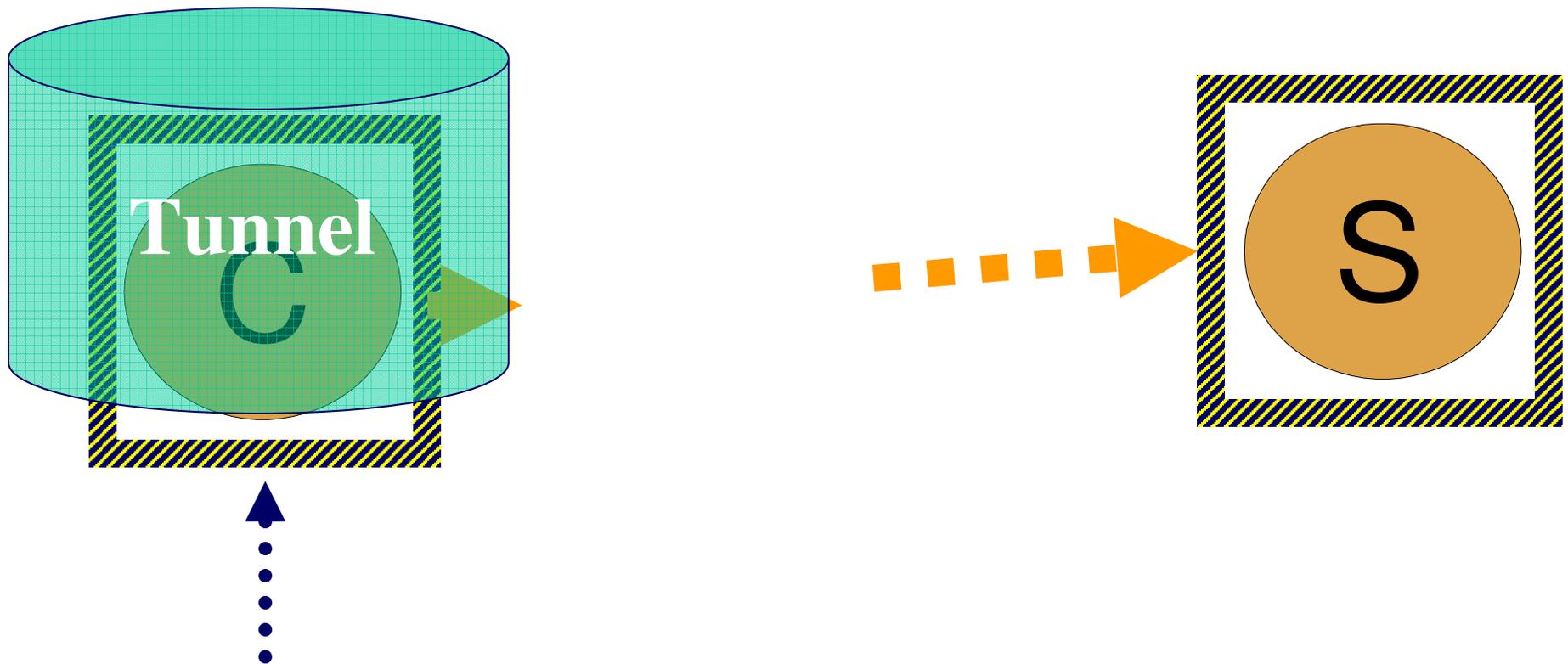
Mobile devices
going around obstacles



Or, why π -calculus is not the whole story.

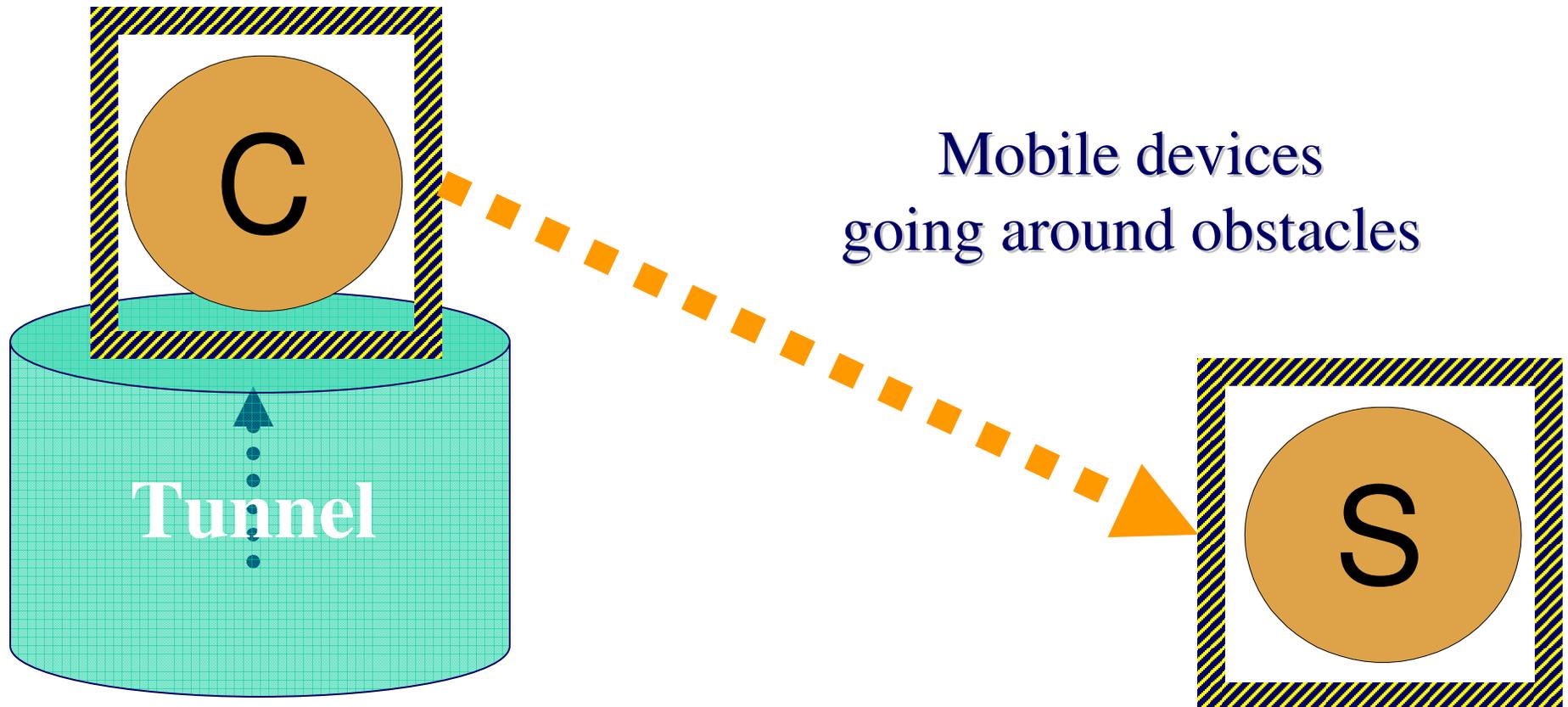
Tunnel Effect

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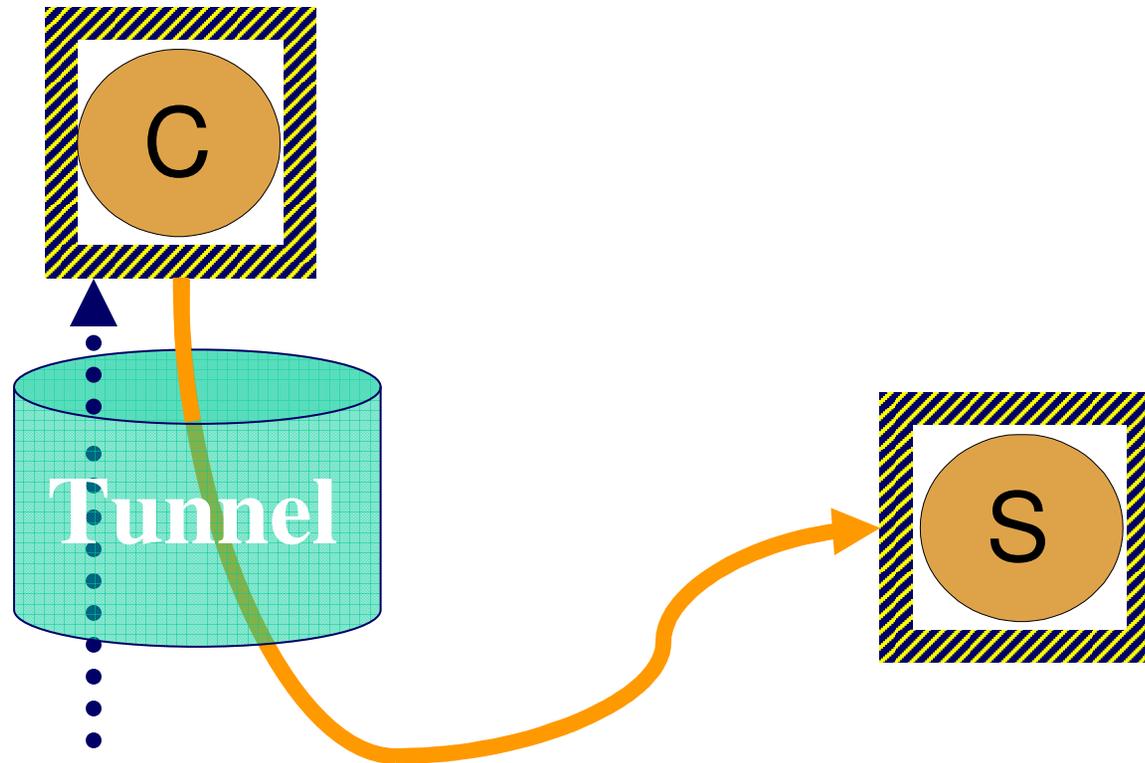
Tunnel Effect



Or, why π -calculus is not the whole story.

Tunnels vs Reliable Communication

Reliable communication = continuous unbreakable wires



Reliable communication + Tunnels

= wires get tangled (and untangling them is hard)

= eventually one can no longer move (or the wire breaks).

About the Tunnel Effect

In hardwired communication:

- Whoever is *capable* of communication (holds one end of the wire) is always *able* to communicate (send/receive on the wire).
- Unless, of course, something is broken.

In the tunnel effect:

- The client is *capable* of communication (holds one end of the “wire”) but is still *unable* to communicate in some cases. (He can scream but no one can hear.)
- Moreover, nothing is broken:
 - The client is working. The server is working.
 - The tunnel tunnels.
 - The ether works like physics says it should.
 - All goes back to normal without need to *fix* anything.

Just one of a variety of phenomena where...

Sudden Inability to Communicate

No longer to be regarded as a failure

It is a state of affairs, due to many causes:

- Congestion (“The server could not be reached.”)
- Obstructions (“Infrared device out of sight.”)
- Geography (“No Cellnet service in Kinloch Rannoch.”)
- Security (“No Internet access at Edinburgh”))
- Safety (“No electronic devices during takeoff and landing.”)
- Policy (“You are prohibited from using mobile phones.”)
- Privacy (“Please leave your number, we will call you back.”)
- Psyche (“I left my mobile phone in my pants.”)
- Crime (“My laptop was stolen at Charles De Gaulle’s.”)
- Physics (“Please wait for an answer from Mars.”)

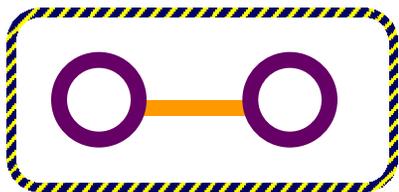
You Are in the Wrong Place

Nothing is broken

- “broken” \triangleq “somebody can be found to fix the problem”.
- In the cases above, nothing is “broken”. Yet, things don’t connect.
- The failure model is not “it crashed” but...

Connectivity Depends on Location

1) Proximity:



Ok. Fast (bounded delay), reliable, secure.

2) Physical distance: (possibly with virtual distance = 0)



No such thing as remote real-time control. No unbreakable links. Observationally different from (1).

3) Virtual distance: (possibly with physical distance = 0)



No such thing as implicitly secure remote links. Observationally different from (1).

Summary: Global Communication

Connectivity is about:

- Not only connectivity of wire endpoints in “flat” dynamic topology (π -calculus, distributed object systems)
- But also connectivity of wire endpoints in nested dynamic topology (Ambient Calculus, agent systems).
- In complex topologies, wires endpoints cannot be continuously connected.

To model global (wide-area, mobile) communication:

- We need to model *locations* where communication is attempted.
- We need to distinguish capability from accessibility:
 - Able to act, but in the wrong place:
security by location access control.
 - In the right place, but unable to act:
security by resource access control.

Global Computation

How do we embed the features and restrictions of global communication in a computational model?

We must abandon the familiar notion of function call/handshake.

- We cannot afford to have every function call over the network to block waiting for an answer. (π vs. $\text{async-}\pi$.)

We must even abandon the familiar notion of symmetric multi-party (even async) channel communication.

- We cannot afford to solve consensus problems all the time. ($\text{async-}\pi$ vs. join .)

We must abandon the familiar notion of pointers/references.

- We cannot afford references of any kind that are *always* connected to their target, and we must be able to reconnect them later. (π vs. ambients .)

We must abandon familiar failure models.

- We cannot assume that every failure leads to an exception.
- We cannot assume we are even allowed to know that a failure ever happened.

Ambients Approach

We want to capture in an abstract way, notions of locality, of mobility, and of ability to cross barriers.

An *ambient* is a place, delimited by a boundary, where computation happens.

Ambients have a name, a collection of local processes, and a collection of subambients.

Ambients can move in and out of other ambients, subject to capabilities that are associated with ambient names.

Ambient names are unforgeable (as in π and spi).

The Ambient Calculus

The *Ambient Calculus*: a computational model for:

- Behaviors that are *capable* but sometimes *unable* to communicate.

To this end, spatial structures (agents, networks, etc.) are represented by nested locations:

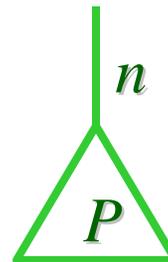
Processes

0 (void)

$n[P]$ (location)

$P \mid Q$ (composition)

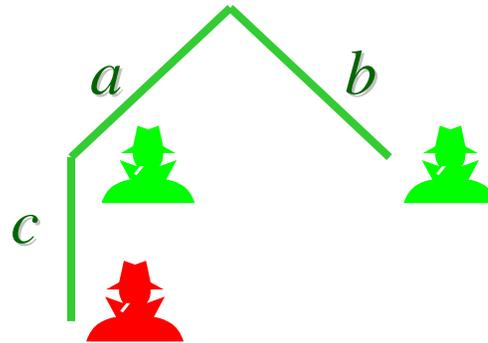
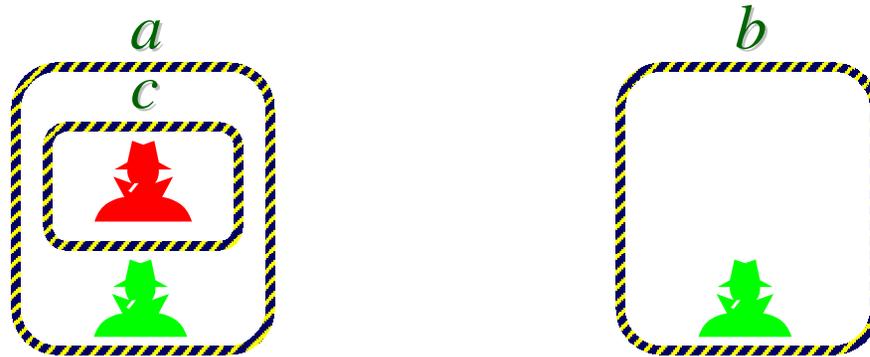
Tree Representation



Mobility



Mobility is change of spatial structures over time.



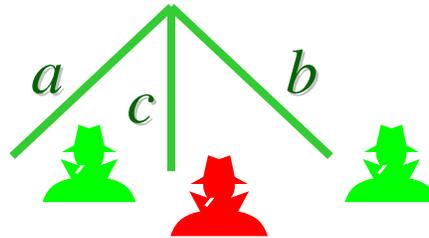
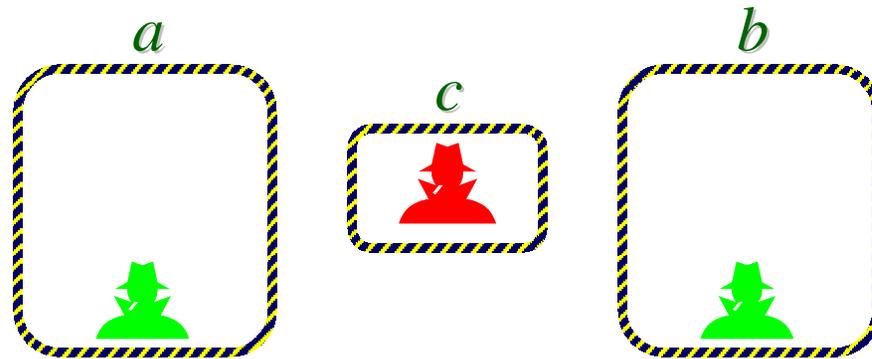
$a[Q \mid c[out\ a.\ in\ b.\ P]]$

$\mid b[R]$

Mobility



Mobility is change of spatial structures over time.

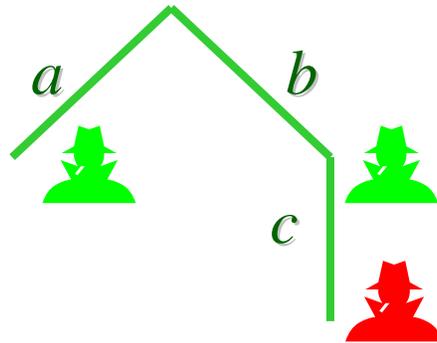
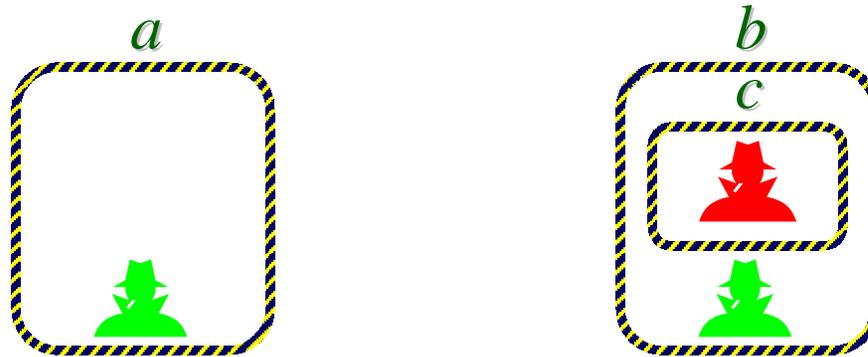


$a[Q]$

$| c[in\ b.\ P] | b[R]$

Mobility

Mobility is change of spatial structures over time.



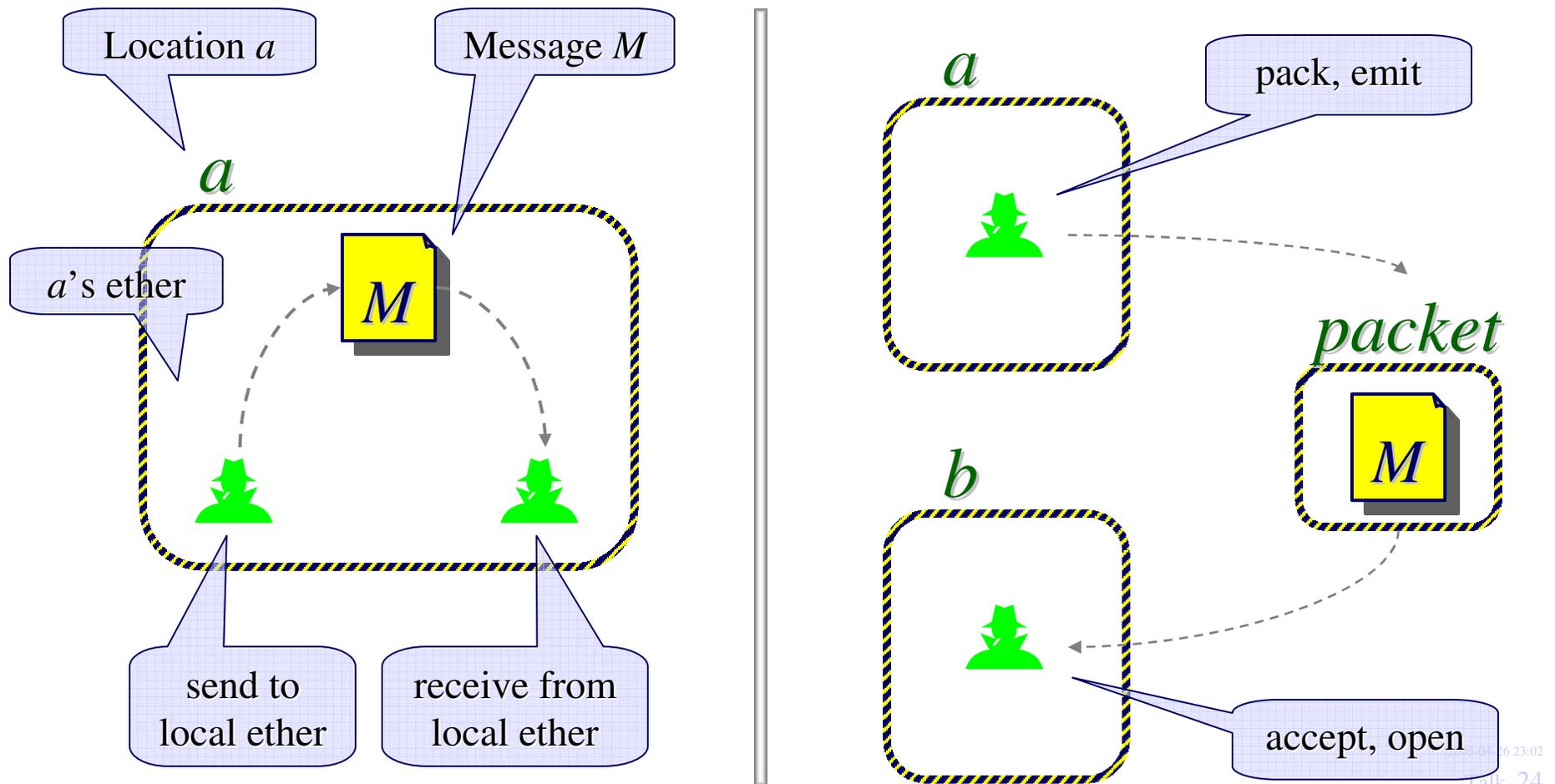
$a[Q]$

$| b[R | c[P]]$

Communication

Communication is strictly local, within a given location.

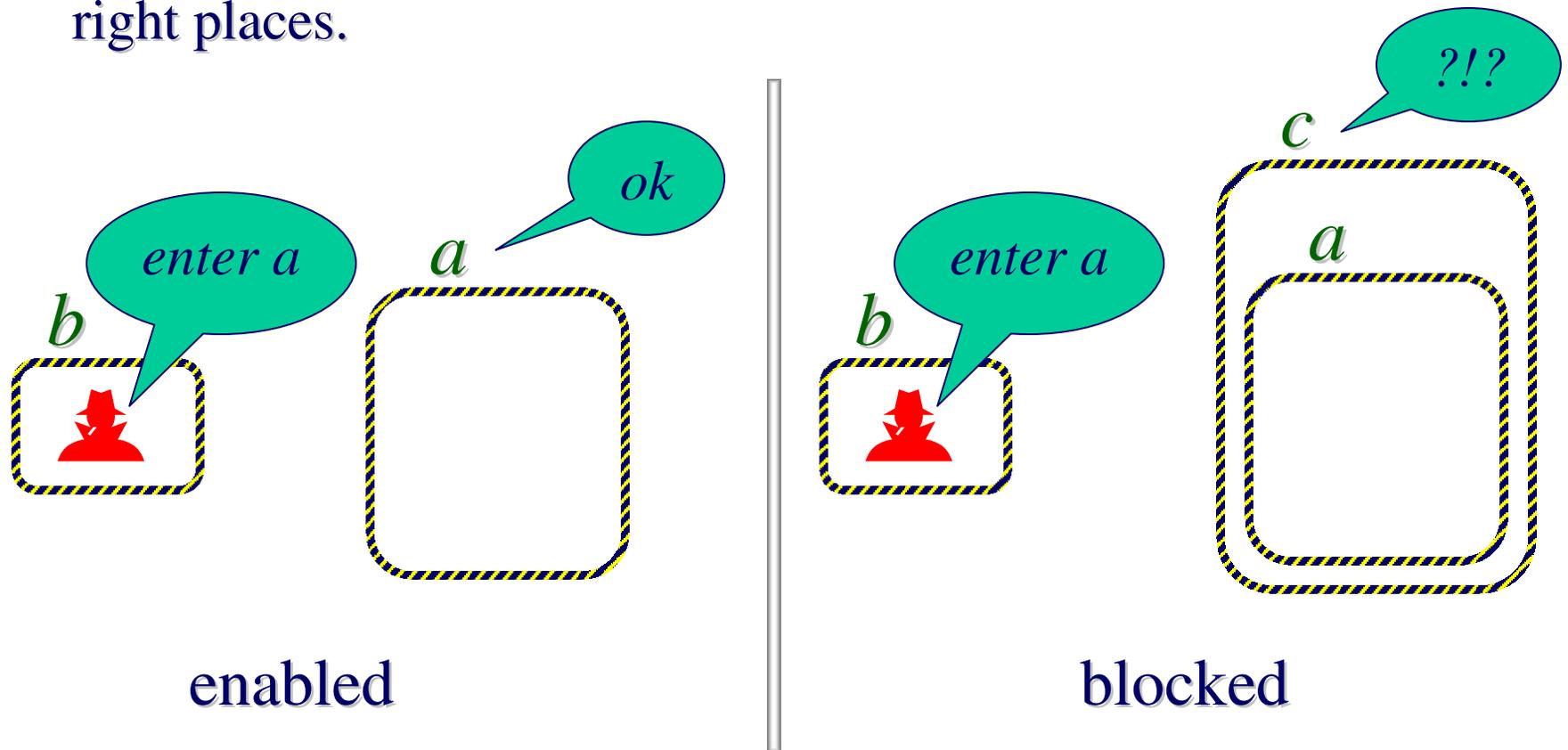
Remote communication must be simulated by sending around mobile packets (which may get lost).



Security

Security issues are reduced to the ability to create, destroy, enter and exit locations.

- π -calculus restriction accounts for private capabilities.
- As for communication, capabilities can be exercised only in the right places.



The Ambient Calculus

$P \in \Pi ::=$ Processes

$(\nu n)P$ restriction

0 inactivity

$P \mid P'$ parallel

$M[P]$ ambient

$!P$ replication

$M.P$ exercise a capability

$(n).P$ input locally, bind to n

$\langle M \rangle$ output locally (async)

Location
Trees
Spatial

$M ::=$

Messages

n

name

$in M$

entry capability

$out M$

exit capability

$open M$

open capability

ε

empty path

$M.M'$

composite path

Actions

Temporal

$$n[] \triangleq n[0]$$

$$M \triangleq M.0 \quad (\text{where appropriate})$$

Reduction Semantics

A structural congruence relation $P \equiv Q$:

- On spatial expressions, $P \equiv Q$ iff P and Q denote the same tree. So, the syntax modulo \equiv is a notation for spatial trees.
- On full ambient expressions, $P \equiv Q$ if in addition the respective threads are “trivially equivalent”.
- Prominent in the definition of the logic.

A reduction relation $P \rightarrow^* Q$:

- Defining the meaning of mobility and communication actions.
- Closed up to structural congruence:

$$P \equiv P', P' \rightarrow^* Q', Q' \equiv Q \quad \Rightarrow \quad P \rightarrow^* Q$$

Reduction

$n[in\ m.\ P \mid Q] \mid m[R]$	$\rightarrow m[n[P \mid Q] \mid R]$	(Red In)
$m[n[out\ m.\ P \mid Q] \mid R]$	$\rightarrow n[P \mid Q] \mid m[R]$	(Red Out)
$open\ m.\ P \mid m[Q]$	$\rightarrow P \mid Q$	(Red Open)
$(n).P \mid \langle M \rangle$	$\rightarrow P\{n \leftarrow M\}$	(Red Comm)
$P \rightarrow Q \Rightarrow (\forall n)P \rightarrow (\forall n)Q$		(Red Res)
$P \rightarrow Q \Rightarrow n[P] \rightarrow n[Q]$		(Red Amb)
$P \rightarrow Q \Rightarrow P \mid R \rightarrow Q \mid R$		(Red Par)
$P' \equiv P, P \rightarrow Q, Q \equiv Q' \Rightarrow P' \rightarrow Q'$		(Red \equiv)

\rightarrow^* is the reflexive-transitive closure of \rightarrow

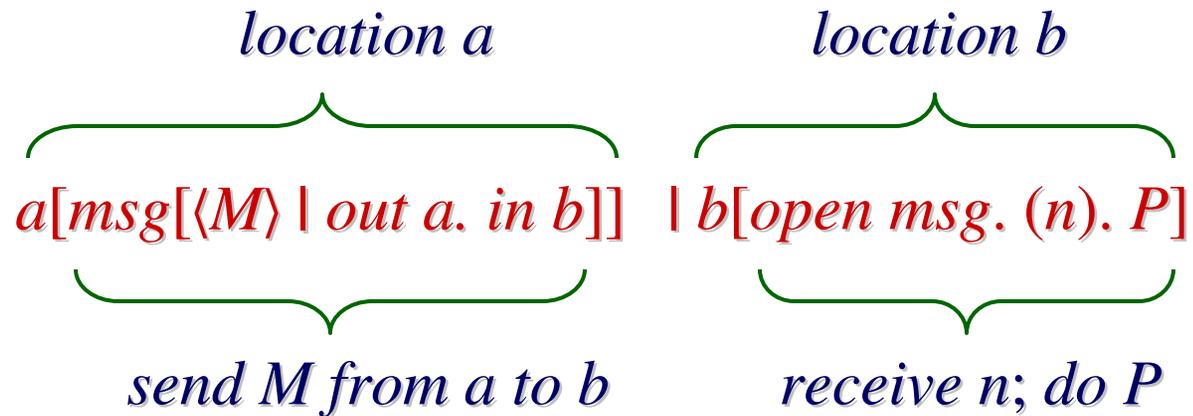
Structural Congruence

$P \equiv P$	(Struct Refl)
$P \equiv Q \Rightarrow Q \equiv P$	(Struct Symm)
$P \equiv Q, Q \equiv R \Rightarrow P \equiv R$	(Struct Trans)
$P \equiv Q \Rightarrow (\nu n)P \equiv (\nu n)Q$	(Struct Res)
$P \equiv Q \Rightarrow P \mid R \equiv Q \mid R$	(Struct Par)
$P \equiv Q \Rightarrow !P \equiv !Q$	(Struct Repl)
$P \equiv Q \Rightarrow M[P] \equiv M[Q]$	(Struct Amb)
$P \equiv Q \Rightarrow M.P \equiv M.Q$	(Struct Action)
$P \equiv Q \Rightarrow (n).P \equiv (n).Q$	(Struct Input)
$\varepsilon.P \equiv P$	(Struct ε)
$(M.M').P \equiv M.M'.P$	(Struct .)

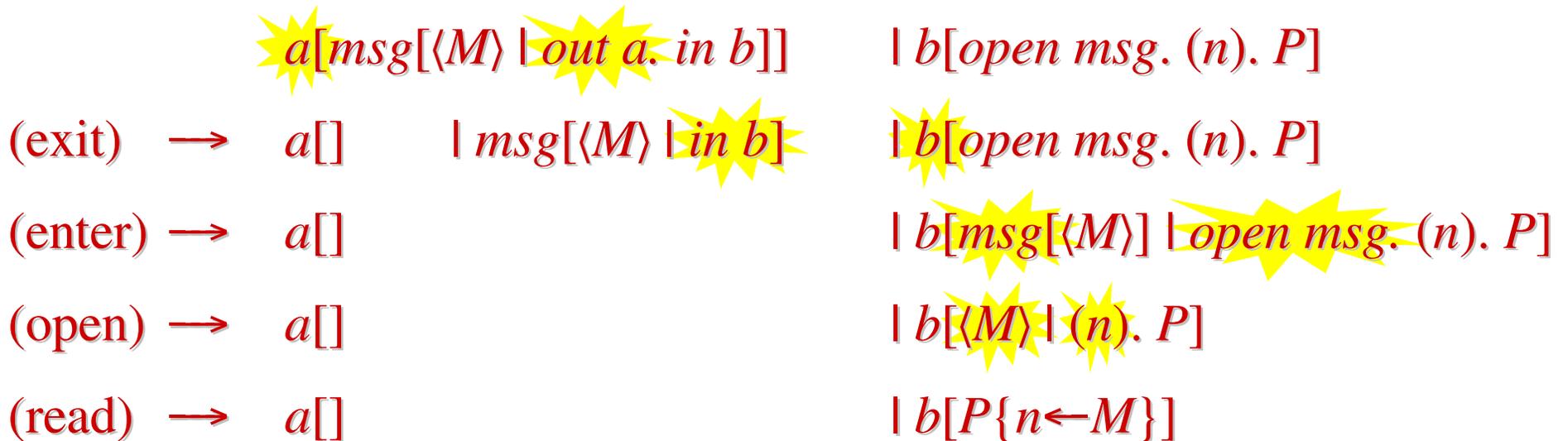
$(\forall n)\mathbf{0} \equiv \mathbf{0}$	(Struct Res Zero)
$(\forall n)(\forall m)P \equiv (\forall m)(\forall n)P$	(Struct Res Res)
$(\forall n)(P \mid Q) \equiv P \mid (\forall n)Q$ if $n \notin fn(P)$	(Struct Res Par)
$(\forall n)(m[P]) \equiv m[(\forall n)P]$ if $n \neq m$	(Struct Res Amb)
$P \mid Q \equiv Q \mid P$	(Struct Par Comm)
$(P \mid Q) \mid R \equiv P \mid (Q \mid R)$	(Struct Par Assoc)
$P \mid \mathbf{0} \equiv P$	(Struct Par Zero)
$!(P \mid Q) \equiv !P \mid !Q$	(Struct Repl Par)
$!\mathbf{0} \equiv \mathbf{0}$	(Struct Repl Zero)
$!P \equiv P \mid !P$	(Struct Repl Copy)
$!P \equiv !!P$	(Struct Repl Repl)

These axioms (particularly the ones for !) are sound and complete with respect to equality of spatial trees: edge-labeled finite-depth unordered trees, with infinite-branching but finitely many distinct labels under each node.

Ambient Calculus: Example



The packet *msg* moves from *a* to *b*, mediated by the capabilities *out a* (to exit *a*), *in b* (to enter *b*), and *open msg* (to open the *msg* envelope).



Noticeable Inequivalences

Replication creates new names:

$$!(\nu n)P \not\equiv (\nu n)!P$$

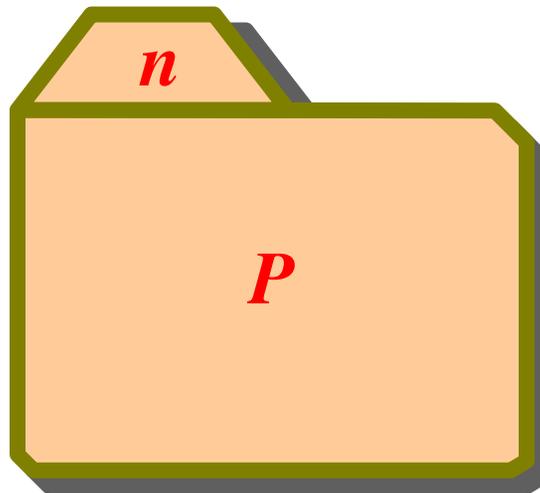
Multiple n ambients have separate identity:

$$n[P] \mid n[Q] \not\equiv n[P \mid Q]$$

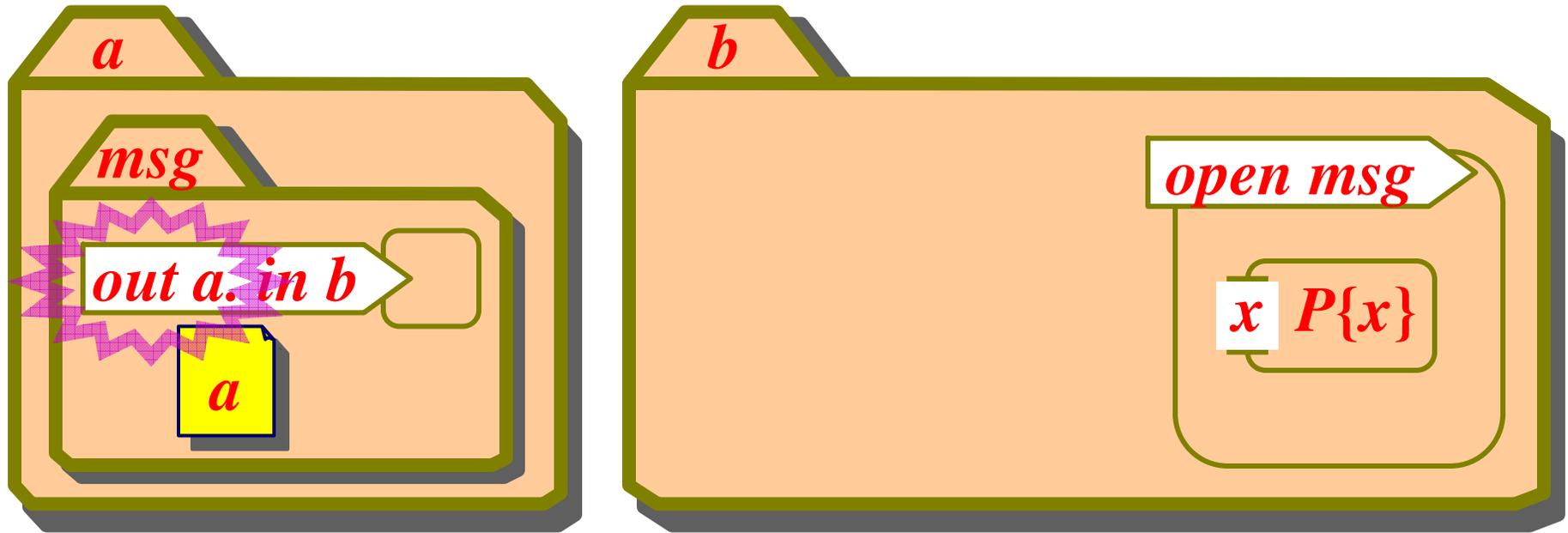
Folder Metaphor

An ambient can be graphically represented as a folder:

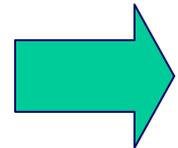
- Consisting of a folder name n ,
- And active contents P , including:
 - Hierarchical data, and computations (“gremlins”).
 - Primitives for mobility and communication.



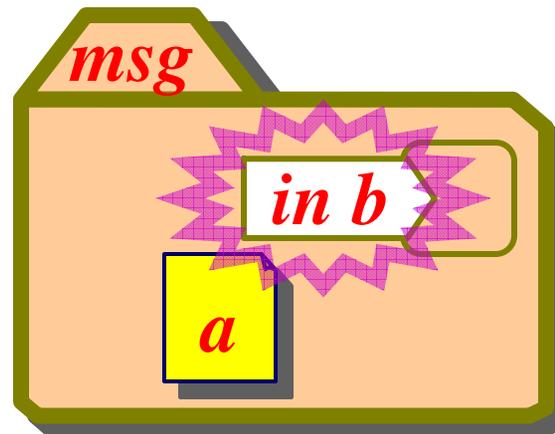
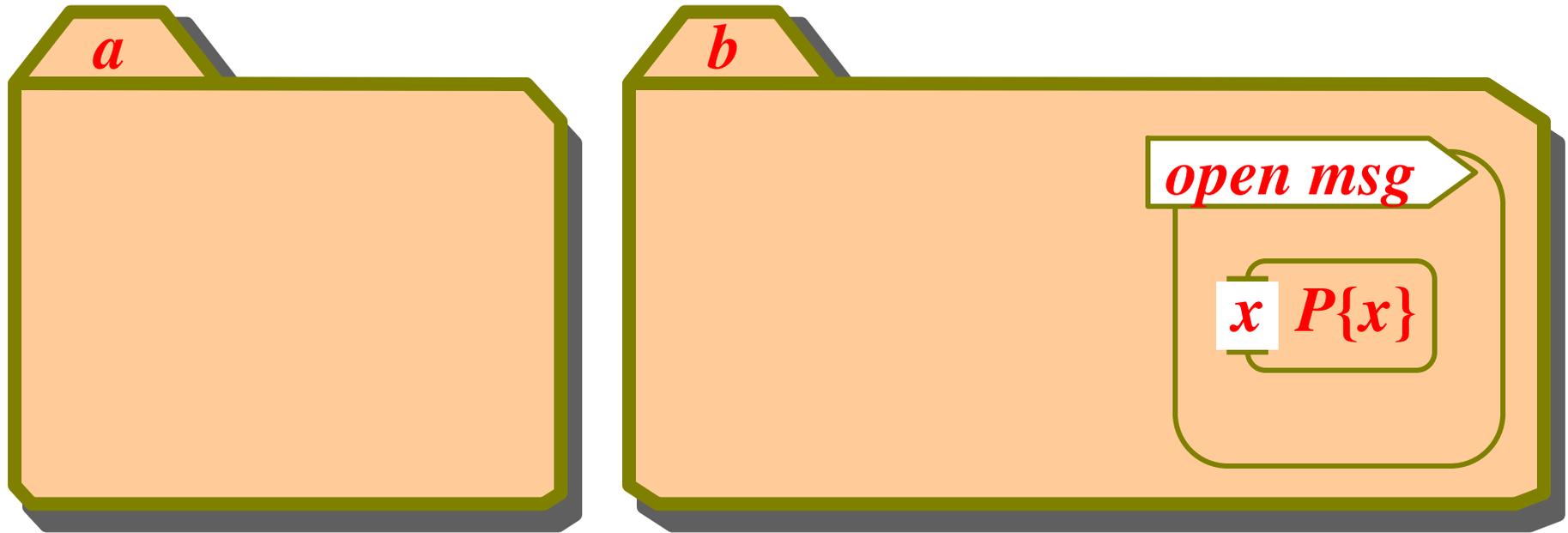
Example: Message from a to b



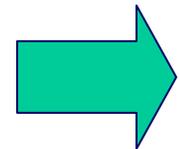
Exit



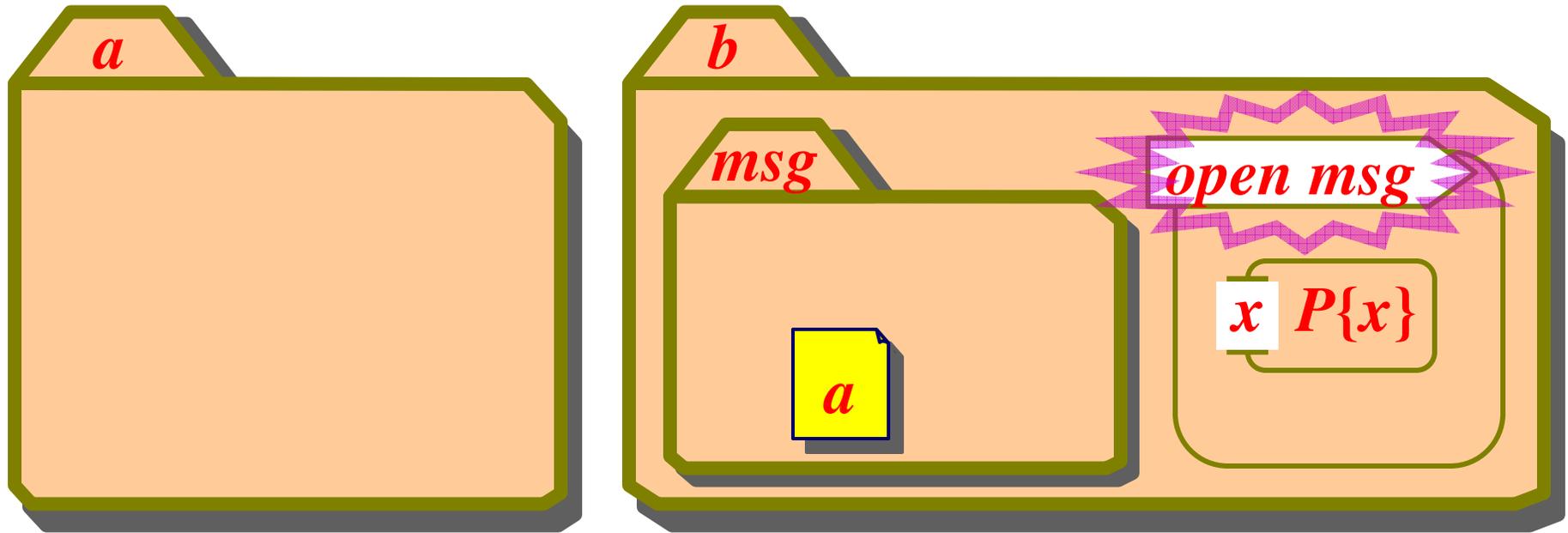
Example: Message from a to b



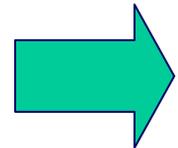
Enter



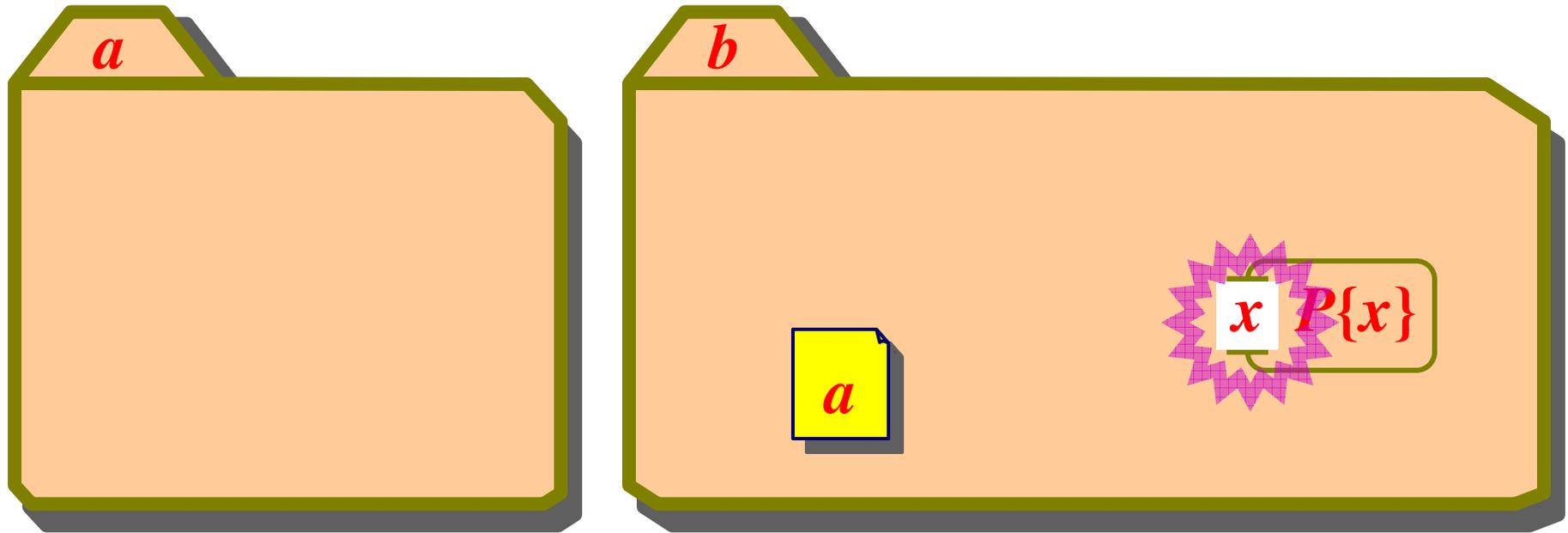
Example: Message from a to b



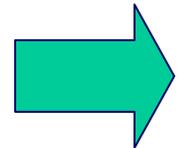
Open



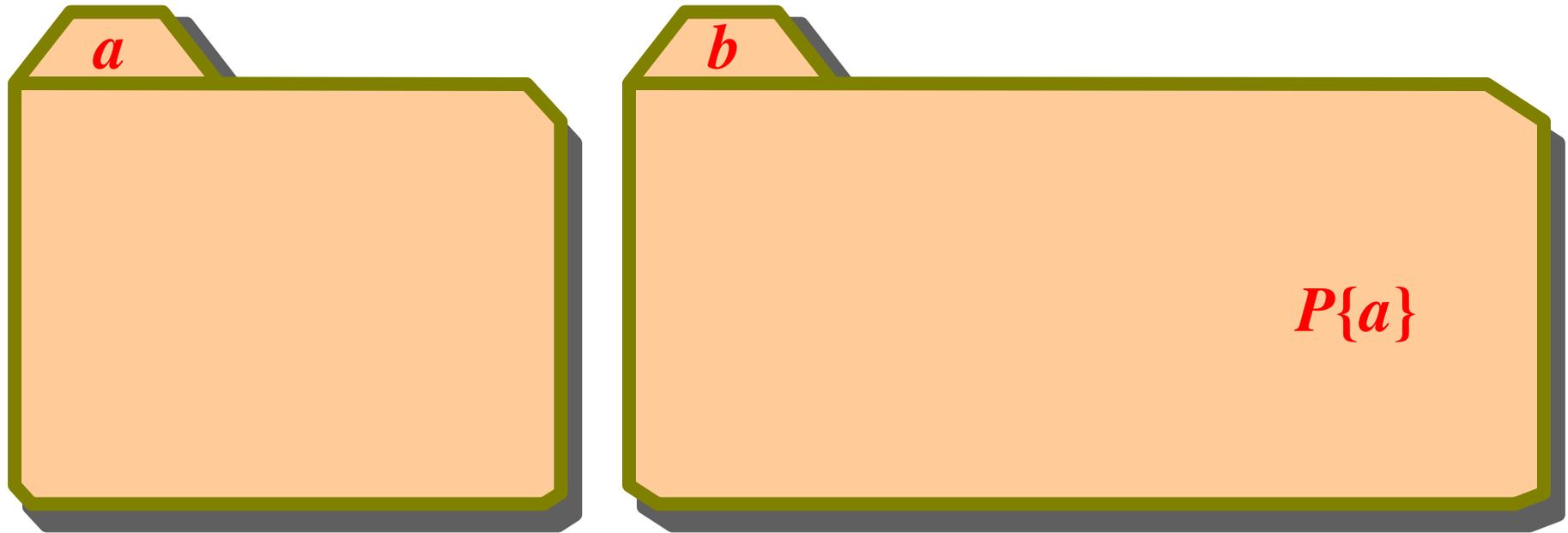
Example: Message from a to b



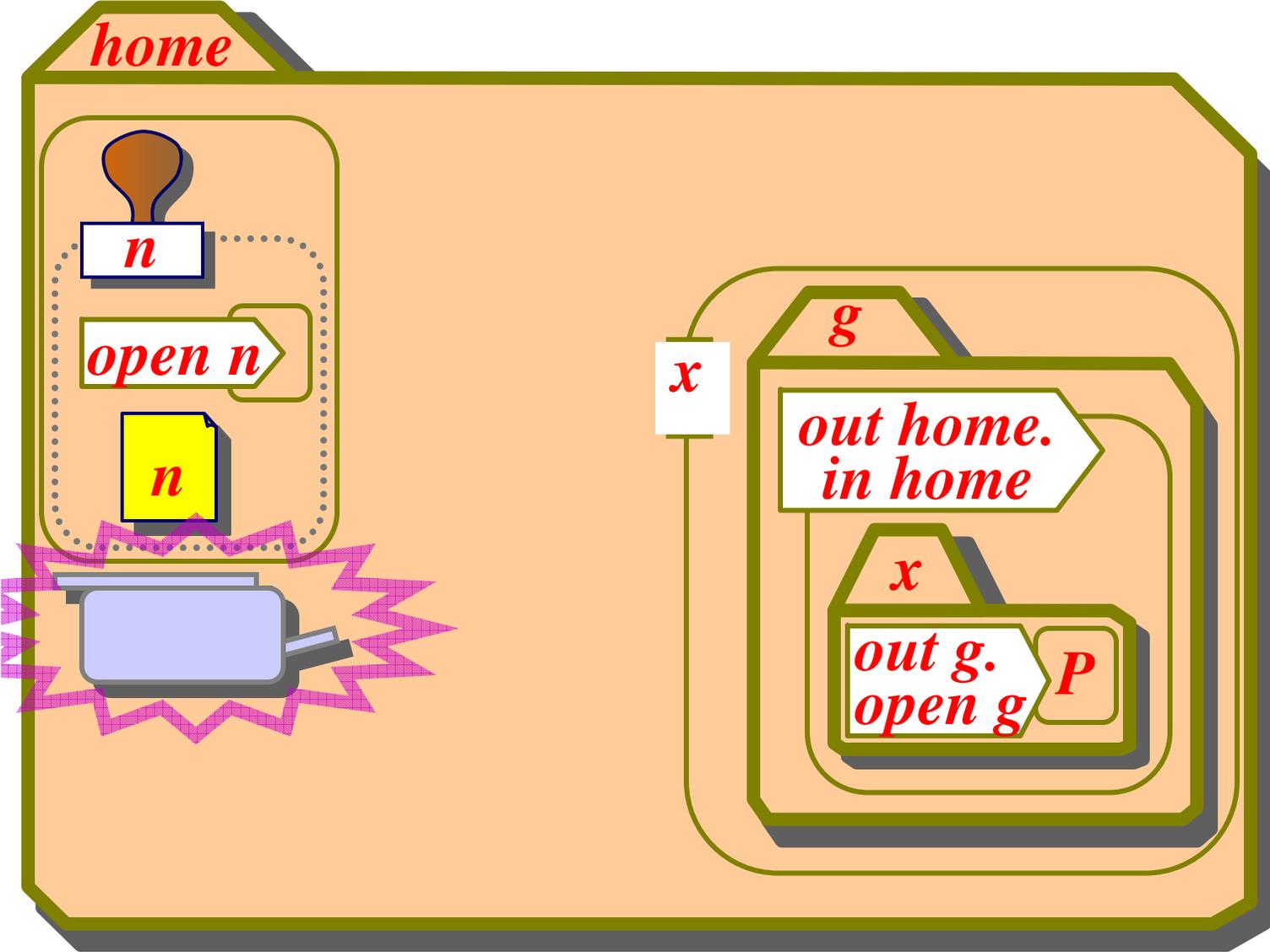
Read



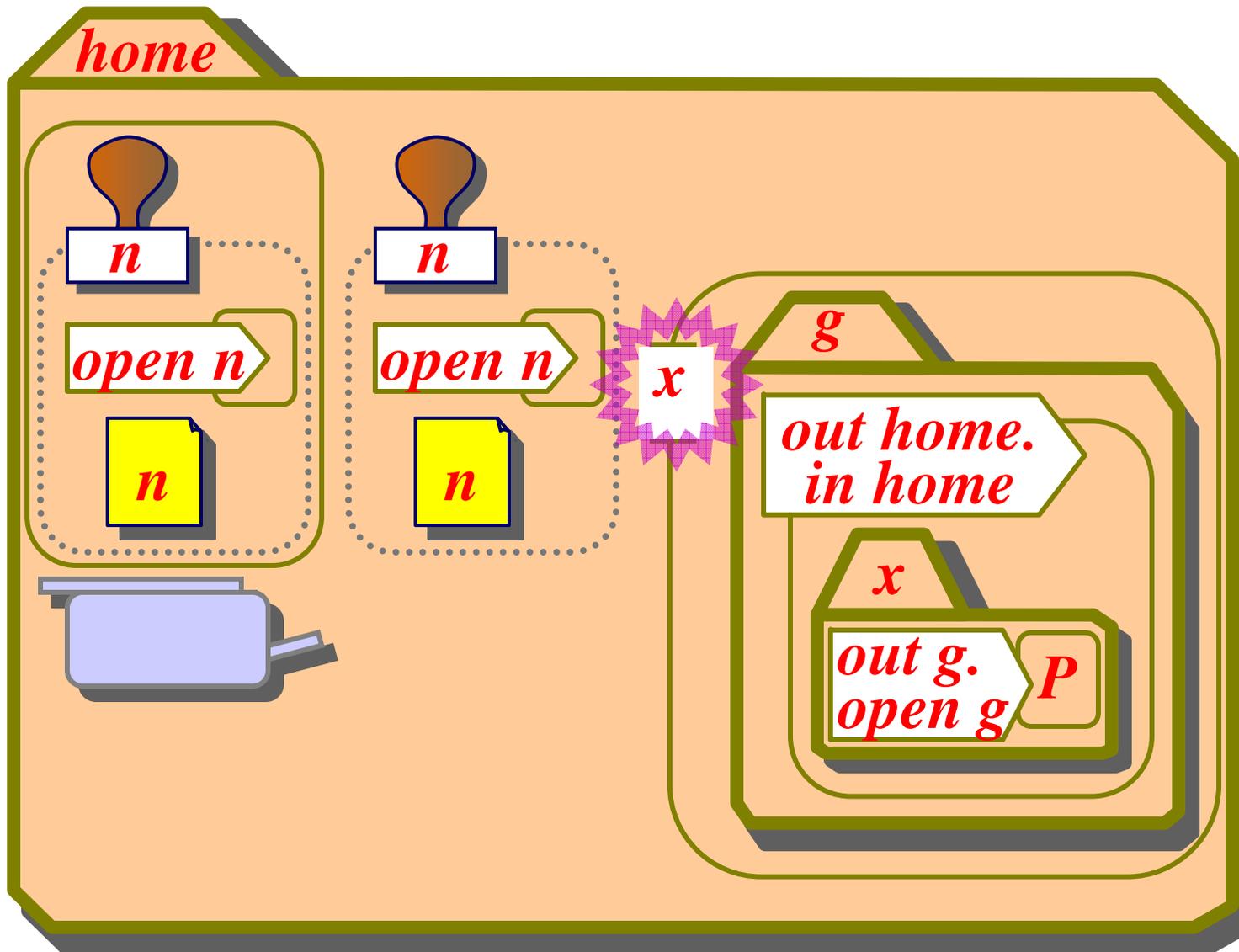
Example: Message from a to b



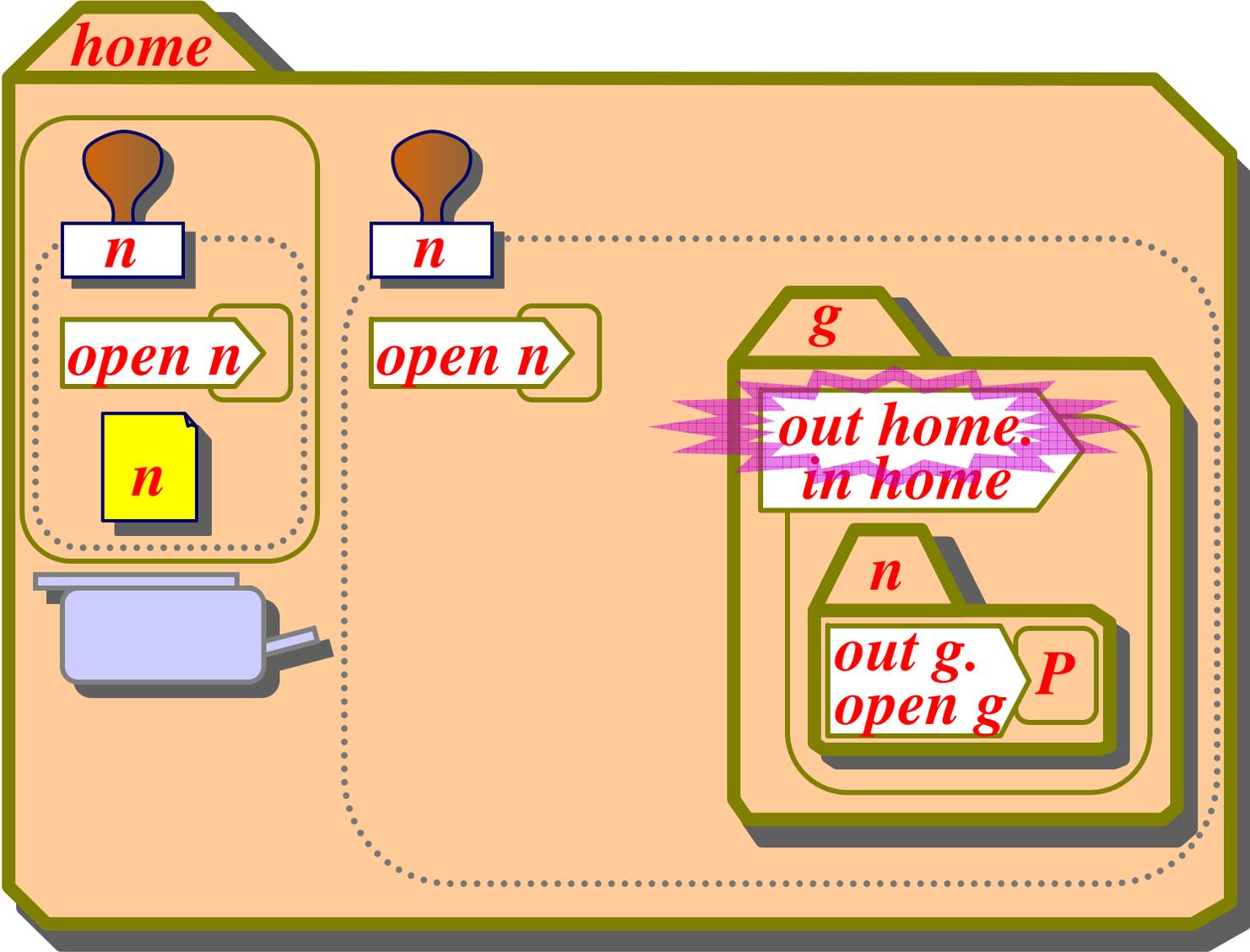
Example: Agent Authentication



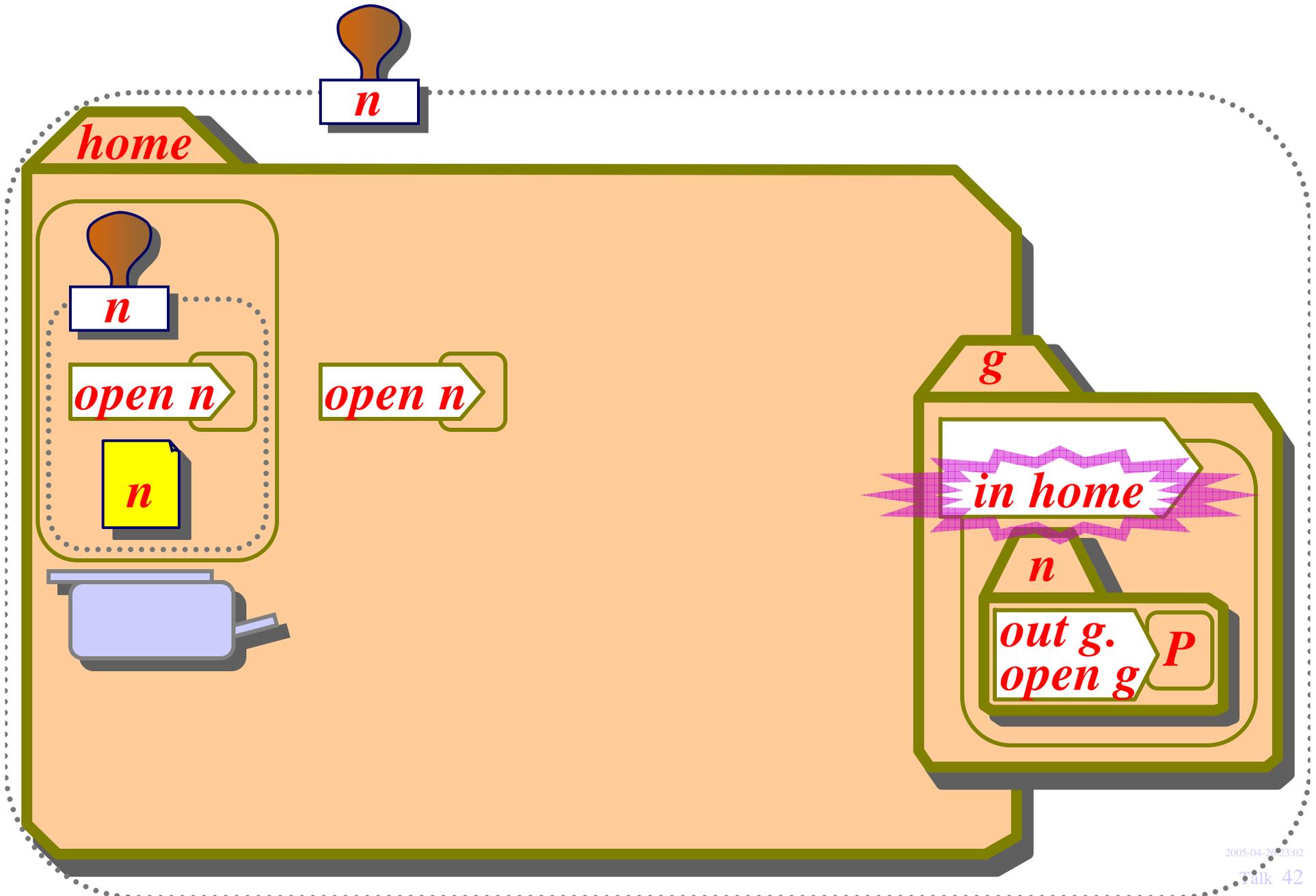
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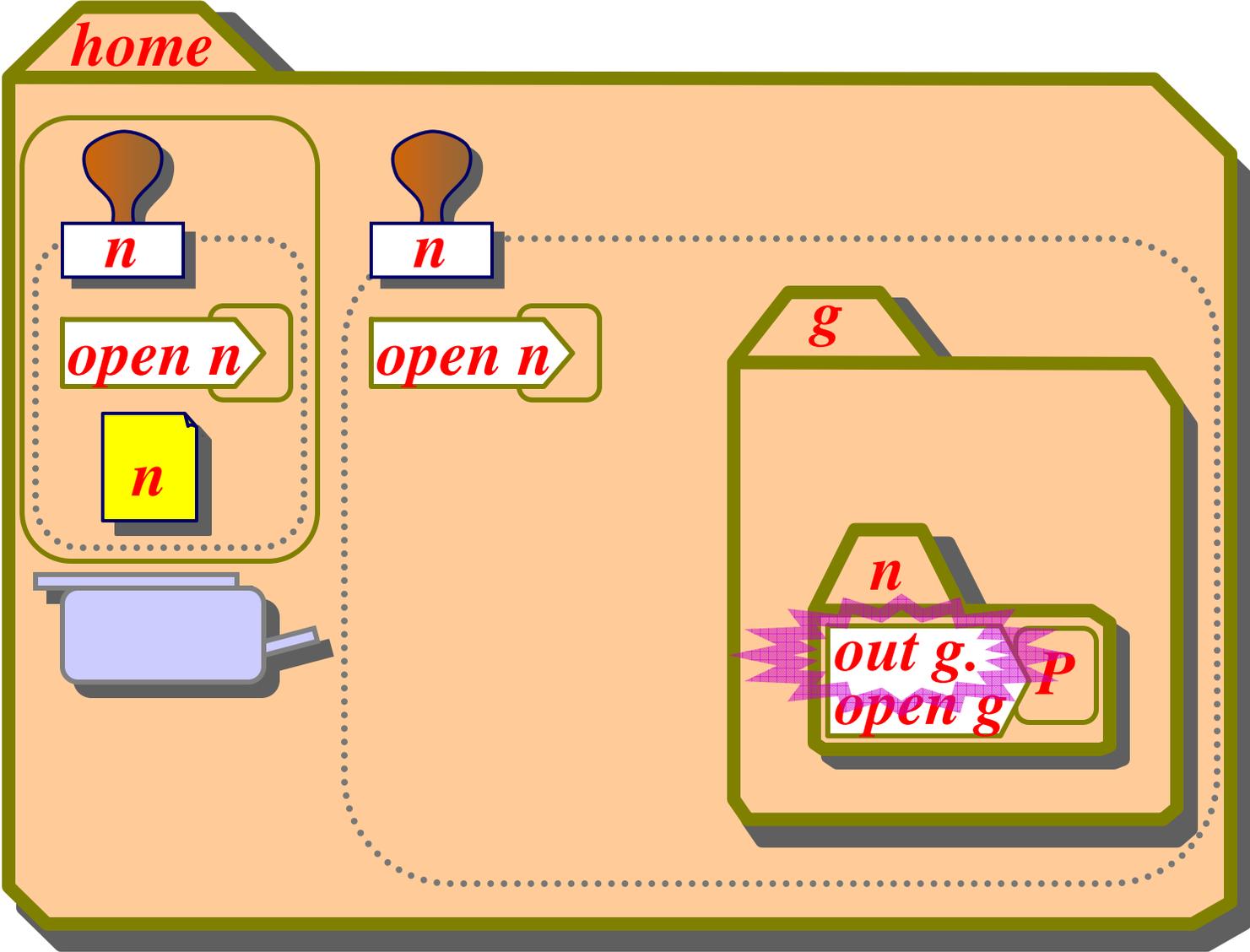
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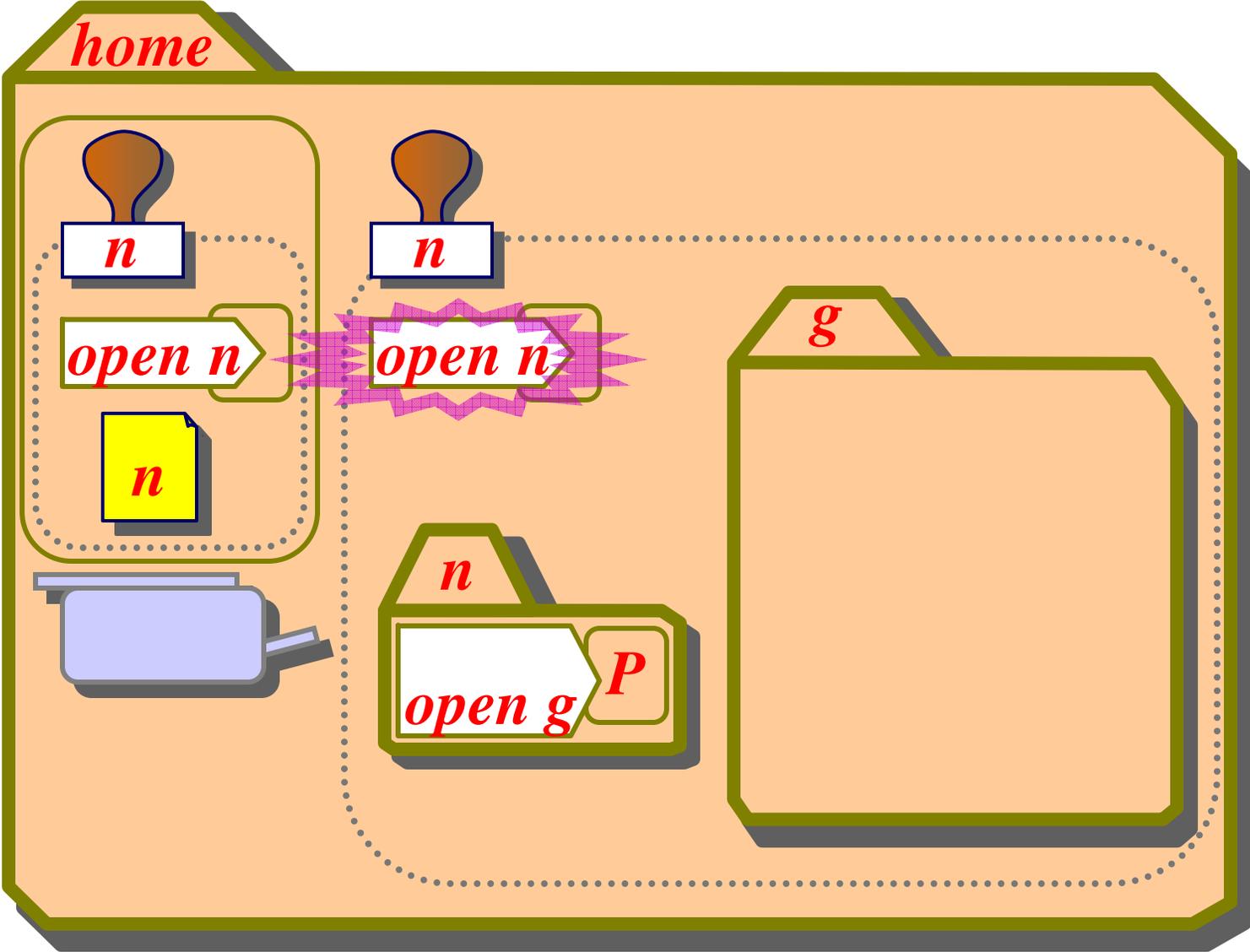
Example: Agent Authentication



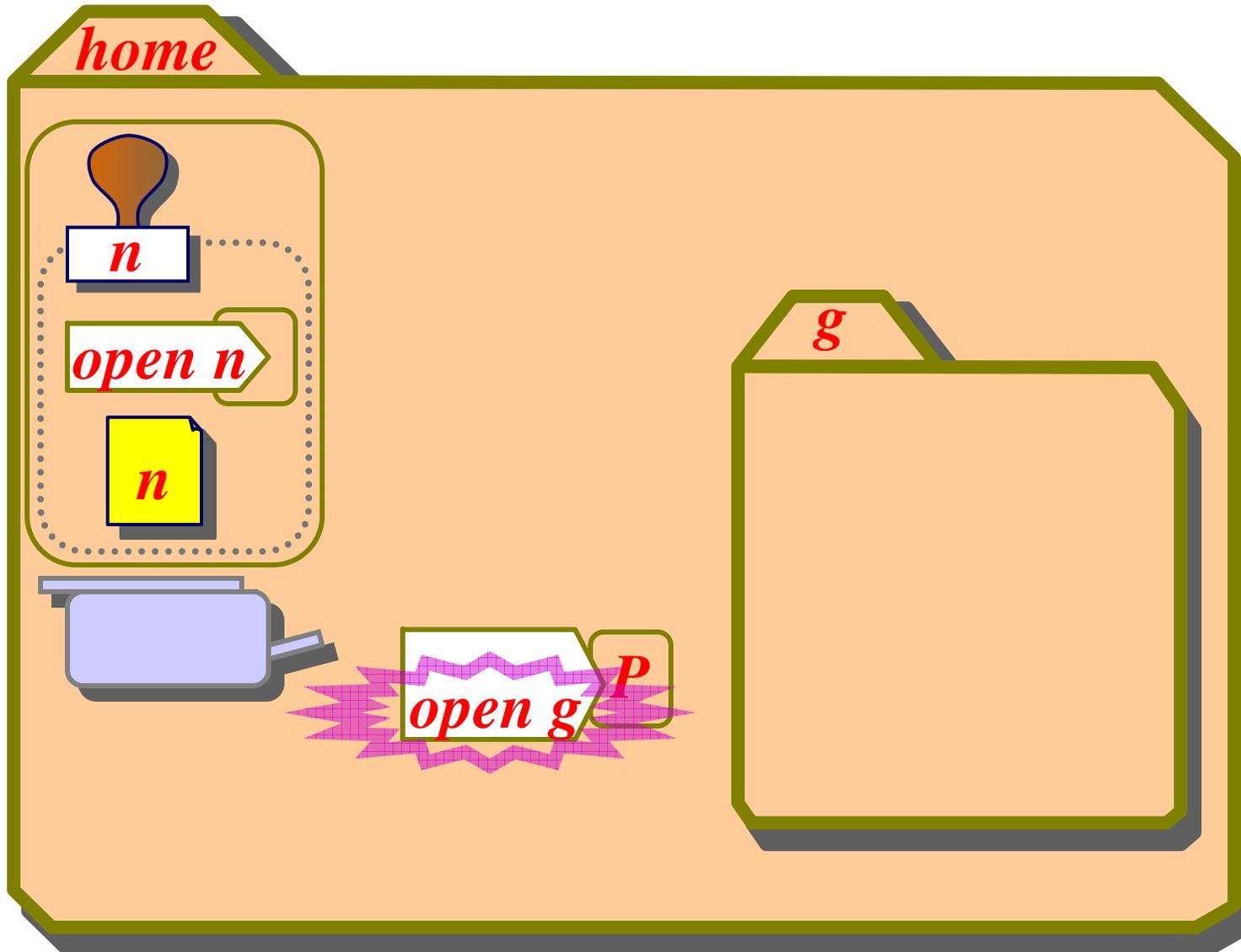
Example: Agent Authentication



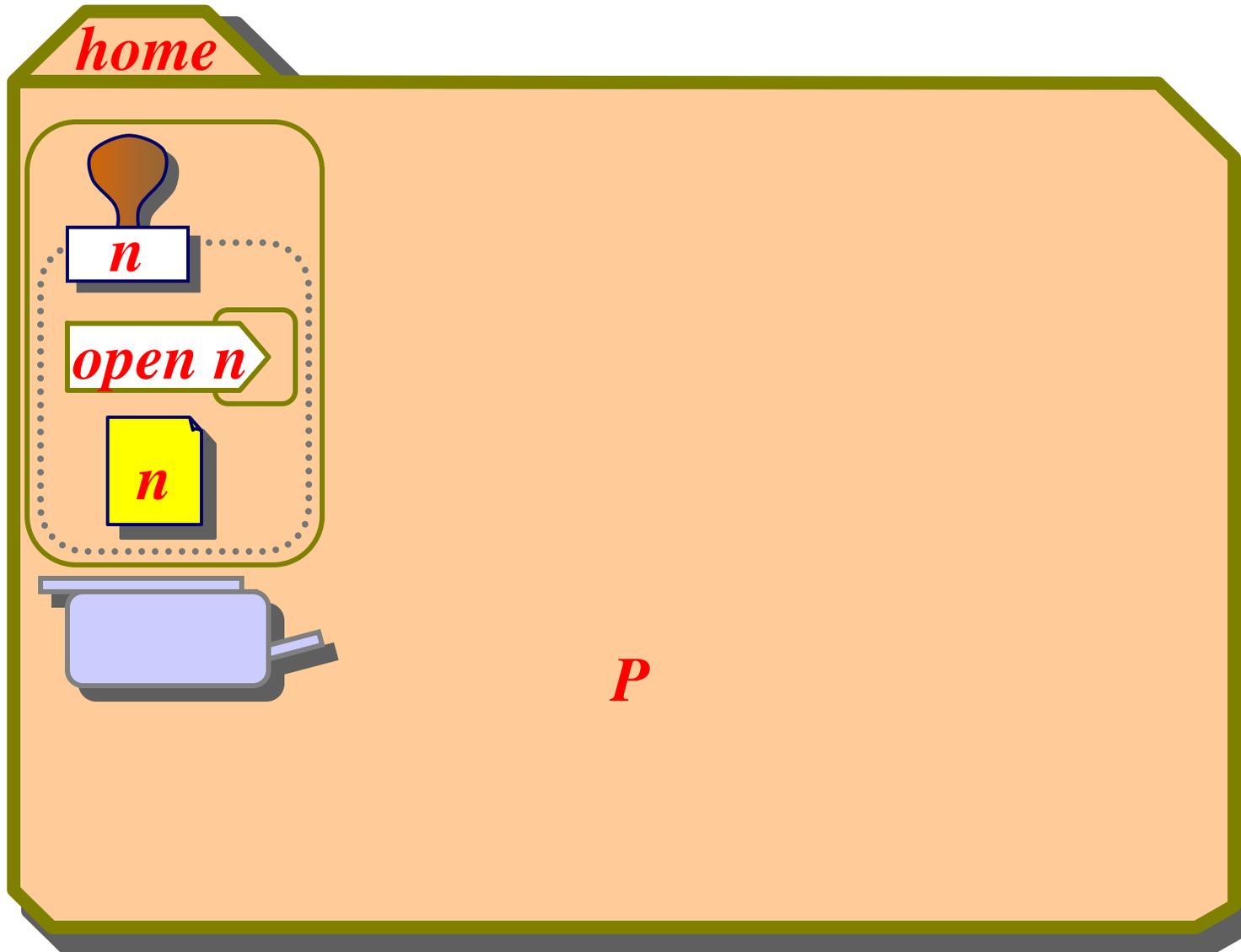
Example: Agent Authentication



Example: Agent Authentication



Example: Agent Authentication



Calculi for Communication

One basic notion

- Communication channels (a.k.a. *wires*).

One billion variations

- Value passing / name passing / process passing
- Synchronous / asynchronous / broadcast
- Internal choice / external choice / mixed choice / no choice
- Linearity / fresh output
- ...

Calculi for Mobility

One basic notion

- Dynamic topology

One million variations

- Name mobility, process mobility
- Synchronous / asynchronous / datagram
- Actions / coactions / intermediaries
- Talk to local ether / talk to parent / talk to children
- ...

Safe Ambients [Levi, Sangiorgi]

“Each action has an equal and opposite coaction.”

In Ambient Calculus it is difficult to count reliably the number of visitors to an ambient. The fix:

$$\begin{array}{lll} n[\mathit{in} \ m. \ P \mid Q] \mid m[\mathit{in} \ m. \ R \mid S] & \longrightarrow & m[n[P \mid Q] \mid R \mid S] & \text{(In)} \\ m[n[\mathit{out} \ m. \ P \mid Q] \mid \mathit{out} \ m. \ R \mid S] & \longrightarrow & n[P \mid Q] \mid m[R \mid S] & \text{(Out)} \\ \mathit{open} \ n. \ P \mid n[\mathit{open} \ n. \ Q \mid R] & \longrightarrow & P \mid Q \mid R & \text{(Open)} \\ (m).P \mid \langle M \rangle.Q & \longrightarrow & P\{m \leftarrow M\} \mid Q & \text{(Comm)} \end{array}$$

The Ambient Calculus is recovered by sprinkling $\mathit{!in} \ n$, $\mathit{!out} \ n$, $\mathit{!open} \ n$ appropriately.

Channeled Ambients [Pericas-Geertsen]

Each ambient contains a list of channels c that are used for named communication within the ambient. They are restricted as usual.

$n[D, c; c\langle M \rangle.P \mid c(m).Q \mid R]$ (Send)

$\rightarrow n[D, c; P \mid Q\{m \leftarrow M\} \mid R]$

$n[D; in\ m.P \mid Q] \mid m[E; R] \rightarrow m[E; n[D; P \mid Q] \mid R]$ (In)

$m[E; n[D; out\ m.P \mid Q] \mid R] \rightarrow n[D; P \mid Q] \mid m[E; R]$ (Out)

$m[D; open\ n.P \mid n[E; Q] \mid R] \rightarrow m[D; P \mid Q \mid R]$ (Open)

Boxed Ambients [Bugliesi, Castagna, Crafa]

I/O to parents/children is tricky to encode reliably in Ambient Calculus, but is a very natural basic primitive.

Boxed Ambients provide it directly (simplifying Seal):

$n[in\ m.\ P \mid Q] \mid m[R]$	$\rightarrow m[n[P \mid Q] \mid R]$	(In)
$m[n[out\ m.\ P \mid Q] \mid R]$	$\rightarrow n[P \mid Q] \mid m[R]$	(Out)
		no (Open)
$(m).P \mid \langle M \rangle.Q$	$\rightarrow P\{m \leftarrow M\} \mid Q$	(Local)
$(m)^n.P \mid n[\langle M \rangle.Q \mid R]$	$\rightarrow P\{m \leftarrow M\} \mid n[Q \mid R]$	(Input n)
$\langle M \rangle^n.P \mid n[(m).Q \mid R]$	$\rightarrow P \mid n[Q\{m \leftarrow M\} \mid R]$	(Output n)
$\langle M \rangle.P \mid n[(m)^\uparrow.Q \mid R]$	$\rightarrow P \mid n[Q\{m \leftarrow M\} \mid R]$	(Input \uparrow)
$(m).P \mid n[\langle M \rangle^\uparrow.Q \mid R]$	$\rightarrow P\{m \leftarrow M\} \mid n[Q \mid R]$	(Output \uparrow)

Ambients [Bugliesi, Castagna]

[CG] Ambient Calculus + [AC] Object Calculus =

$n.a(M).P \mid n[D; a(m).Q; R] \quad (\text{Send})$
 $\rightarrow P \mid Q\{m \leftarrow M, \text{self} \leftarrow n\} \mid n[D; a(m).Q; R]$

$n[D; \text{in } m. P \mid Q] \mid m[E; R] \quad \rightarrow \quad m[E; n[D; P \mid Q] \mid R] \quad (\text{In})$

$m[E; n[D; \text{out } m. P \mid Q] \mid R] \quad \rightarrow \quad n[D; P \mid Q] \mid m[E; R] \quad (\text{Out})$

$m[E; \text{open } n. P \mid n[D; Q] \mid R] \quad \rightarrow \quad m[E; D; P \mid Q \mid R] \quad (\text{Open})$

Joinbients [Anonymous]

Ambient Calculus + Join Calculus =

??? $n[D; P]$

(Join)

$n[D; \text{in } m. P \mid Q] \mid m[E; R] \rightarrow m[E; n[D; P \mid Q] \mid R]$

(In)

$m[E; n[D; \text{out } m. P \mid Q] \mid R] \rightarrow n[D; P \mid Q] \mid m[E; R]$

(Out)

$m[E; \text{open } n. P \mid n[D; Q]] \rightarrow m[E; D; P \mid Q]$

(Open)

BioAmbients [Shapiro, Cardelli, et. al.]

Nameless membranes

$[in\ n.\ P\ Q] \mid [\underline{in}\ n.\ R\ S]$	\rightarrow	$[[P\ Q] \mid R\ S]$	(In)
$[[out\ n.\ P\ Q] \mid \underline{out}\ n.\ R\ S]$	\rightarrow	$[P\ Q] \mid [R\ S]$	(Out)
$[merge\ n.\ P\ Q] \mid [\underline{merge}\ n.\ R\ S]$	\rightarrow	$[P\ Q\ R\ S]$	(Merge)
...			(Comm)

Daring Classification

	Will work fine on a: LAN (bounded-delay, integrated management, uniform access)	Will work fine on a: WAN (unbounded-delay, federated management, restricted access)
F- (fixed processes and locations)	<p><u>Calculi</u> (synch/asynch-)π, d-π</p> <p><u>Infrastructure</u> DOOP</p> <p><u>Apps</u> File Servers</p>	<p><u>Calculi</u> π-i, join</p> <p><u>Infrastructure</u> SOAP, B2C, B2B, P2P</p> <p><u>Apps</u> Email, Web, Kazaa</p>
M- (mobile processes or locations)	<p><u>Calculi</u> d-join</p> <p><u>Soft Infrastructure</u> AGLETS</p> <p><u>Soft Apps</u> Trusted Applets</p> <p><u>Hard Infrastructure</u> Wireless Ethernet</p> <p><u>Hard Apps</u> Work during meetings</p>	<p><u>Calculi</u> ambients, ..., seals</p> <p><u>Soft Infrastructure</u> Mobile Threads</p> <p><u>Soft Apps</u> Worms, Agents?</p> <p><u>Hard Infrastructure</u> Wireless Telephony</p> <p><u>Hard Apps</u> Mobile B2C, B2B</p>

Conclusions

Studied many encodings, type systems, and equivalences.

- Often building on π -calculus technology.

“Strong mobility” is still a dream, in practice.

- Although many interesting techniques have been proposed, typically in Java.

Ambients suggest new security models.

- Location-based; perhaps more intuitive.
- Analysis of security boundaries.
- But new security issues are also raised.

Ambients are “more” than π .

- Still don’t know how to encode ambients in π (vice versa is easy).
- For a generalization of both Ambients and π , see Milner’s BiGraphs.