

# Artificial Biochemistry

Luca Cardelli

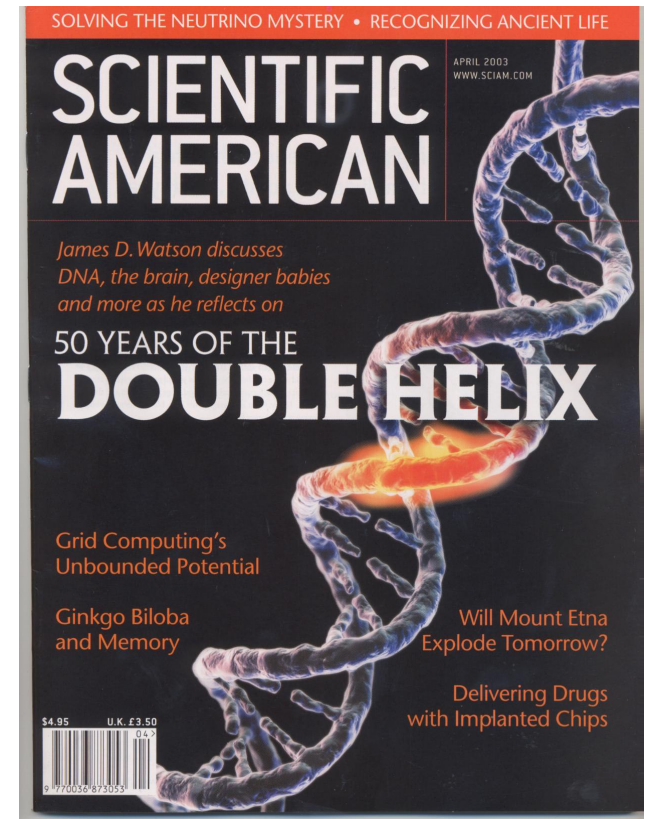
Microsoft Research

Sophia Antipolis 2007-05-10

<http://LucaCardelli.name>

# 50 Years of Molecular Cell Biology

- The genome (3.2 GBases) is made of DNA
  - Stores digital information as sequences of 4 different nucleotides
  - Directs protein assembly through RNA and the Genetic Code
- Proteins (1M coded from 25K genes) are made of amino acids
  - Catalyze all biochemical reactions
  - Control metabolism (energy & materials)
  - Process signals, activate genes
- Bootstrapping still a mystery
  - DNA, RNA, proteins, membranes are today interdependent. Not clear who came first
  - Not understood, not essential for us



# Cells Compute

- Understanding how cells compute
  - How do signaling networks work?
  - Much is understood, and much is not.
- An unusual computational paradigm
  - By protein interactions (mostly)
  - Is it related to:
    - Electronic circuits?
    - Automata?
    - Process Algebra?
- Why study signaling networks?
  - It's "just chemistry", we should be able to cope with it.
    - Simpler than gene networks, neural networks, ants, and bees!
  - Yet non-trivial; general principles and algorithms may apply.

Ultrasensitivity in the mitogen-activated protein cascade, Chi-Ying F. Huang and James E. Ferrell, Jr., 1996, *Proc. Natl. Acad. Sci. USA*, 93, 10078-10083.

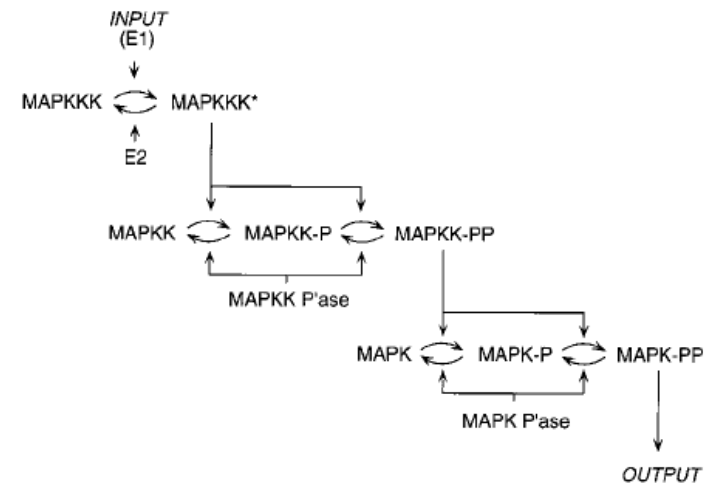


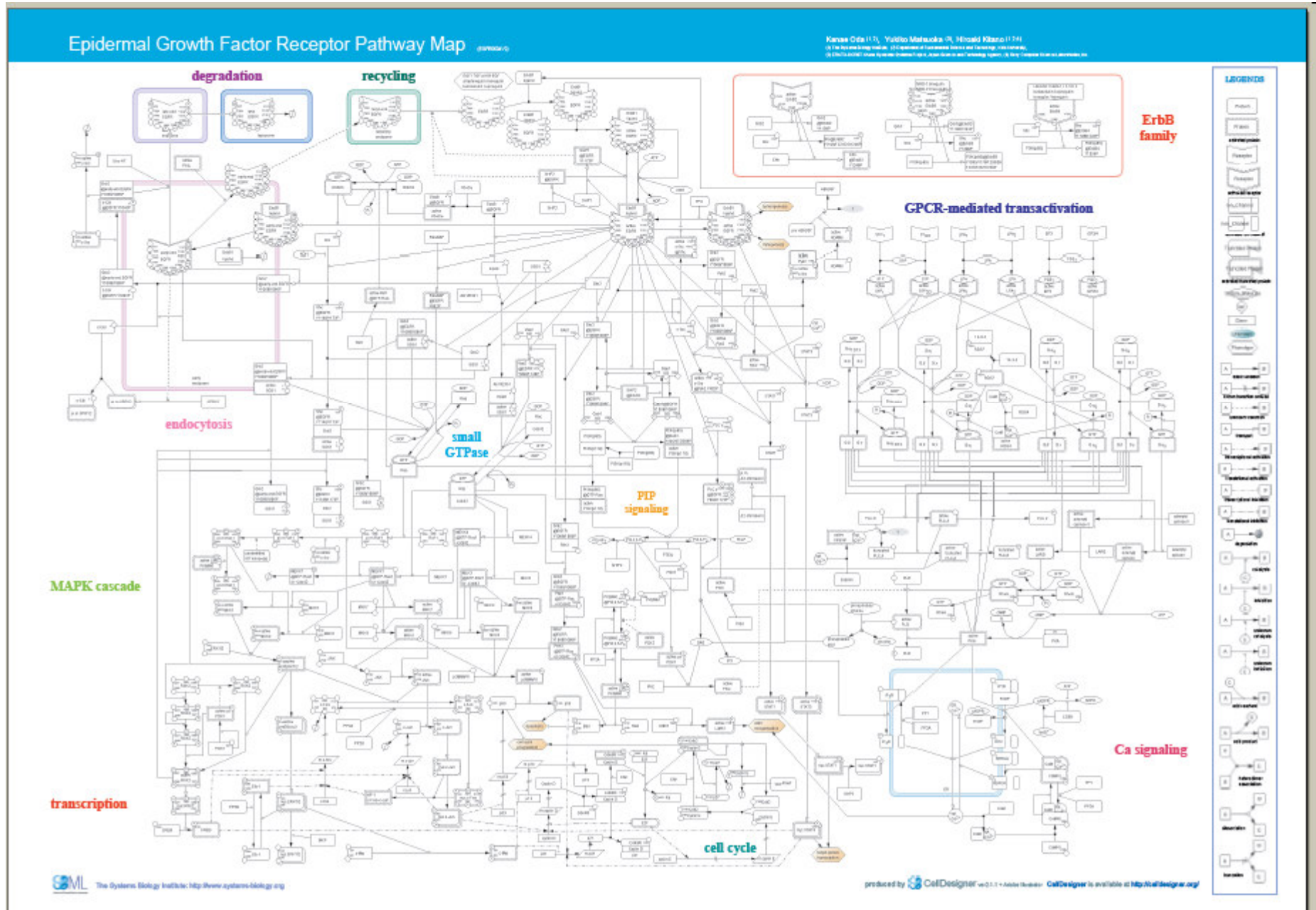
FIG. 1. Schematic view of the MAPK cascade. Activation of MAPK depends upon the phosphorylation of two conserved sites [Thr-183 and Tyr-185 in rat p42 MAPK/Erk2 (4, 5)]. Full activation of MAPKK also requires phosphorylation of two sites [Ser-218 and Ser-222 in mouse Mek-1/MKK1 (6-10)]. Detailed mechanisms for the activation of various MAPKKs (e.g., Raf-1, B-Raf, Mos) are not yet established; here we assume that MAPKKs are activated and inactivated by enzymes we denote E1 and E2. MAPKK\* denotes activated MAPKK. MAPKK-P and MAPKK-PP denote singly and doubly phosphorylated MAPKK, respectively. MAPK-P and MAPK-PP denote singly and doubly phosphorylated MAPK. P'ase denotes phosphatase.

# Stochastic Collectives

# Stochastic Collectives

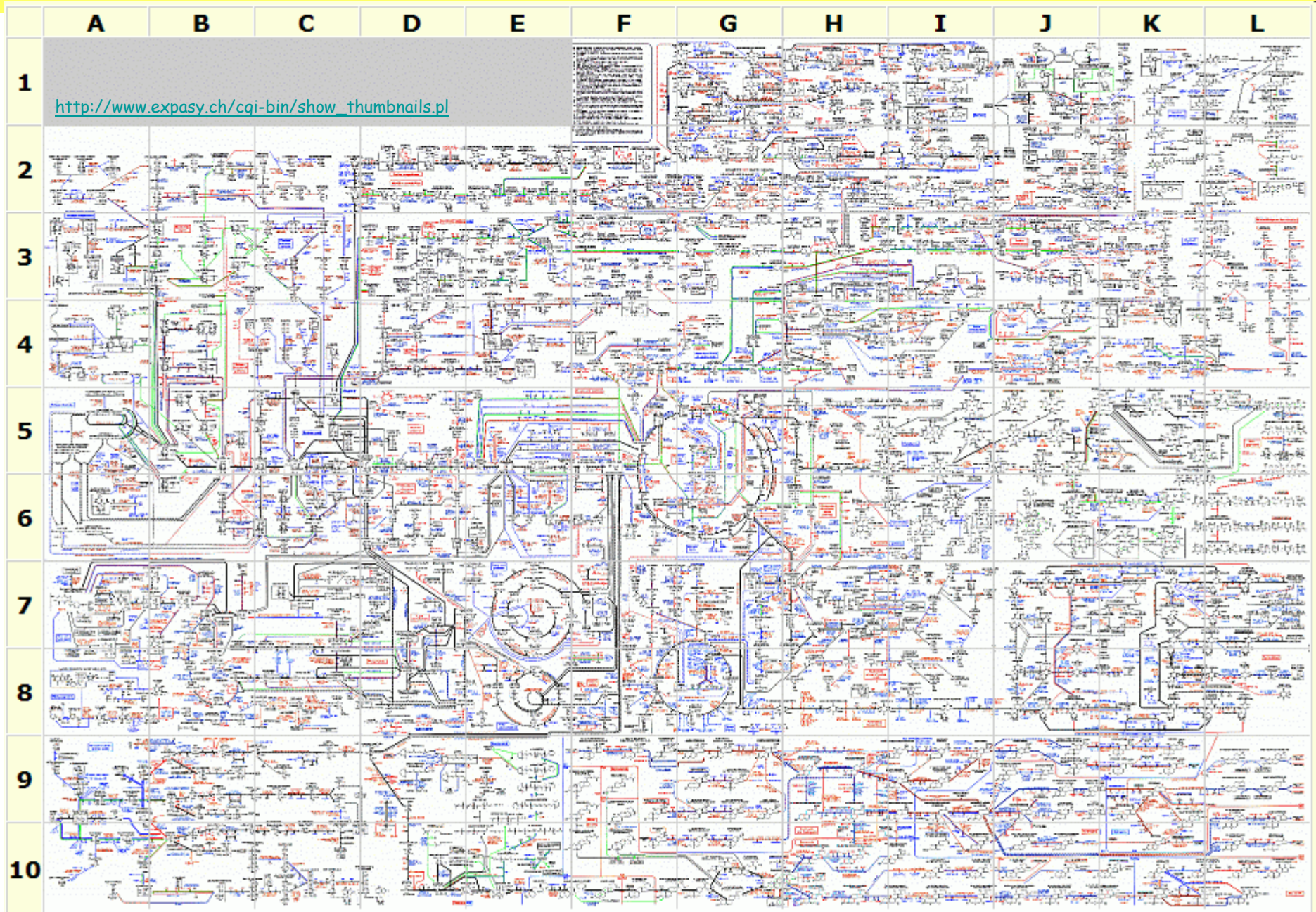
- "Collective":
  - A large set of interacting finite state automata:
    - Not quite language automata ("large set")
    - Not quite cellular automata ("interacting" but not on a grid)
    - Not quite process algebra ("collective behavior")
    - Cf. multi-agent systems and swarm intelligence
- "Stochastic":
  - Interactions have *rates*
    - Not quite discrete (hundreds or thousands of components)
    - Not quite continuous (non-trivial stochastic effects)
    - Not quite hybrid (no "switching" between regimes)
- Very much like biochemistry
  - Which is a large set of stochastically interacting molecules/proteins
  - Are proteins **finite state** and subject to automata-like **transitions**?
    - Let's say they are, at least because:
    - Much of the knowledge being accumulated in Systems Biology is described as state transition diagrams [Kitano].

# State Transitions

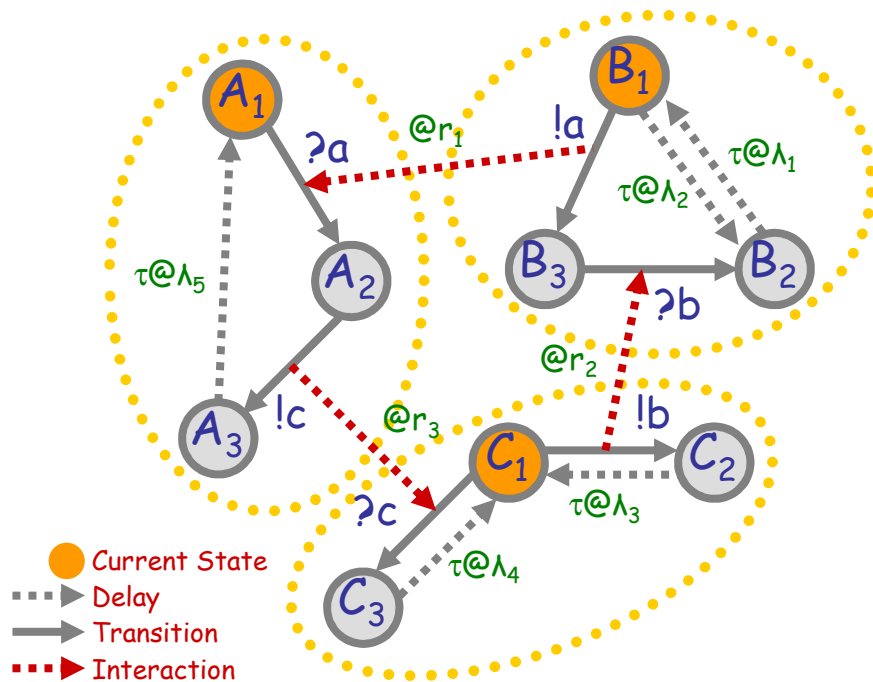




# Compositionality (NOT!)



# Interacting Automata

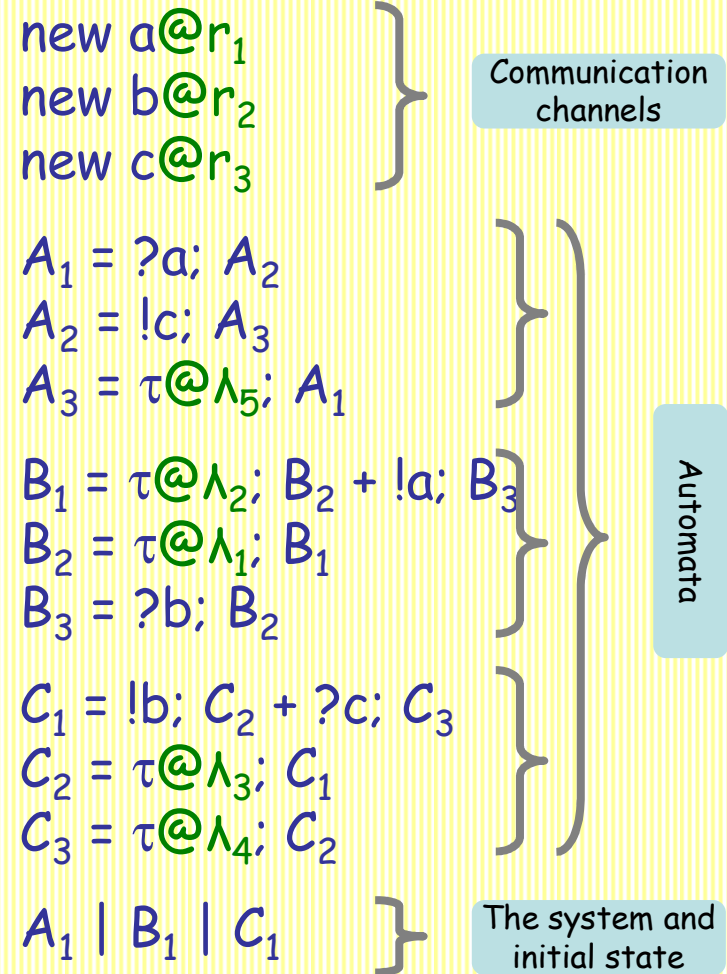


**Communicating automata:** a graphical FSA-like notation for "finite state restriction-free  $\pi$ -calculus processes". **Interacting automata** do not even exchange values on communication.

The stochastic version has *rates* on communications, and delays.

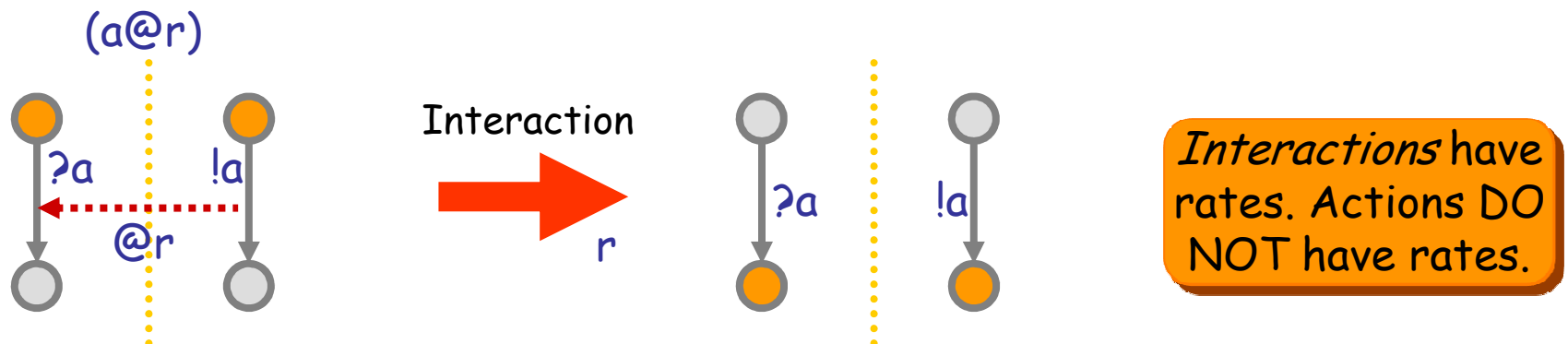
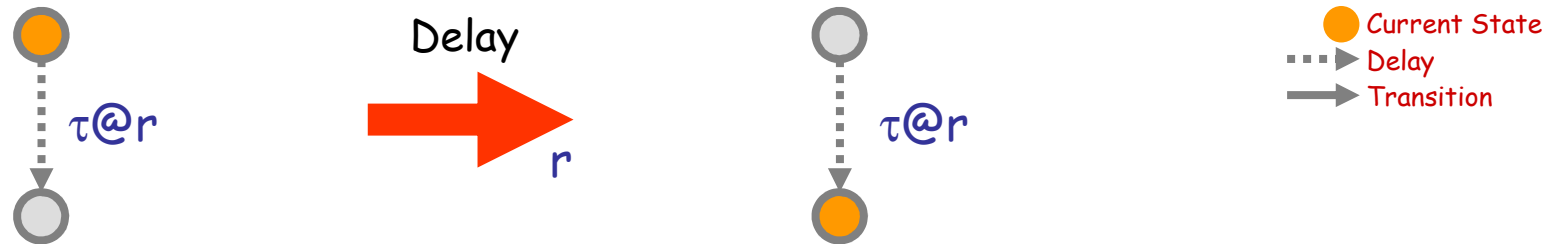
"Finite state" means: no composition or restriction inside recursion.

Analyzable by standard Markovian techniques, by first computing the "product automaton" to obtain the underlying finite Markov transition system. [Buchholz]





# Interacting Automata Transition Rules

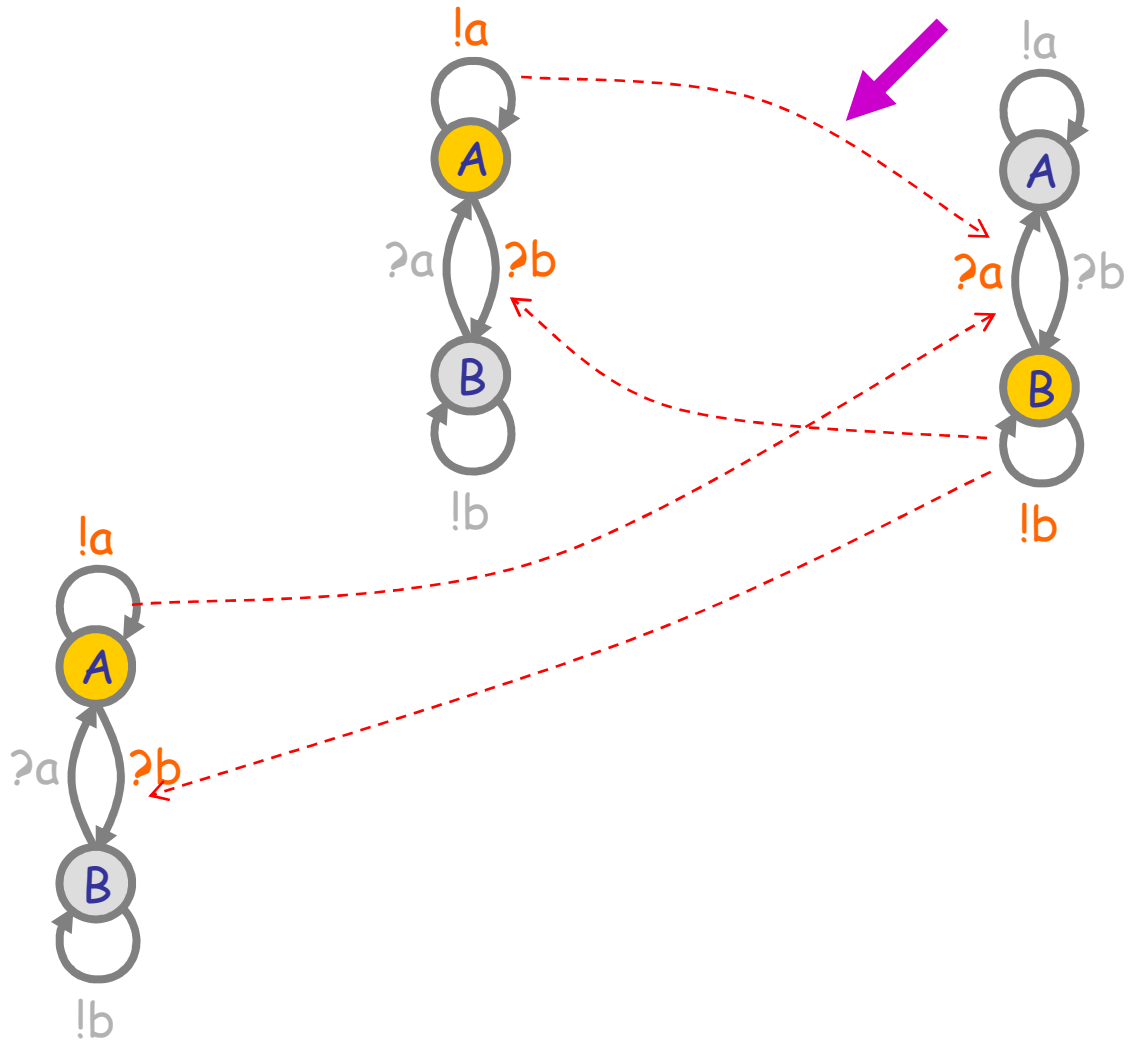


**Q: What kind of mass behavior can this produce?**

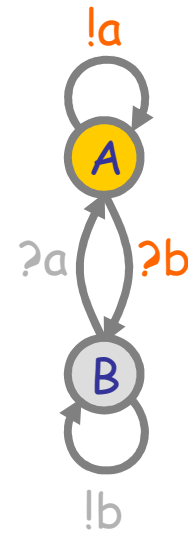
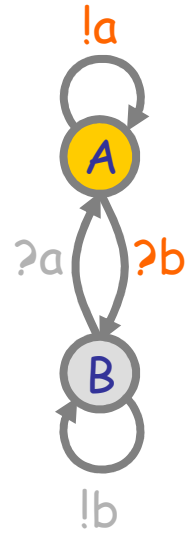
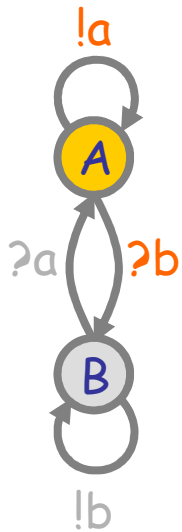
(We need to understand that if we want to understand biochemical systems.)



# Interactions in a Population



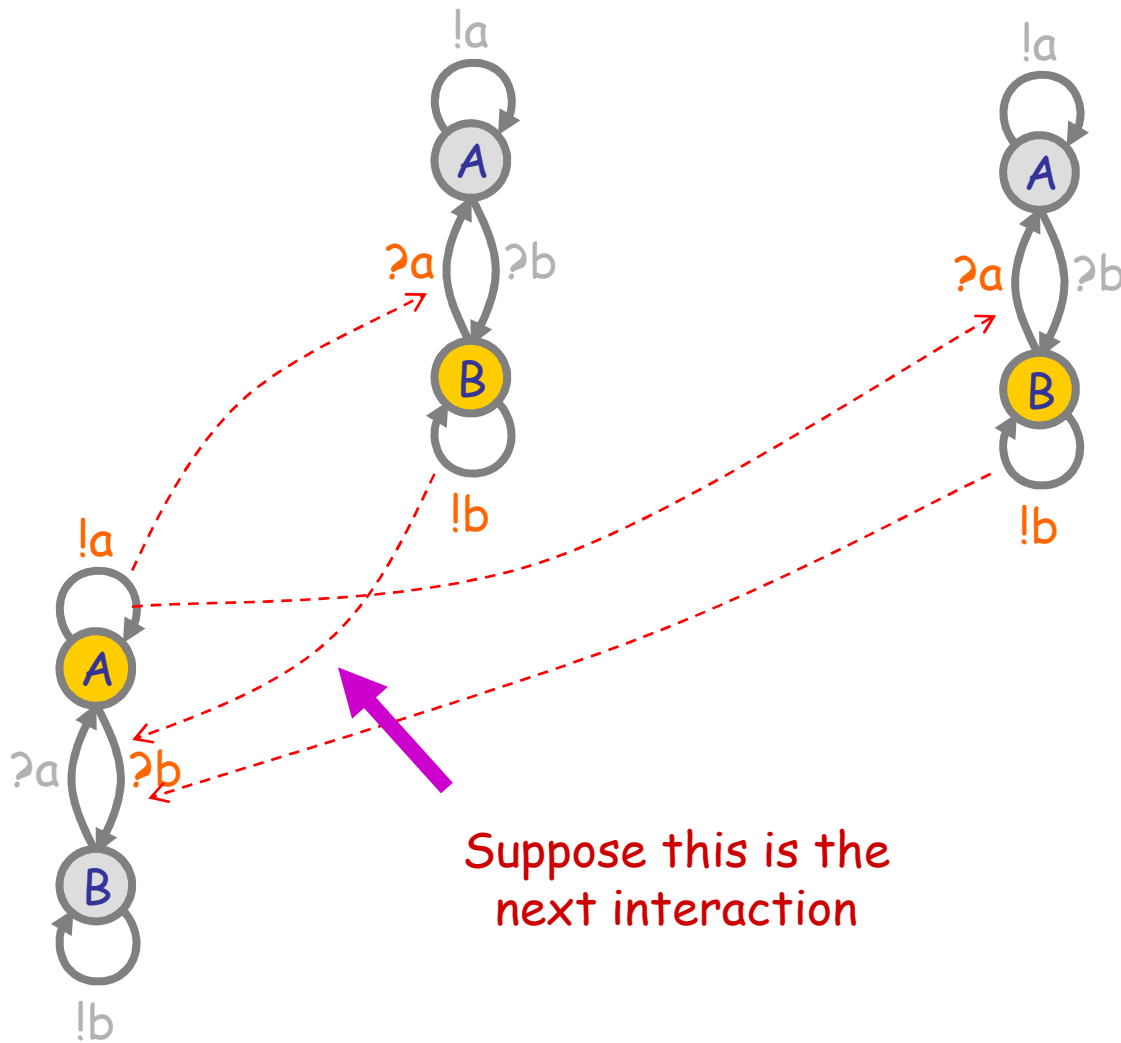
# Interactions in a Population



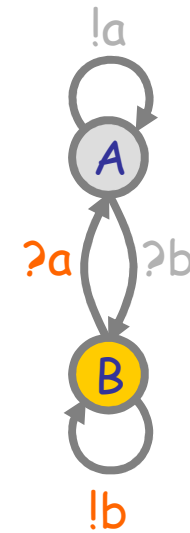
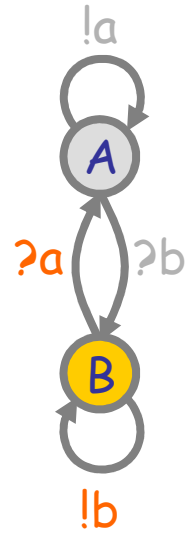
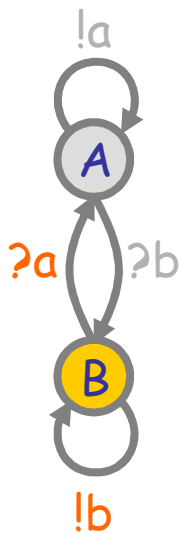
All-A stable population



# Interactions in a Population (2)



# Interactions in a Population (2)

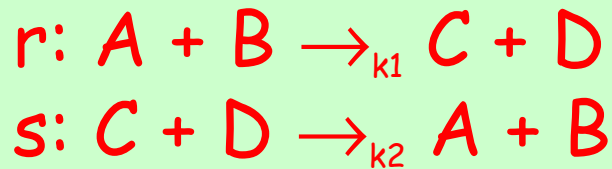


All-B stable population

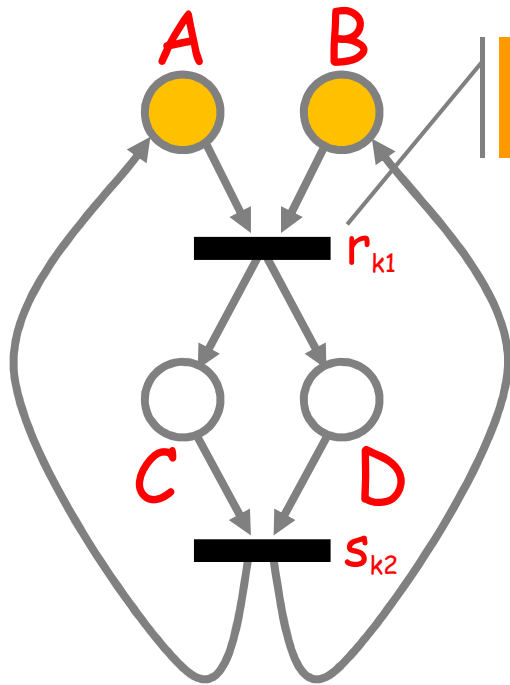
Nondeterministic population behavior ("multistability")

# Chemistry vs. Automata

A process calculus (chemistry)



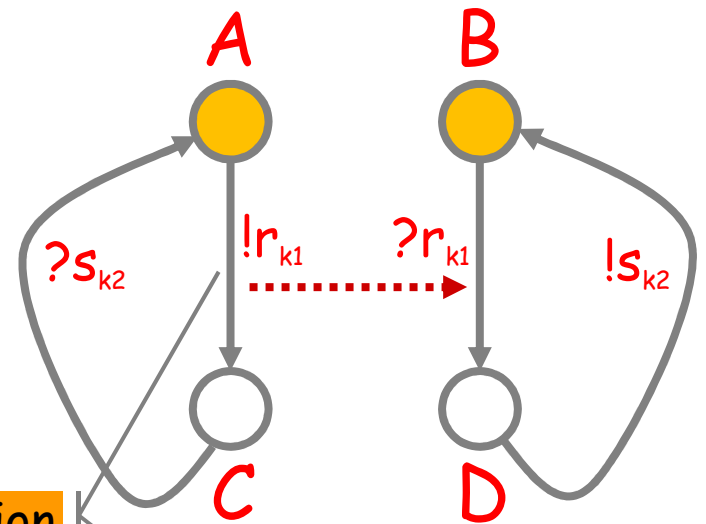
Does A become C or D?



Reaction oriented

1 line per reaction

A different process calculus (automata)



Interaction oriented

1 line per component

$$A = !r_{k1}; C$$

$$C = ?s_{k2}; A$$

$$B = ?r_{k1}; D$$

$$D = !s_{k2}; B$$

A becomes C not D!

The same "model"

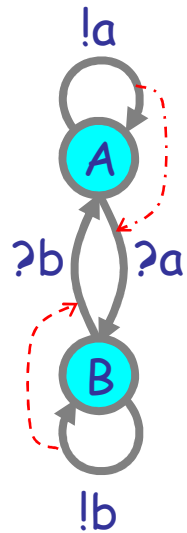
Maps to a CTMC

Maps to a CTMC

A Petri-Net-like representation. Precise and dynamic, but not modular, scalable, or maintainable.

A compositional graphical representation (precise, dynamic *and* modular) and the corresponding calculus.

# Groupies and Celebrities



## Celebrity

(does not want to be like somebody else)

```
directive sample 0.1 200
directive plot A(); B()
```

```
new a@1.0:chan()
new b@1.0:chan()
```

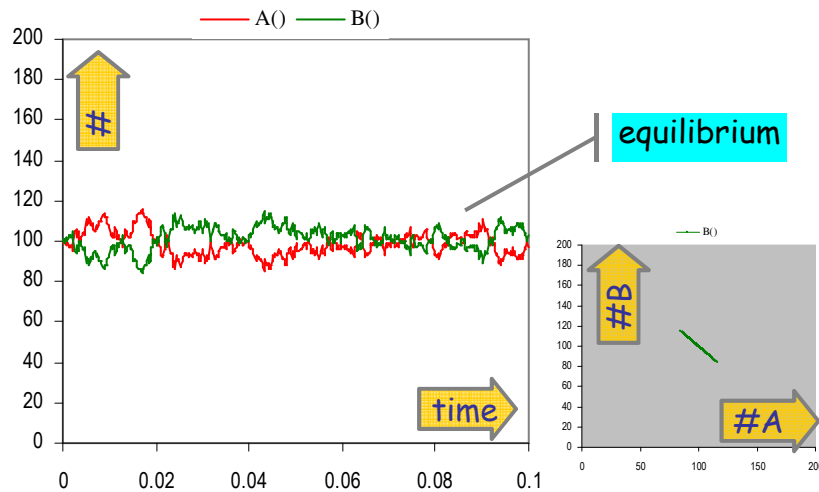
```
let A() = do !a; A() or ?a; B()
and B() = do !b; B() or ?b; A()
```

```
run 100 of (A() | B())
```

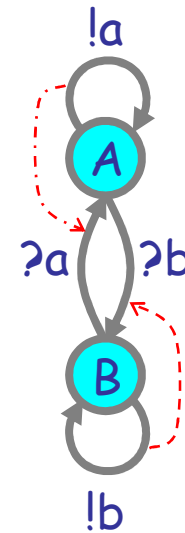
a@1.0

b@1.0

A stochastic collective of celebrities:



Stable because as soon as a A finds itself in the majority, it is more likely to find somebody in the same state, and hence change, so the majority is weakened.



## Groupie

(wants to be like somebody different)

```
directive sample 0.1 200
directive plot A(); B()
```

```
new a@1.0:chan()
new b@1.0:chan()
```

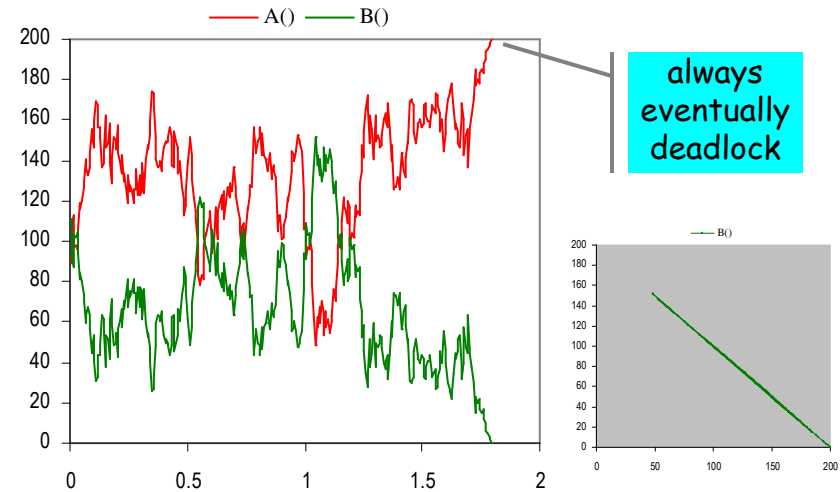
```
let A() = do !a; A() or ?b; B()
and B() = do !b; B() or ?a; A()
```

```
run 100 of (A() | B())
```

a@1.0

b@1.0

A stochastic collective of groupies:

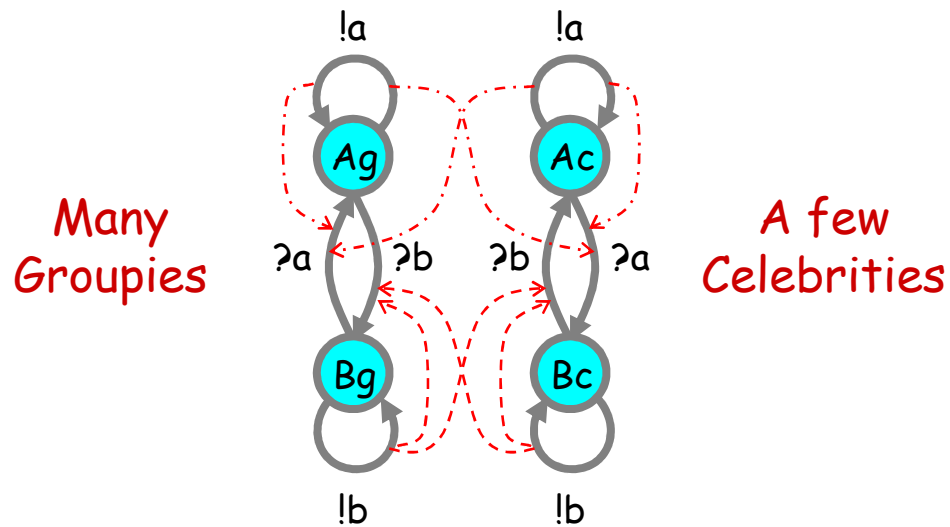


Unstable because within an A majority, an A has difficulty finding a B to emulate, but the few B's have plenty of A's to emulate, so the majority may switch to B. Leads to deadlock when everybody is in the same state and there is nobody different to emulate.



# Both Together

A way to break the deadlocks: Groupies with just a few Celebrities



```
directive sample 10.0
directive plot Ag(); Bg(); Ac(); Bc()

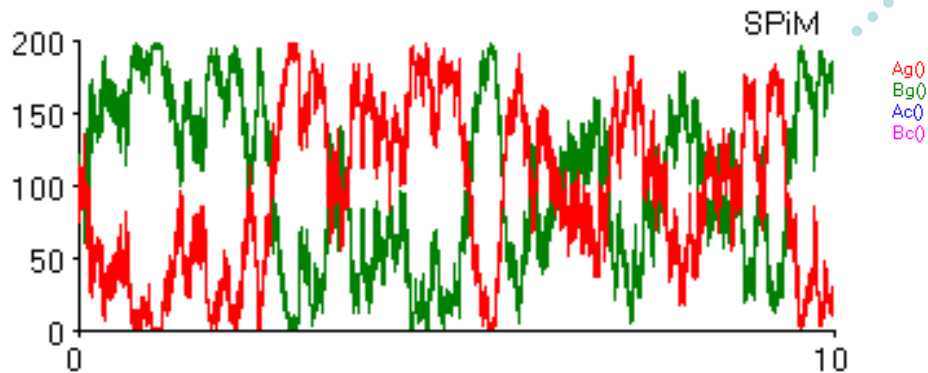
new a@1.0:chan()
new b@1.0:chan()

let Ac() = do !a; Ac() or ?a; Bc()
and Bc() = do !b; Bc() or ?b; Ac()

let Ag() = do !a; Ag() or ?b; Bg()
and Bg() = do !b; Bg() or ?a; Ag()

run 1 of Ac()
run 100 of (Ag() | Bg())
```

never  
deadlock

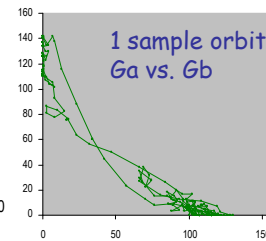
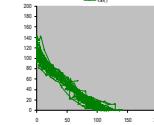
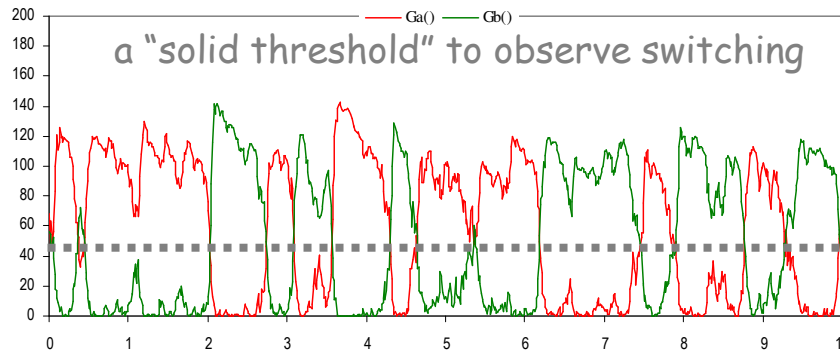
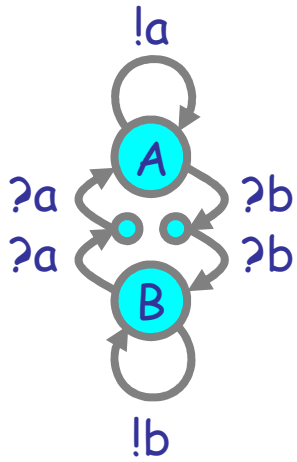


A tiny bit of  
"noise" can make a  
huge difference

Regularity can arise not far from chaos

# Hysteric Groupies

We can get more regular behavior from groupies if they "need more convincing", or "hysteresis" (history-dependence), to switch states.



```
directive sample 10.0 1000
directive plot Ga(); Gb()

new a@1.0:chan()
new b@1.0:chan()

let Ga() = do !a; Ga() or ?b; ?b; Gb()
and Gb() = do !b; Gb() or ?a; ?a; Ga()

let Da() = !a; Da()
and Db() = !b; Db()

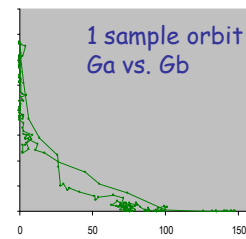
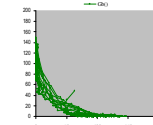
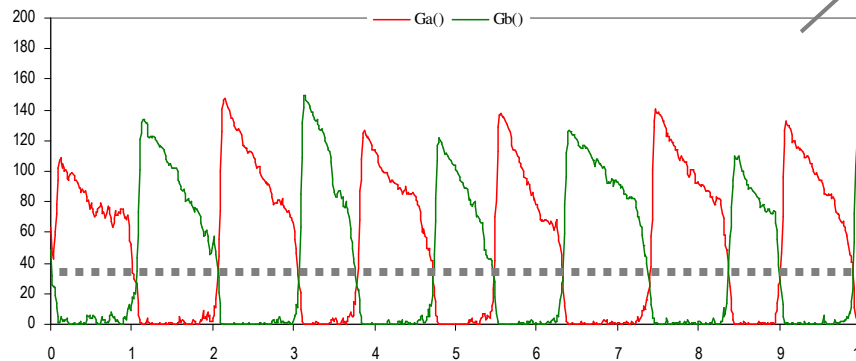
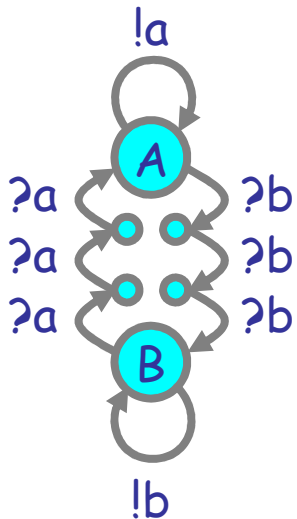
run 100 of (Ga() | Gb())
run 1 of (Da() | Db())
```



(With doping to break deadlocks)

N.B.: It will not oscillate without doping (noise)

"regular" oscillation



```
directive sample 10.0 1000
directive plot Ga(); Gb()

new a@1.0:chan()
new b@1.0:chan()

let Ga() = do !a; Ga() or ?b; ?b; ?b; Gb()
and Gb() = do !b; Gb() or ?a; ?a; ?a; Ga()

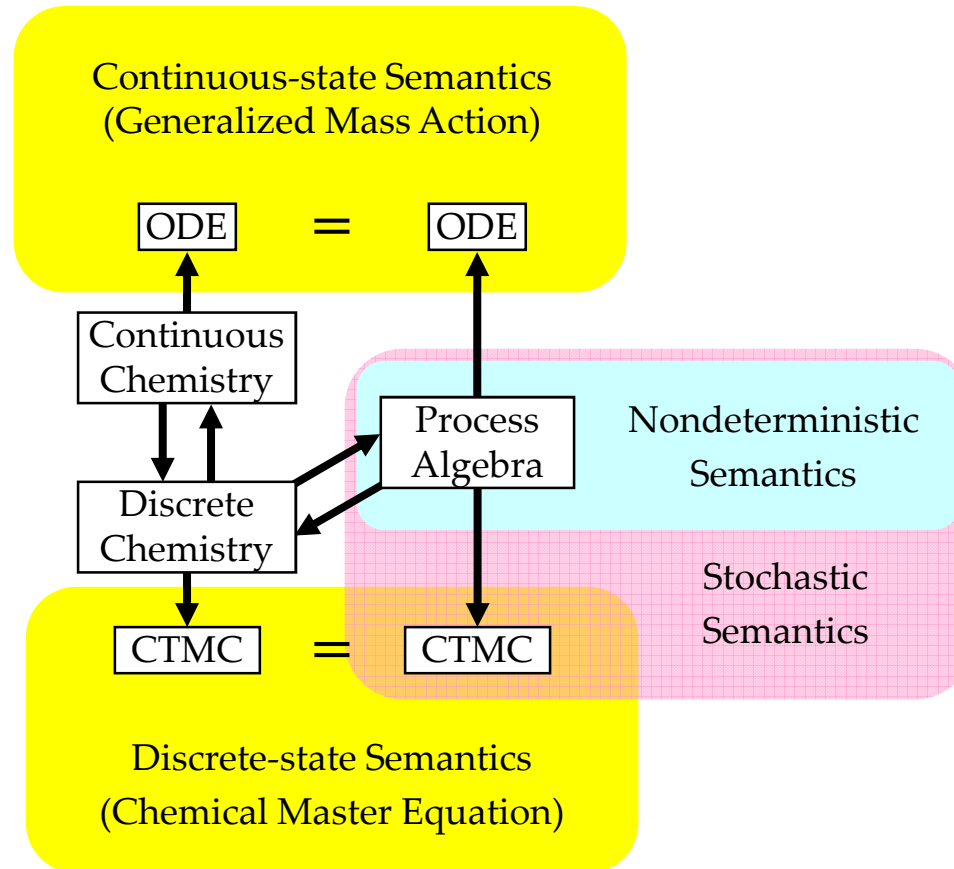
let Da() = !a; Da()
and Db() = !b; Db()

run 100 of (Ga() | Gb())
run 1 of (Da() | Db())
```



# Semantics of Collective Behavior

# The Two Semantic Faces of Chemistry



These diagrams commute via appropriate maps.

L. Cardelli: "On Process Rate Semantics"



# From Processes to Chemistry

# Chemical Ground Form (CGF)

$E ::= X_1=M_1, \dots, X_n=M_n$

Reagents ( $n \geq 0$ )

$M ::= \pi_1;P_1 \oplus \dots \oplus \pi_n;P_n$

Molecules ( $n \geq 0$ )

$P ::= X_1 \mid \dots \mid X_n$

Solutions ( $n \geq 0$ )

$\pi ::= \tau_r \ ?n_{(r)} \ !n_{(r)}$

Interactions (delay, input, output)

$CGF ::= E, P$

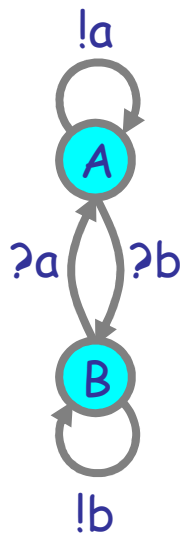
Reagents plus Initial Conditions

CGF =  
Interacting Automata  
+ dynamic forking

Simplest process  
algebra *ever*

(To translate chemistry to processes we need a bit more than interacting automata: we may have "+" on the right of  $\rightarrow$ , that is we may need "|" after  $\pi$ .)

$\oplus$  is stochastic choice (vs. + for chemical reactions)  
0 is the null solution ( $P \mid 0 = 0 \mid P = P$ )  
and null molecule ( $M \oplus 0 = 0 \oplus M = M$ ) ( $\tau_0;P = 0$ )  
 $X_i$  are distinct in  $E$   
Each name  $n$  is assigned a fixed rate  $r$ :  $n_{(r)}$



Ex: interacting automata  
(which are finite-control CGFs: use "|" only in initial conditions):

$A = !a;A \oplus ?b;B$

$B = !b;B \oplus ?a;A$

$A \mid A \mid B \mid B$


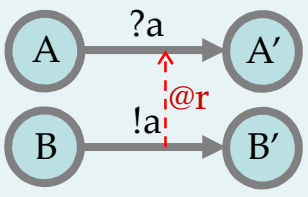
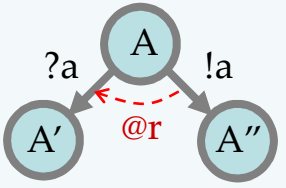
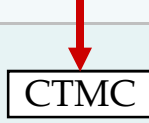
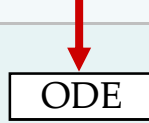
Automaton in state A

Automaton in state B

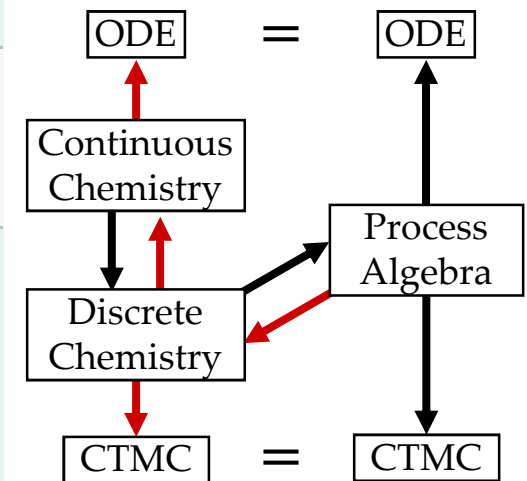
Initial  
conditions:  
2A and 2B

# Processes to Chemistry

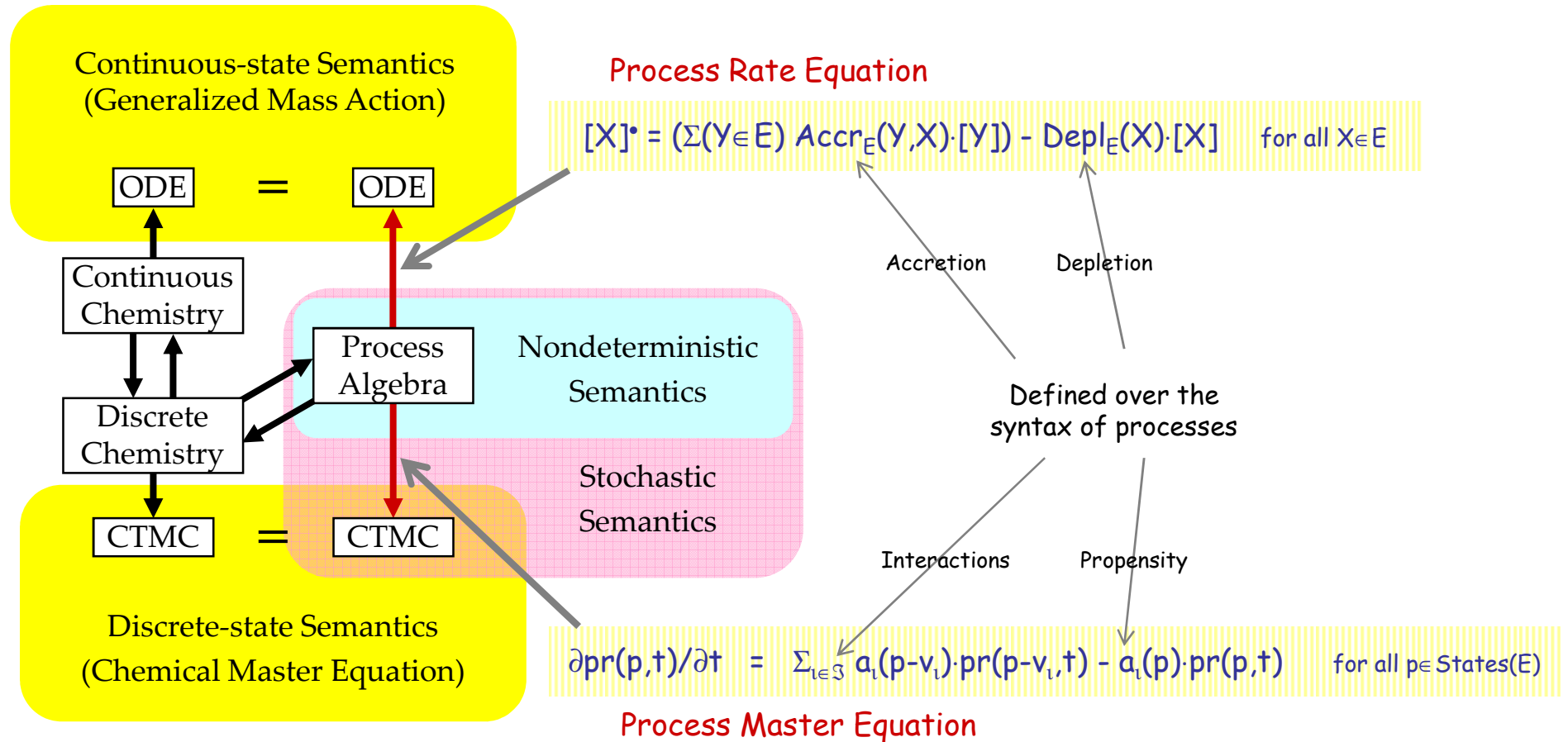
$V$  = interaction volume  
 $N_A$  = Avogadro's number

Automata	Discrete Chemistry	Continuous Chemistry
$\gamma = N_A V$		
initial states $A \mid A \mid \dots \mid A$	initial quantities $\#A_0$	initial concentrations $[A]_0$ with $[A]_0 = \#A_0/\gamma$
	$A \xrightarrow{r} A'$	$A \xrightarrow{k} A'$ with $k = r$
	$A+B \xrightarrow{r} A'+B'$	$A+B \xrightarrow{k} A'+B'$ with $k = r\gamma$
	$A+A \xrightarrow{2r} A'+A''$	$A+A \xrightarrow{2k} A'+A''$ with $k = r\gamma/2$
		

Think  $\gamma = 1$   
 i.e.  $V = 1/N_A$



# Quantitative Process Semantics



# Processes to GMA Directly

## Process Rate Equation for Reagents E

$$[X]^{\bullet} = (\sum_{Y \in E} \text{Accr}_E(Y, X) \cdot [Y]) - \text{Depl}_E(X) \cdot [X] \quad \text{for all } X \in E$$

$$\text{Depl}_E(X) =$$

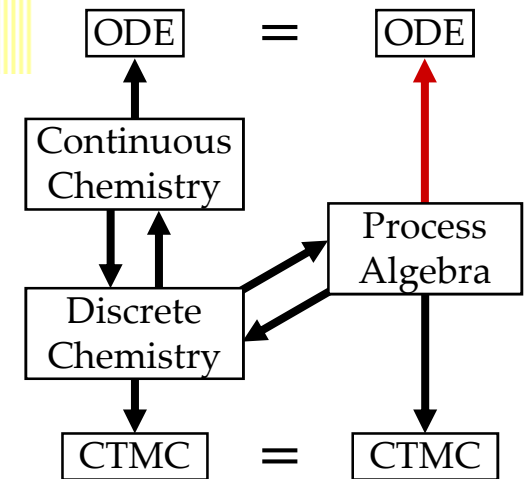
$$\begin{aligned} & \sum_{(i: E.X.i = \tau_{(r)}; P)} r + \\ & \sum_{(i: E.X.i = ?a_{(r)}; P)} r\gamma \cdot \text{OutsOn}_E(a) + \\ & \sum_{(i: E.X.i = !a_{(r)}; P)} r\gamma \cdot \text{InsOn}_E(a) \end{aligned}$$

$$\text{Accr}_E(Y, X) =$$

$$\begin{aligned} & \sum_{(i: E.Y.i = \tau_{(r)}; P)} \#X(P) \cdot r + \\ & \sum_{(i: E.Y.i = ?a_{(r)}; P)} \#X(P) \cdot r\gamma \cdot \text{OutsOn}_E(a) + \\ & \sum_{(i: E.Y.i = !a_{(r)}; P)} \#X(P) \cdot r\gamma \cdot \text{InsOn}_E(a) \end{aligned}$$

$$\text{InsOn}_E(a) = \sum_{(Y \in E)} \#\{Y.i \mid E.Y.i = ?a_{(r)}; P\} \cdot [Y]$$

$$\text{OutsOn}_E(a) = \sum_{(Y \in E)} \#\{Y.i \mid E.Y.i = !a_{(r)}; P\} \cdot [Y]$$



$$X = \tau_{(r)}; 0 \quad \rightarrow \quad [X]^{\bullet} = -r[X]$$

$$X = ?a_{(r)}; 0 \quad \rightarrow \quad [X]^{\bullet} = -r\gamma[X][Y]$$

$$Y = !a_{(r)}; 0 \quad \rightarrow \quad [Y]^{\bullet} = -r\gamma[X][Y]$$

$$\begin{aligned} X = ?a_{(r)}; 0 & \rightarrow [X]^{\bullet} = -2r\gamma[X]^2 \\ & \oplus !a_{(r)}; 0 \end{aligned}$$

# Processes to CME Directly

## Process Master Equation for Reagents E

$$\frac{\partial \text{pr}(p,t)}{\partial t} = \sum_{\iota \in \mathcal{S}} a_{\iota}(p-v_{\iota}) \cdot \text{pr}(p-v_{\iota},t) - a_{\iota}(p) \cdot \text{pr}(p,t) \quad \text{for all } p \in \text{States}(E)$$

$\text{pr}(p,t) = \Pr\{\mathbf{S}(t)=p \mid \mathbf{S}(0)=p_0\}$  is the conditional probability of the system being in state  $p$  (a multiset of molecules) at time  $t$  given that it was in state  $p_0$  at time 0.

$\mathcal{S} = \{\{X.i\} \text{ s.t. } E.X.i = \tau_{(r)};Q\} \cup \{\{X.i, Y.j\} \text{ s.t. } E.X.i = ?n_{(r)};Q \text{ and } E.Y.j = !n_{(r)};R\}$  is the set of possible interactions in E

$v_{\iota}$  is the *state change* caused by an interaction  $\iota \in \mathcal{S}$ .

$$v_{\iota} = -X+Q \quad \text{if } \iota = \{X.i\} \text{ s.t. } E.X.i = \tau_{(r)};Q$$

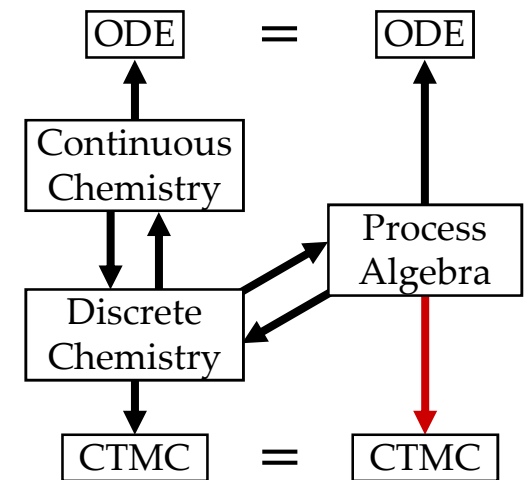
$$v_{\iota} = -X-Y+Q_R \quad \text{if } \iota = \{X.i, Y.j\} \text{ s.t. } E.X.i = ?n_{(r)};Q \text{ and } E.Y.j = !n_{(r)};R$$

$a_{\iota}$  is the *propensity* of interaction  $\iota$  in state  $p$ . Here  $p^{\#X}$  is the number of  $X$  in  $p$ .

$$a_{\iota}(p) = r \cdot p^{\#X} \quad \text{if } \iota = \{X.i\} \text{ s.t. } E.X.i = \tau_{(r)};Q$$

$$a_{\iota}(p) = r \cdot p^{\#X} \cdot p^{\#Y} \quad \text{if } \iota = \{X.i, Y.j\} \text{ s.t. } X \neq Y \text{ and } E.X.i = ?a_{(r)};Q \text{ and } E.Y.j = !a_{(r)};R$$

$$a_{\iota}(p) = r \cdot p^{\#X} \cdot (p^{\#X}-1) \quad \text{if } \iota = \{X.i, X.j\} \text{ s.t. } E.X.i = ?a_{(r)};Q \text{ and } E.X.j = !a_{(r)};R$$



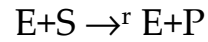
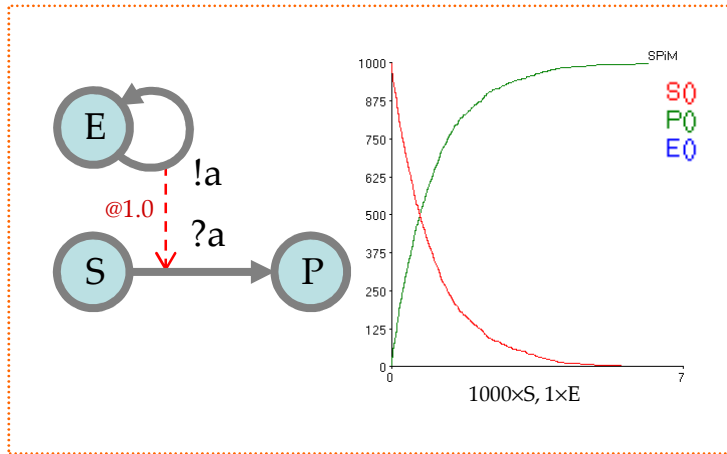
# Examples of stochastic collectives where:

- (1) Simulation is puzzling and ODE analysis is more useful.
- (2) ODE analysis is puzzling and simulation is more useful.



# Zero-Order Regime

# Second-order and Zero-order Regime



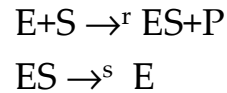
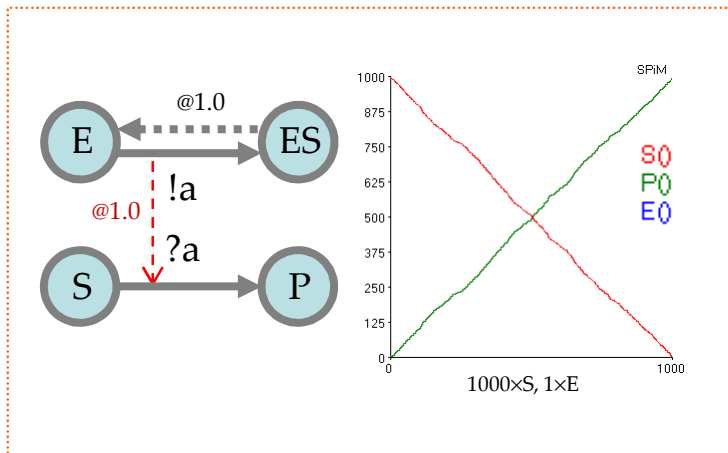
```
directive sample 1000.0
directive plot S(); P(); E()
```

```
new a@1.0:chan()
```

```
let E() = !a; E()
and S() = ?a; P()
and P() = ()
```

```
run (1 of E() | 1000 of S())
```

Second-Order Regime  
 $[S]^* = -r[E][S]$



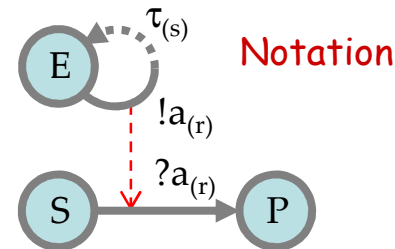
```
directive sample 1000.0
directive plot S(); P(); E()
```

```
new a@1.0:chan()
```

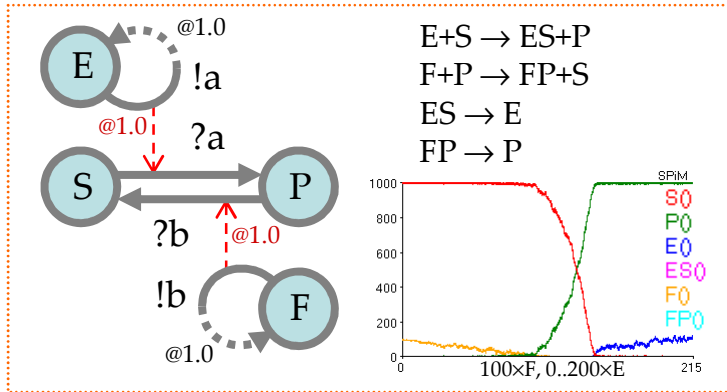
```
let E() = !a; delay@1.0; E()
and S() = ?a; P()
and P() = ()
```

```
run (1 of E() | 1000 of S())
```

Zero-Order Regime  
 $[S]^* \cong -1$  (by assuming  $[ES]^* = 0$ )



# Ultrasensitivity



```

directive sample 215.0
directive plot S(): P(): E(): ES(): F(): FP()

new a@1.0:chan() new b@1.0:chan()

let S() = ?a: P()
and P() = ?b: S()

let E() = !a: delay@1.0: E()
and F() = !b: delay@1.0: F()

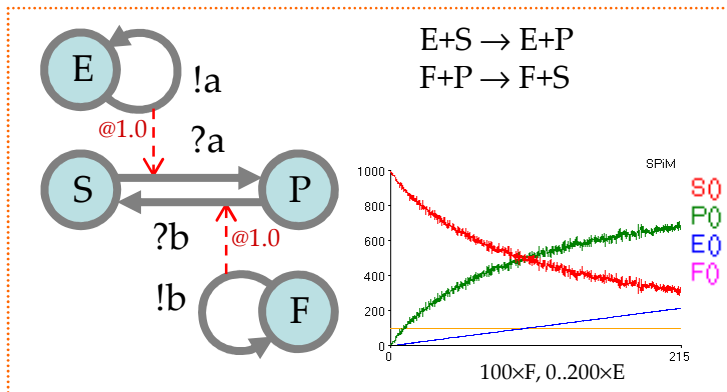
run 1000 of S()

let clock(t:float, tick:chan) = (* sends a tick every t time *)
(val ti = 1/100.0 val d = 1.0/ti (* by 100-step erlang timers *))
let step(n:int) = if n<=0 then !tick: clock(t,tick) else delay@d: step(n-1)
run step(100)

let Sig(p:proc(), tick:chan) = (p() | ?tick: Sig(p,tick))
let raising(p:proc(), t:float) =
(new tick:chan run (clock(t,tick) | Sig(p,tick)))

run 100 of F()
run raising(E,1.0)
    
```

Zero-Order Regime  
A small E-F imbalance causes a much larger S-P switch.



```

directive sample 215.0 1000
directive plot S(): P(): E(): F()

new a@1.0:chan() new b@1.0:chan()

let S() = ?a: P()
and P() = ?b: S()

let E() = !a: E()
and F() = !b: F()

run 1000 of S()

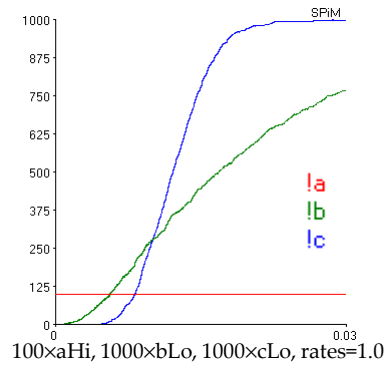
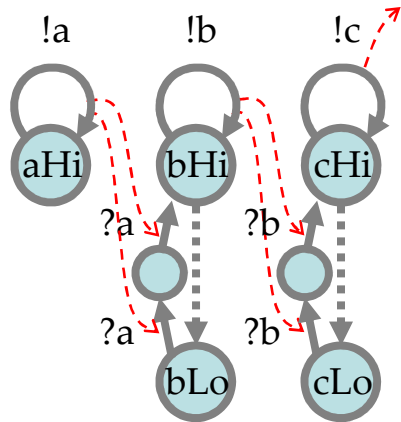
let clock(t:float, tick:chan) = (* sends a tick every t time *)
(val ti = 1/100.0 val d = 1.0/ti (* by 100-step erlang timers *))
let step(n:int) = if n<=0 then !tick: clock(t,tick) else delay@d: step(n-1)
run step(100)

let Sig(p:proc(), tick:chan) = (p() | ?tick: Sig(p,tick))
let raising(p:proc(), t:float) =
(new tick:chan run (clock(t,tick) | Sig(p,tick)))

run 100 of F()
run raising(E,1.0)
    
```

Second-Order Regime

# Cascades



Second-Order Regime cascade:  
a signal amplifier (MAPK)  
 $a_{Hi} > 0 \Rightarrow c_{Hi} = \max$

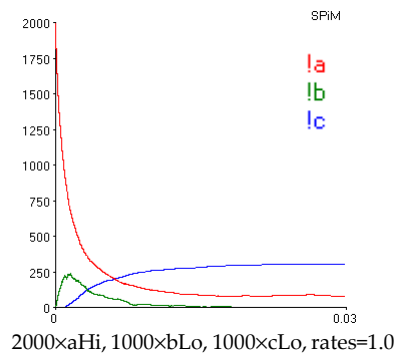
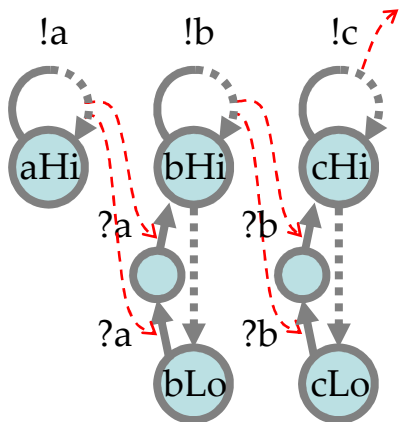
```
directive sample 0.03
directive plot !a: !b: !c

new a@1.0:chan new b@1.0:chan new c@1.0:chan

let Amp_hi(a:chan, b:chan) =
do !b: delay@1.0: Amp_hi(a,b) or delay@1.0: Amp_lo(a,b)
and Amp_lo(a:chan, b:chan) =
?a: ?a: Amp_hi(a,b)

run 1000 of (Amp_lo(a,b) | Amp_lo(b,c))

let A() = !a: A()
run 100 of A()
```



Zero-Order Regime cascade:  
a signal *divider*!  
 $a_{Hi} = \max \Rightarrow c_{Hi} = 1/3 \max$

```
directive sample 0.03
directive plot !a: !b: !c

new a@1.0:chan new b@1.0:chan new c@1.0:chan

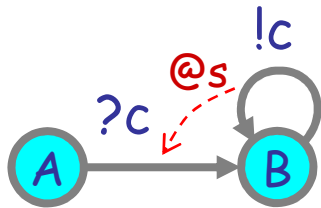
let Amp_hi(a:chan, b:chan) =
do !b: delay@1.0: Amp_hi(a,b) or delay@1.0: Amp_lo(a,b)
and Amp_lo(a:chan, b:chan) =
?a: ?a: Amp_hi(a,b)

run 1000 of (Amp_lo(a,b) | Amp_lo(b,c))

let A() = !a: delay@1.0: A()
run 2000 of A()
```

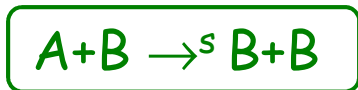
# Nonlinear Transitions

# Nonlinear Transition (NLT)



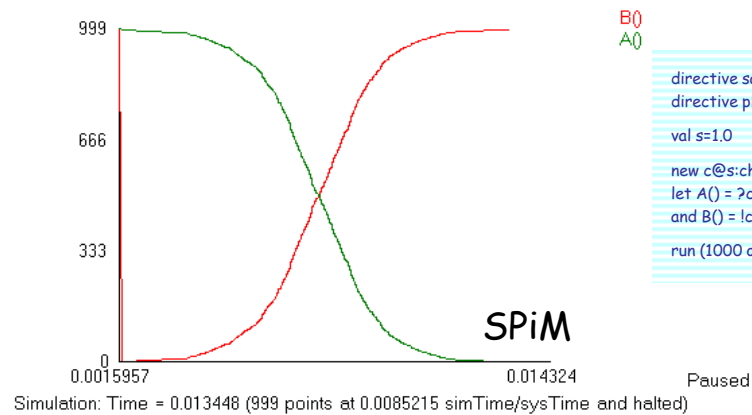
$$A = ?c_{(s)};B$$

$$B = !c_{(s)};B$$



$$[A]^{\bullet} = -s[A][B]$$

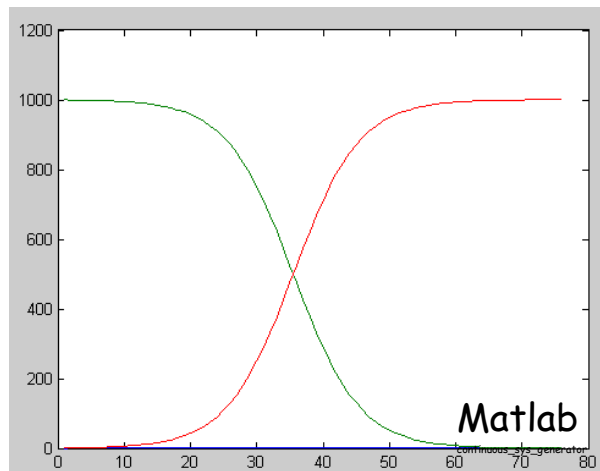
$$[B]^{\bullet} = s[A][B]$$



```

directive sample 0.02 1000
directive plot B(): A()
val s=1.0
new c@s:chan
let A() = ?c; B()
and B() = !c;B()
run (1000 of A() | 1 of B())
    
```

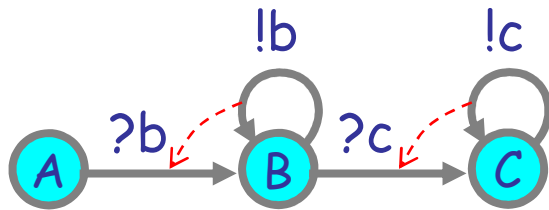
N.B.: needs at least 1 B to "get started".



```

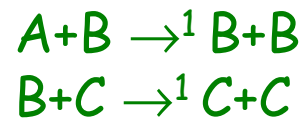
interval/step [0:0.001:0.0]
(A) dx1/dt = - x1*x2 1000.0
(B) dx2/dt = x1*x2 1.0
    
```

# Two NLTs: Bell Shape



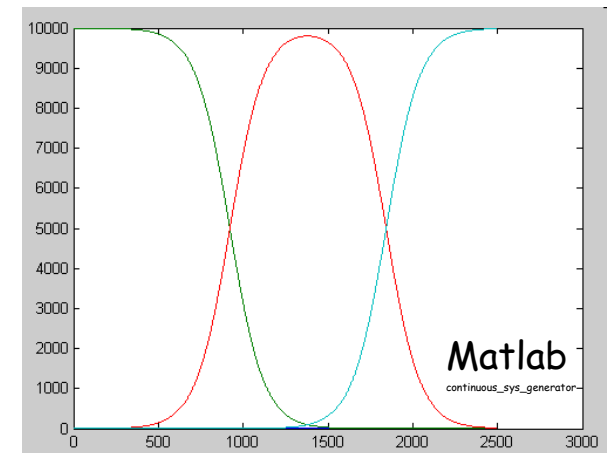
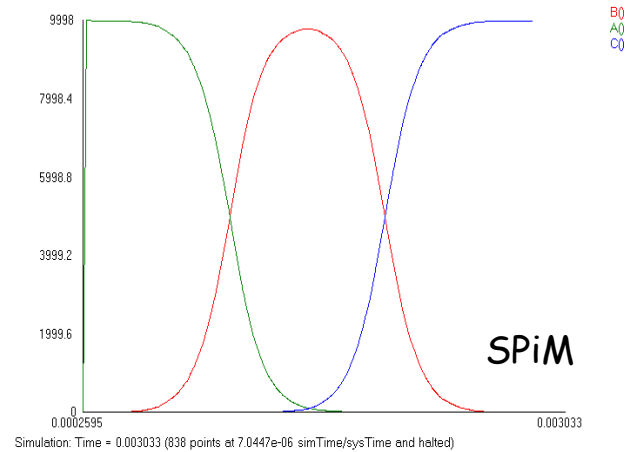
$$[B]^{\bullet} = [B]([A] - [C])$$

$$\begin{aligned} A &= ?b_{(1)}; B \\ B &= !b_{(1)}; B \oplus ?c_{(1)}; C \\ C &= !c_{(1)}; C \end{aligned}$$



$$\begin{aligned} [A]^{\bullet} &= -[A][B] \\ [B]^{\bullet} &= [A][B] - [B][C] \\ [C]^{\bullet} &= [B][C] \end{aligned}$$

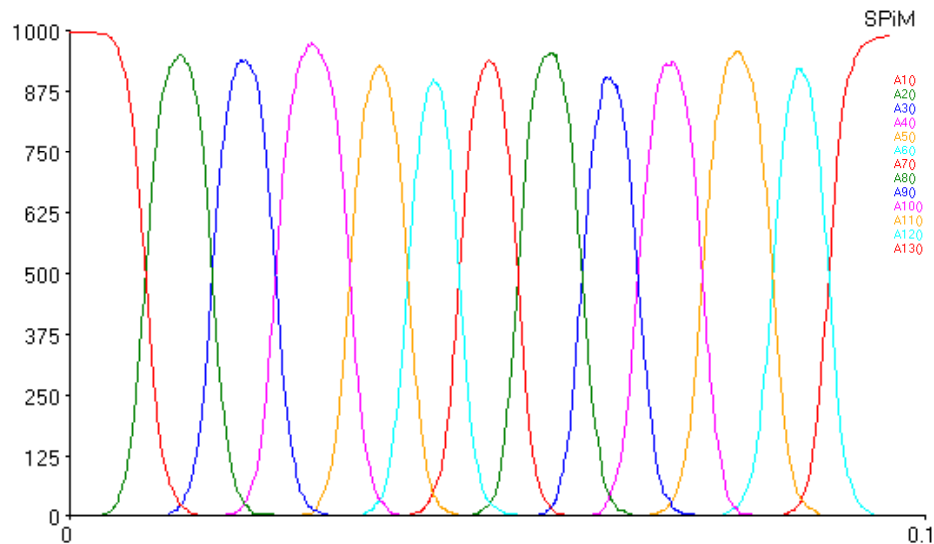
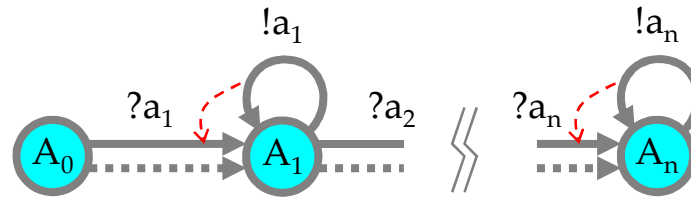
```
directive sample 0.0025 1000
directive plot B(); A(); C()
new b@1.0:chan new c@1.0:chan
let A() = ?b; B()
and B() = do !b;B() or ?c; C()
and C() = !c;C()
run ((10000 of A()) | B() | C())
```



interval/step	[0:0.000001:0.0025]
(A)	$dx1/dt = -x1*x2$ 10000.0
(B)	$dx2/dt = x1*x2 - x2*x3$ 1.0
(C)	$dx3/dt = x2*x3$ 1.0



# NLTs in Series: Soliton Propagation



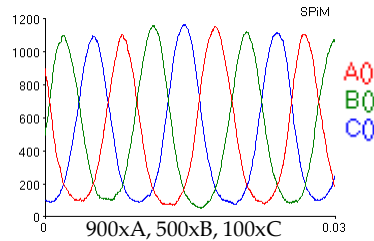
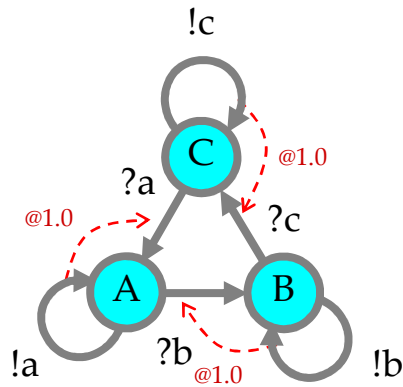
```
directive sample 0.1 1000
directive plot A1(); A2(); A3(); A4(); A5(); A6(); A7(); A8();
A9(); A10(); A11(); A12(); A13()
```

```
val r=1.0 val s=1.0
```

```
new a2@s:chan new a3@s:chan new a4@s:chan
new a5@s:chan new a6@s:chan new a7@s:chan
new a8@s:chan new a9@s:chan new a10@s:chan
new a11@s:chan new a12@s:chan new a13@s:chan
let A1() = do delay@r:A2() or ?a2; A2()
and A2() = do la2;A2() or delay@r:A3() or ?a3; A3()
and A3() = do la3;A3() or delay@r:A4() or ?a4; A4()
and A4() = do la4;A4() or delay@r:A5() or ?a5; A5()
and A5() = do la5;A5() or delay@r:A6() or ?a6; A6()
and A6() = do la6;A6() or delay@r:A7() or ?a7; A7()
and A7() = do la7;A7() or delay@r:A8() or ?a8; A8()
and A8() = do la8;A8() or delay@r:A9() or ?a9; A9()
and A9() = do la9;A9() or delay@r:A10() or ?a10; A10()
and A10() = do la10;A10() or delay@r:A11() or ?a11; A11()
and A11() = do la11;A11() or delay@r:A12() or ?a12; A12()
and A12() = do la12;A12() or delay@r:A13() or ?a13; A13()
and A13() = la13;A13()
```

```
run 1000 of A1()
```

# NLT in a Cycle: Oscillator



```
directive sample 0.03 1000
directive plot A(): B(): C()
```

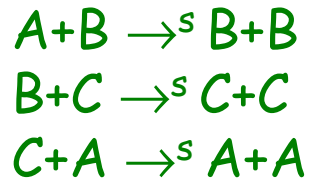
```
new a@1.0:chan new b@1.0:chan new c@1.0:chan
let A() = do !a;A() or ?b; B()
and B() = do !b;B() or ?c; C()
and C() = do !c;C() or ?a; A()
```

```
run (900 of A() | 500 of B() | 100 of C())
```

$$A = !a_{(s)}; A \oplus ?b_{(s)}; B$$

$$B = !b_{(s)}; B \oplus ?c_{(s)}; C$$

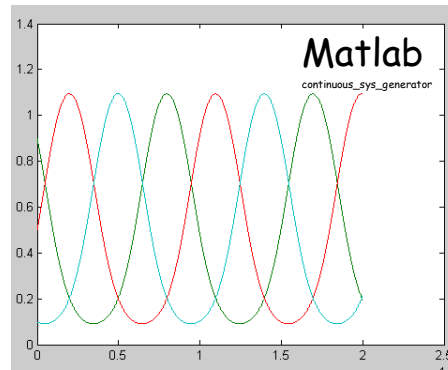
$$C = !c_{(s)}; C \oplus ?a_{(s)}; A$$



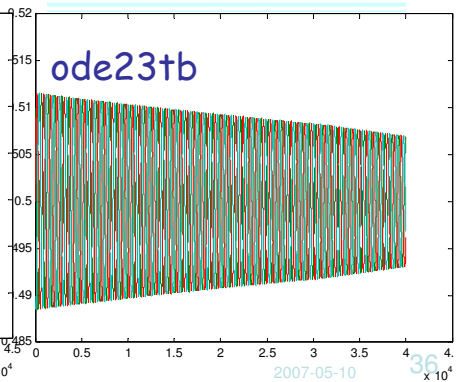
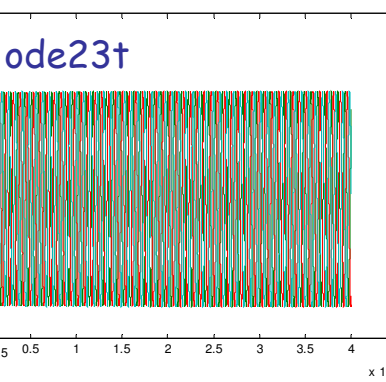
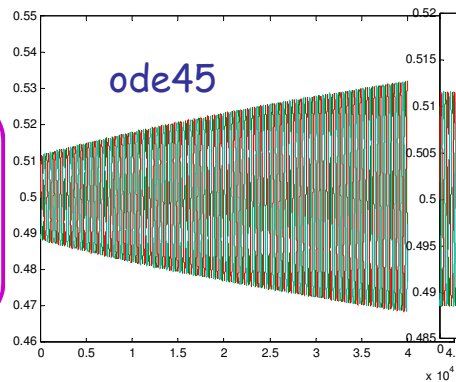
$$[A]^{\bullet} = -s[A][B] + s[C][A]$$

$$[B]^{\bullet} = -s[B][C] + s[A][B]$$

$$[C]^{\bullet} = -s[C][A] + s[B][C]$$



```
interval/step [0:0.001:20.0]
(A) dx1/dt = -x1*x2 + x3*x1 0.9
(B) dx2/dt = -x2*x3 + x1*x2 0.5
(C) dx3/dt = -x3*x1 + x2*x3 0.1
```



```
interval/step [0:0.01:400.0]
(A) dx1/dt = -x1*x2 + x3*x1 0.51
(B) dx2/dt = -x2*x3 + x1*x2 0.5
(C) dx3/dt = -x3*x1 + x2*x3 0.49
```

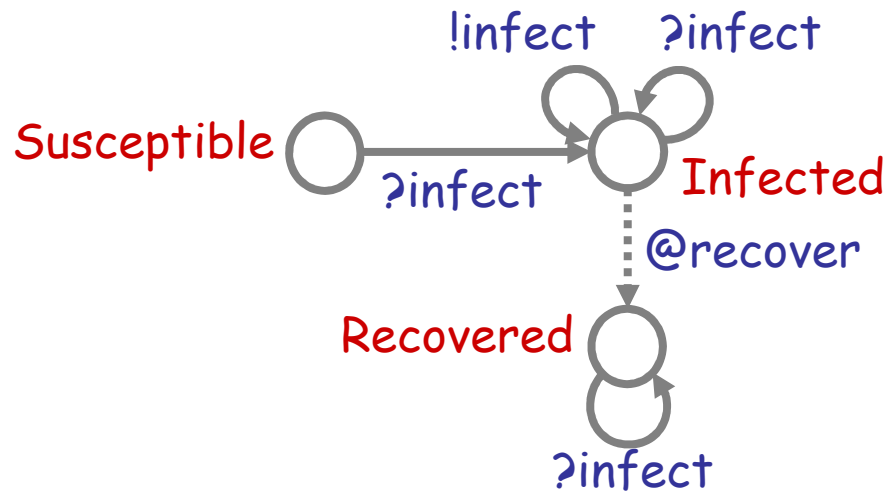


# Epidemics

Kermack, W. O. and McKendrick, A. G. "A Contribution to the Mathematical Theory of Epidemics." *Proc. Roy. Soc. Lond. A* 115, 700-721, 1927.

<http://mathworld.wolfram.com/Kermack-McKendrickModel.html>

# Epidemics



```

directive sample 500.0 1000
directive plot Recovered(); Susceptible(); Infected()

new infect @0.001:chan()
val recover = 0.03

let Recovered() =
  ?infect; Recovered()

and Susceptible() =
  ?infect; Infected()

and Infected() =
  do !infect; Infected()
  or ?infect; Infected()
  or delay@recover; Recovered()

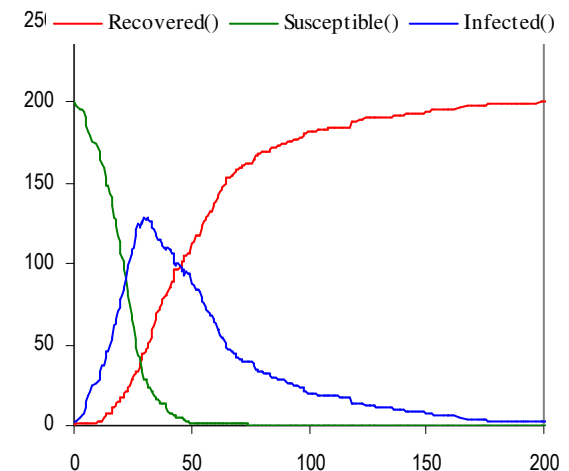
run (200 of Susceptible() | 2 of Infected())
  
```

## Developing the Use of Process Algebra in the Derivation and Analysis of Mathematical Models of Infectious Disease

R. Norman and C. Shankland

Department of Computing Science and Mathematics, University of Stirling, UK.  
 {ces,ran}@cs.stir.ac.uk

**Abstract.** We introduce a series of descriptions of disease spread using the process algebra WSCCS and compare the derived mean field equations with the traditional ordinary differential equation model. Even the preliminary work presented here brings to light interesting theoretical questions about the “best” way to defined the model.



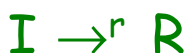
# ODE

Differentiating Processes!

$$S = ?i_{(t)}; I$$

$$I = !i_{(t)}; I \oplus ?i_{(t)}; I \oplus \tau_r; R$$

$$R = ?i_{(t)}; R$$



"useless" reactions

$$[S]^\bullet = -t\gamma[S][I]$$

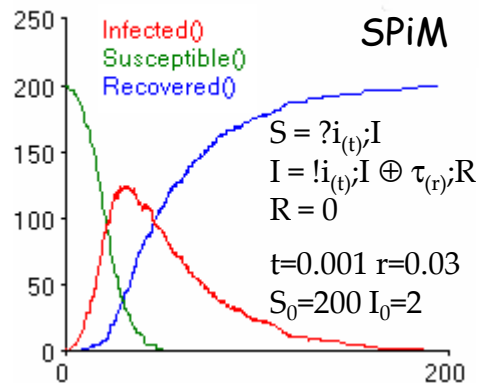
$$[I]^\bullet = t\gamma[S][I] - r[I]$$

$$[R]^\bullet = r[I]$$

Automata produce the standard ODEs!

$$\begin{aligned} \frac{dS}{dt} &= -aIS \\ \frac{dI}{dt} &= aIS - bI \\ \frac{dR}{dt} &= bI \end{aligned}$$

(the Kermack-McKendrick, or SIR model)

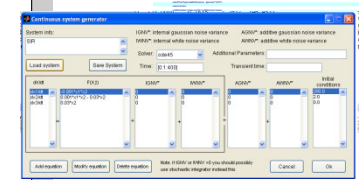
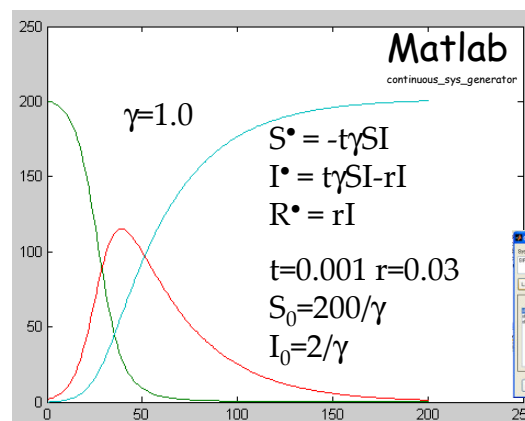
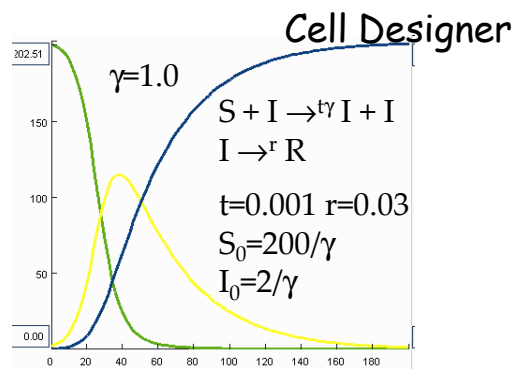


```
directive sample 5000 1000
directive plot Recovered(), Susceptible(), Infected()

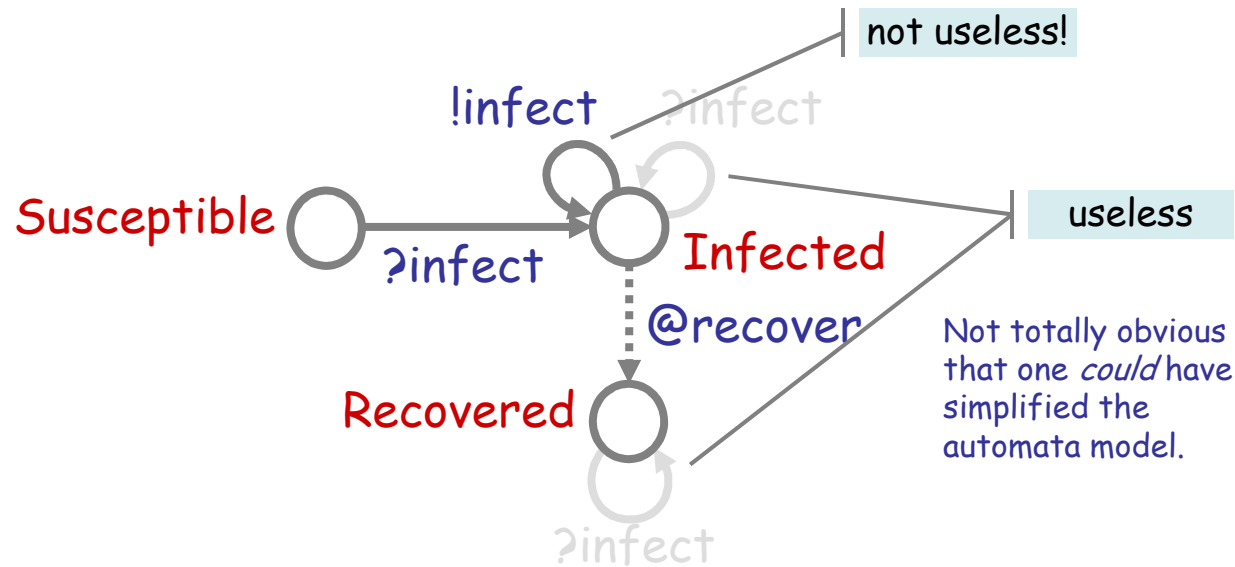
new infect @0.001:chan()
val recover = 0.03

let Recovered() =
  ?infect: Recovered()
and Susceptible() =
  ?infect: Infected()
and Infected() =
  do infect: Infected()
  or ?infect: Infected()
  or delay@recover: Recovered()

run (200 of Susceptible() | 2 of Infected())
```



# Simplified Model



```
directive sample 500.0 1000
directive plot Recovered(); Susceptible(); Infected()

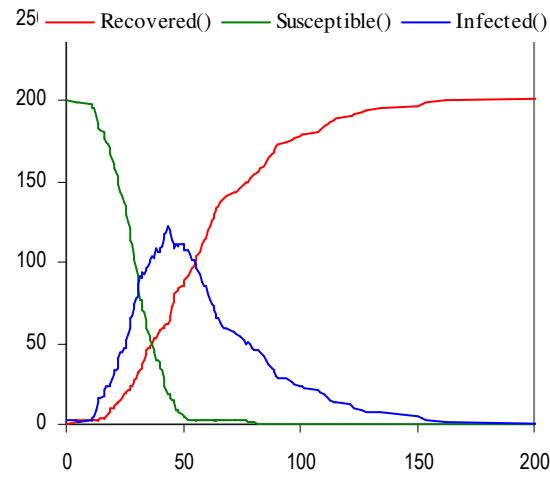
new infect @0.001:chan()
val recover = 0.03

let Recovered() =
  ()

and Susceptible() =
  ?infect; Infected()

and Infected() =
  do !infect; Infected()
  or delay@recover; Recovered()

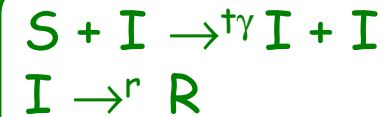
run (200 of Susceptible() | 2 of Infected())
```



$$S = ?i_{(t)}; I$$

$$I = !i_{(t)}; I \oplus \tau_r; R$$

$$R = 0$$



$$[S]' = -\tau[S][I]$$

$$[I]' = \tau[S][I] - r[I]$$

$$[R]' = r[I]$$

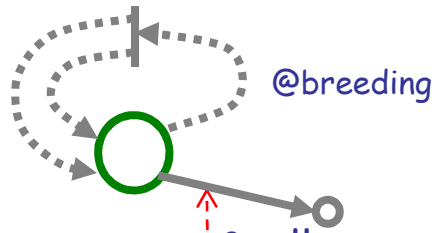
Same ODE, hence equivalent automata models.

# Lotka-Volterra

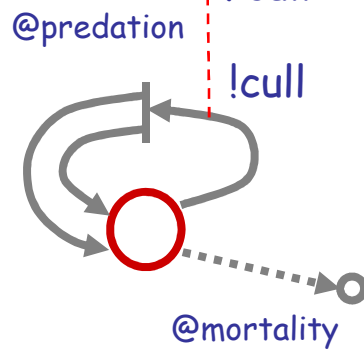


# Predator-Prey

Herbivor



Carnivor



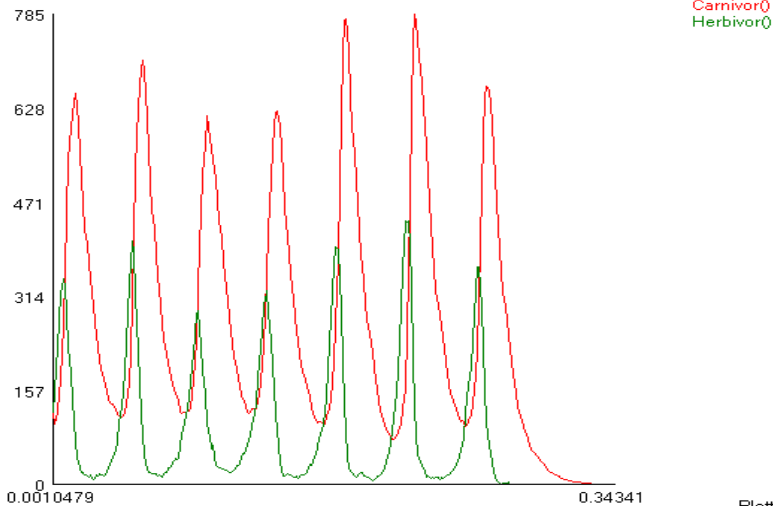
```
directive sample 1.0 1000
directive plot Carnivor(); Herbivor()
```

```
val mortality = 100.0
val breeding = 300.0
val predation = 1.0
new cull @predation:chan()
```

```
let Herbivor() =
  do delay@breeding; (Herbivor() | Herbivor())
  or ?cull; ()
```

```
and Carnivor() =
  do delay@mortality; ()
  or !cull; (Carnivor() | Carnivor())
```

```
run 100 of Herbivor()
run 100 of Carnivor()
```



Simulation: Halted, Time = 0.343410 (317 points at 0.0068489 simTime/sysTime)

Plotting: Live

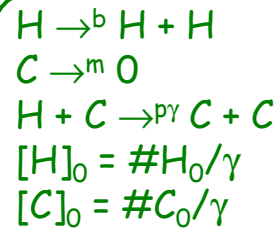
*An unbounded  
state system!*

# Lotka-Volterra in Matlab

$$H = \tau_b: (H|H) \oplus ?c_{(p)}:0$$

$$C = \tau_m:0 \oplus !c_{(p)}:(C|C)$$

#H<sub>0</sub>, #C<sub>0</sub>



$$[H]^* = b[H] - p\gamma[H][C]$$

$$[C]^* = -m[C] + p\gamma[H][C]$$

$$[H]_0 = \#H_0/\gamma$$

$$[C]_0 = \#C_0/\gamma$$

m=100.0  
 b=300.0  
 p=1.0  
 γ=1.0  
 #H<sub>0</sub> = 100  
 #C<sub>0</sub> = 100

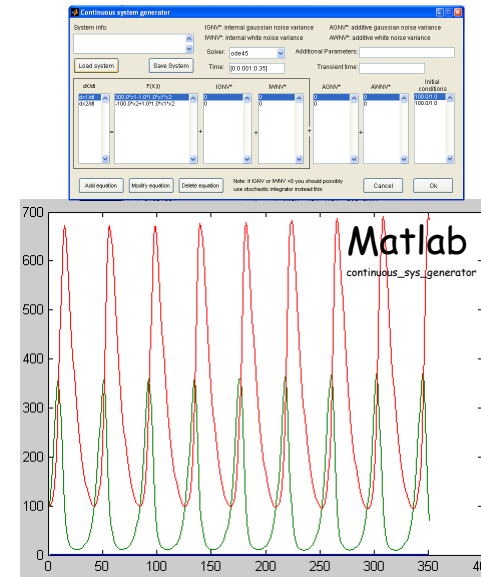
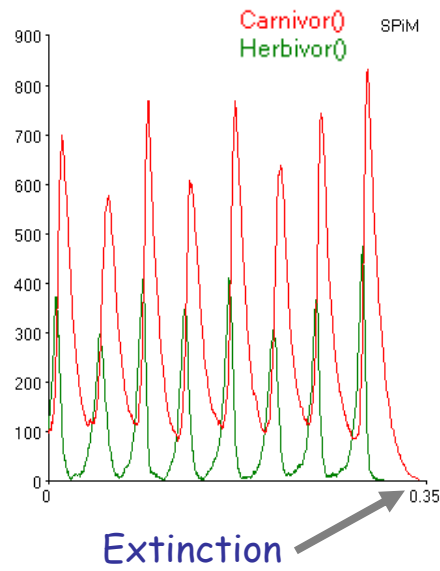
```
directive sample 0.35 1000
directive plot Carnivor(); Herbivor();
```

```
val mortality = 100.0
val breeding = 300.0
val predation = 1.0
new cull @predation:chan()
```

```
let Herbivor() =
do delay@breeding; (Herbivor() | Herbivor())
or ?cull; ()
```

```
and Carnivor() =
do delay@mortality; ()
or !cull; (Carnivor() | Carnivor())
```

```
run 100 of Herbivor()
run 100 of Carnivor()
```



# Parametric Processes

# Chemical Parametric Form (CPF)

$E ::= X_1(\mathbf{p}_1)=M_1, \dots, X_n(\mathbf{p}_n)=M_n$

$M ::= \pi_1;P_1 \oplus \dots \oplus \pi_n;P_n$

$P ::= X_1(\mathbf{p}_1) \mid \dots \mid X_n(\mathbf{p}_n)$

$\pi ::= \tau_r \ ?n(\mathbf{p}) \ !n(\mathbf{p})$

$CPF ::= E, P$

Reagents  $(n \geq 0)$

Molecules  $(n \geq 0)$

Solutions  $(n \geq 0)$

Interactions

with initial conditions

Not bounded-state systems.

Not finite-control systems.

But still **finite-species** systems.

$\oplus$  is stochastic choice (vs. + for chemical reactions)

$O$  is the null solution ( $P|O = O|P = P$ )

and null molecule ( $M \oplus O = O \oplus M = M$ ) ( $\tau_0;P = O$ )

$X_i$  are distinct in  $E$ ,  $\mathbf{p}$  are vectors of names

$\mathbf{p}$  are vectors of distinct names when in **binding position**

Each free name  $n$  in  $E$  is assigned a fixed rate  $r$ :

written either  $n_{(r)}$ , or  $\rho_{CPF}(n)=r$ .

A translation from CPF to CGF exists

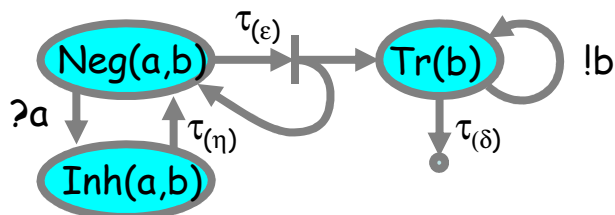
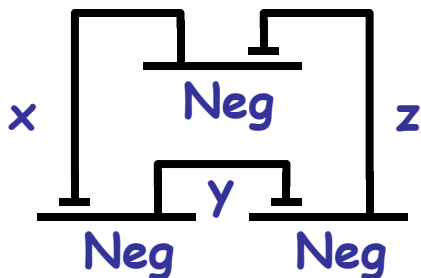
(expanding all possible instantiation of parameters from the initial conditions)

An incremental translation algorithm exists

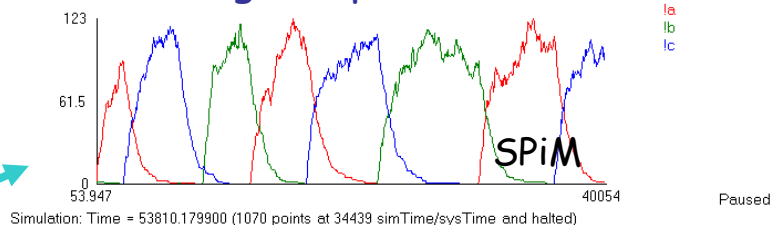
(expanding on demand from initial conditions)

# And Yet It Moves

## The Repressilator



A fine stochastic oscillator over a wide range of parameters.



## Parametric representation

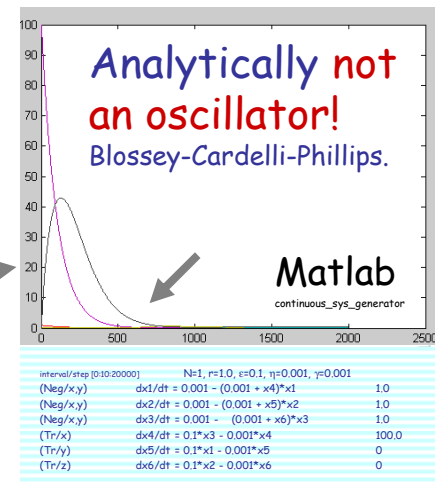
$$\begin{aligned} \text{Neg}(a,b) &= ?a; \text{Inh}(a,b) \oplus \tau_\epsilon; (\text{Tr}(b) \mid \text{Neg}(a,b)) \\ \text{Inh}(a,b) &= \tau_\eta; \text{Neg}(a,b) \\ \text{Tr}(b) &= !b; \text{Tr}(b) \oplus \tau_\delta; 0 \\ \text{Neg}(x_{(r)}, y_{(r)}) \mid \text{Neg}(y_{(r)}, z_{(r)}) \mid \text{Neg}(z_{(r)}, x_{(r)}) \end{aligned}$$

$$\begin{aligned} [\text{Neg}/x,y]^* &= -r[\text{Tr}/x][\text{Neg}/x,y] + \eta[\text{Inh}/x,y] \\ [\text{Neg}/y,z]^* &= -r[\text{Tr}/y][\text{Neg}/y,z] + \eta[\text{Inh}/y,z] \\ [\text{Neg}/z,x]^* &= -r[\text{Tr}/z][\text{Neg}/z,x] + \eta[\text{Inh}/z,x] \\ [\text{Inh}/x,y]^* &= r[\text{Tr}/x][\text{Neg}/x,y] - \eta[\text{Inh}/x,y] \\ [\text{Inh}/y,z]^* &= r[\text{Tr}/y][\text{Neg}/y,z] - \eta[\text{Inh}/y,z] \\ [\text{Inh}/z,x]^* &= r[\text{Tr}/z][\text{Neg}/z,x] - \eta[\text{Inh}/z,x] \\ [\text{Tr}/x]^* &= \epsilon[\text{Neg}/z,x] - \gamma[\text{Tr}/x] \\ [\text{Tr}/y]^* &= \epsilon[\text{Neg}/x,y] - \gamma[\text{Tr}/y] \\ [\text{Tr}/z]^* &= \epsilon[\text{Neg}/y,z] - \gamma[\text{Tr}/z] \end{aligned}$$

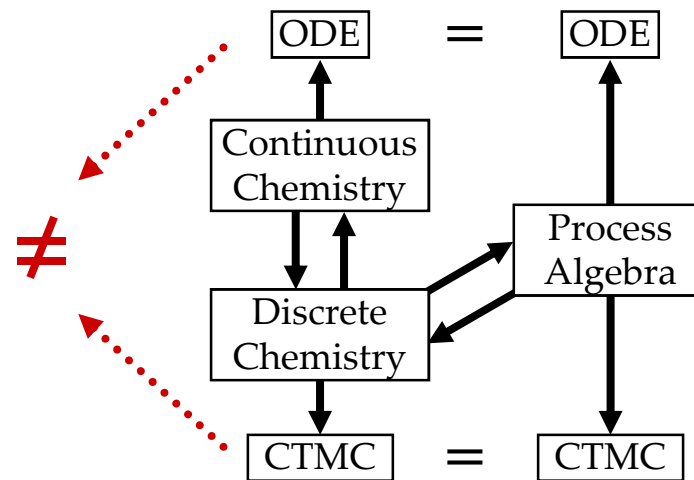
$$\begin{aligned} \text{Neg}/x,y &\rightarrow^\epsilon \text{Tr}/y + \text{Neg}/x,y \\ \text{Neg}/y,z &\rightarrow^\epsilon \text{Tr}/z + \text{Neg}/y,z \\ \text{Neg}/z,x &\rightarrow^\epsilon \text{Tr}/x + \text{Neg}/z,x \\ \text{Tr}/x + \text{Neg}/x,y &\rightarrow^r \text{Tr}/x + \text{Inh}/x,y \\ \text{Tr}/y + \text{Neg}/y,z &\rightarrow^r \text{Tr}/y + \text{Inh}/y,z \\ \text{Tr}/z + \text{Neg}/z,x &\rightarrow^r \text{Tr}/z + \text{Inh}/z,x \\ \text{Inh}/x,y &\rightarrow^\eta \text{Neg}/x,y \\ \text{Inh}/y,z &\rightarrow^\eta \text{Neg}/y,z \\ \text{Inh}/z,x &\rightarrow^\eta \text{Neg}/z,x \\ \text{Tr}/x &\rightarrow^\gamma 0 \\ \text{Tr}/y &\rightarrow^\gamma 0 \\ \text{Tr}/z &\rightarrow^\gamma 0 \\ \text{Neg}/x,y + \text{Neg}/y,z + \text{Neg}/z,x & \end{aligned}$$

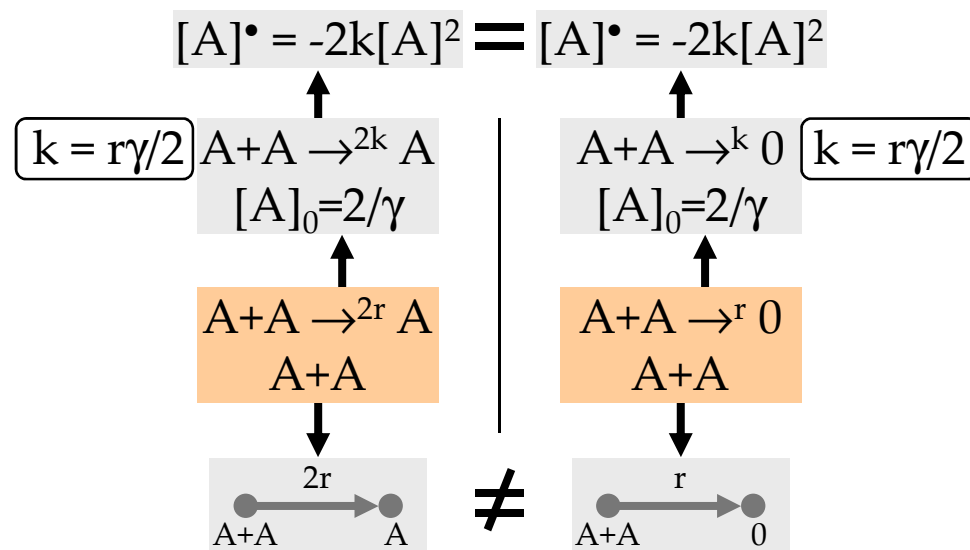
simplifying (N is the quantity of each of the 3 gates)

$$\begin{aligned} [\text{Neg}/x,y]^* &= \eta N - (\eta + r[\text{Tr}/x])[\text{Neg}/x,y] \\ [\text{Neg}/y,z]^* &= \eta N - (\eta + r[\text{Tr}/y])[\text{Neg}/y,z] \\ [\text{Neg}/z,x]^* &= \eta N - (\eta + r[\text{Tr}/z])[\text{Neg}/z,x] \\ [\text{Tr}/x]^* &= \epsilon[\text{Neg}/z,x] - \gamma[\text{Tr}/x] \\ [\text{Tr}/y]^* &= \epsilon[\text{Neg}/x,y] - \gamma[\text{Tr}/y] \\ [\text{Tr}/z]^* &= \epsilon[\text{Neg}/y,z] - \gamma[\text{Tr}/z] \end{aligned}$$

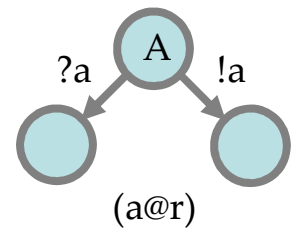
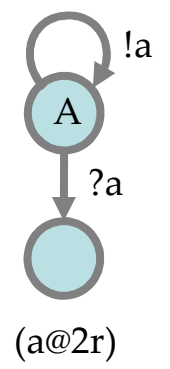
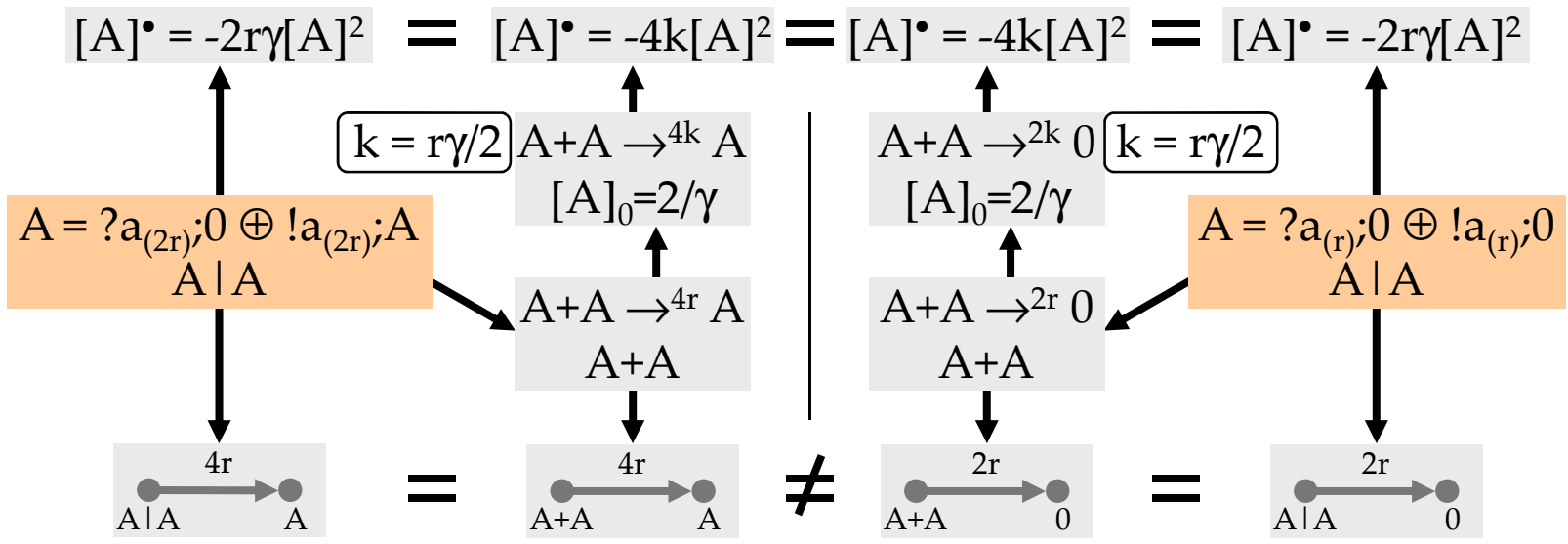


# GMA $\neq$ CME





# ... as Automata





# Conclusions

# Conclusions

<http://LucaCardelli.name>

- **Devising Compositional Models**
  - Accurate (at the "appropriate" abstraction level).
  - Manageable (so we can scale them up by composition).
- **Interacting Automata**
  - Complex global behavior from simple components.
  - Bridging individual and collective behavior.
  - Connections to classical Markov theory, chemical Master Equation, and Rate Equation.
- **PolyAutomata (not shown)**
  - Artificial *Bio*-Chemistry: complexation and polymerization.
- **An "artificial biochemistry"**
  - A scalable mathematical and computational modeling framework.
  - To investigate "real biochemistry" on a large scale.